

# Oscillatory Solutions to Equations in Fluid Dynamics

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# Wild solutions?



In a letter to Stieltjes

I turn with terror and horror from this lamentable  
scourge of continuous functions with no derivatives

Charles Hermite [1822-1901]

- **Past:** What is not allowed is forbidden
- **Present:** What is not forbidden is allowed

# Oscillations

## Oscillatory sequence

$$g(x+a) = g(x) \text{ for all } x \in R, \int_0^a g(x) dx = 0,$$
$$g_n(x) = g(nx), \quad n = 1, 2, \dots$$

## Weak convergence (convergence in integral averages)

$$\int_R g_n(x) \varphi(x) dx, \text{ where } \varphi \in C_c^\infty(R).$$

$$G(x) = \int_0^x g(z) dz$$

$$\int_R g_n(x) \varphi(x) dx = \int_R g(nx) \varphi(x) dx = -\frac{1}{n} \int_R G(nx) \partial_x \varphi(x) dx \rightarrow 0$$

## Beware

$g_n \rightharpoonup g$  does not imply  $H(g_n) \rightharpoonup H(g)$  if  $H$  is not linear.

# Concentrations

## Concentrating sequence

$$g_n(x) = ng(nx)$$

$$g \in C_c^\infty(-1, 1), \quad g(-x) = g(x), \quad g \geq 0, \quad \int_R g(x) \, dx = 1.$$

■

$g_n(x) \rightarrow 0$  as  $n \rightarrow \infty$  for any  $x \neq 0$ , in particular  $g_n \rightarrow 0$  a.a. in  $R$ ;

■

$$\|g_n\|_{L^1(R)} = \int_R g_n(x) \, dx = \int_R g(x) \, dx = 1 \text{ for any } n = 1, 2, \dots$$

## Convergence in the space of measures

$$\int_R g_n(x) \varphi(x) \, dx = \int_{-1/n}^{1/n} g_n(x) \varphi(x) \, dx$$

$$\in \left[ \min_{x \in [-1/n, 1/n]} \varphi(x), \max_{x \in [-1/n, 1/n]} \varphi(x) \right] \rightarrow \varphi(0) \Rightarrow g_n \rightarrow \delta_0$$

# Equations preventing oscillations

## Elliptic problems

$-\Delta_x u = f$  in a bounded domain  $\Omega$ ,  $u|_{\partial\Omega} = 0$

## Compactness argument

- A priori bounds:

$$\int_{\Omega} |\nabla_x u|^2 \, dx = \int_{\Omega} fu \, dx \leq \|f\|_{L^2(\Omega)} \|u\|_{L^2(\Omega)}.$$

- Poincaré inequality

$$\|u\|_{L^2(\Omega)} \lesssim \|\nabla_x u\|_{L^2(\Omega)},$$

- Rellich–Kondrashev theorem

$$W^{1,2}(\Omega) \hookrightarrow \hookrightarrow L^2(\Omega)$$

# Scalar conservation laws

## Burgers equation

$$\partial_t u + \partial_x f(u) = 0, \quad u(t, 0) = u(t, 1), \quad t \in (0, T)$$

## Entropies

$$\partial_t S(u) + \partial_x F(u) = 0, \text{ where } F'(z) = f'(z)S'(z)$$

## Maximum principle

$$S(z) = \begin{cases} 0 & \text{for } z \leq L \\ > 0 & \text{for } z > L \end{cases}$$

$$\frac{d}{dt} \int_0^1 S(u(t, x)) dx = 0.$$

## Entropy inequality

$$\partial_t S(u) + \partial_x F(u) \leq 0, \text{ where } S \text{ is convex, } F'(z) = f'(z)S'(z)$$

# Example of blow up

Burger's equation

$$\partial_t u(t, x) + u(t, x) \partial_x u(t, x) = 0, \quad u(0, x) = u_0(x)$$

Characteristics

$$u(t, x + tu_0(x)) = u_0(x)$$

Schock development in finite time

$$u_0(x_1) > u_0(x_2), \quad x_1 < x_2$$

$$u(t, x_1 + tu_0(x_1)) = u_0(x_1) \neq u_0(x_2) = u(t, x_2 + tu_0(x_2))$$

but

$$x_1 + tu_0(x_1) = x_2 + tu_0(x_2) \Leftrightarrow t = \frac{x_2 - x_1}{u_0(x_1) - u_0(x_2)} > 0$$

# Compactness for scalar conservation laws

## Entropy formulation

$$\partial_t S(u) + \partial_x F(u) \leq 0, \text{ where } S \text{ is convex, } F'(z) = f'(z)S'(z)$$

## Solution sequence

$$|u_n(t, x)| \leq c \text{ for all } (t, x)$$

## Weak convergence

$u_n \rightarrow u$  weakly- $(*)$  in  $L^\infty$ ,

$S(u_n) \rightarrow \overline{S(u)}$  weakly- $(*)$  in  $L^\infty$ ,

$F(u_n) \rightarrow \overline{F(u)}$  weakly- $(*)$  in  $L^\infty$

for any convex entropy  $S$  with the corresponding flux  $F$

# Compensated compactness

## Div-Curl Lemma

Let  $\{\mathbf{U}_n\}_{n=1}^{\infty}$ ,  $\{\mathbf{V}_n\}_{n=1}^{\infty}$  be two sequences of vector valued defined on a set  $Q \subset \mathbb{R}^N$  such that

$$\mathbf{U}_n \rightarrow \mathbf{U} \text{ weakly in } L^p(Q; \mathbb{R}^N),$$

$$\mathbf{V}_n \rightarrow \mathbf{V} \text{ weakly in } L^q(Q; \mathbb{R}^N),$$

where

$$\frac{1}{p} + \frac{1}{q} < 1.$$

In addition, let

$$\{\operatorname{div} \mathbf{U}_n\}_{n=1}^{\infty} \text{ be precompact in } W^{-1,s}(Q),$$

$$\{\operatorname{curl} \mathbf{V}_n\}_{n=1}^{\infty} \text{ be precompact in } W^{-1,s}(Q; \mathbb{R}^{N \times N})$$

for some  $s > 1$ .

Then

$$\mathbf{U}_n \cdot \mathbf{V}_n \rightarrow \mathbf{U} \cdot \mathbf{V} \text{ weakly in } L^r(Q), \quad \frac{1}{r} = \frac{1}{p} + \frac{1}{q}.$$

# Application to scalar conservation laws, I

## Ansatz for Div-Curl Lemma

$$N = 2, \operatorname{div}_{t,x}[S_1, F_1] = \partial_t S_1 + \partial_x F_1, \operatorname{curl}_{t,x}[F_2, -S_2] = \partial_t S_2 + \partial_x F_2$$

## Conclusion – Tartar's identity

$$S_1(u_n)F_2(u_n) - F_1(u_n)S_2(u_n) \rightarrow \overline{S_1(u)} \overline{F_2(u)} - \overline{F_1(u)} \overline{S_2(u)}$$

## Application to scalar conservation laws, II

### Ansatz for Div-Curl Lemma

$$S_1(u) = u, \quad F_1(u) = f(u)$$

$$S_2(u) = |u - U|, \quad F_2(u) = \operatorname{sgn}(u - U)(f(u) - f(U)), \quad U - \text{constant}$$

$$\begin{aligned} & \lim_{n \rightarrow \infty} \left[ u_n \operatorname{sgn}(u_n - U)(f(u_n) - f(U)) - |u_n - U| f(u_n) \right] \\ &= \lim_{n \rightarrow \infty} u_n \lim_{n \rightarrow \infty} \left[ \operatorname{sgn}(u_n - U)(f(u_n) - f(U)) \right] \\ &\quad - \lim_{n \rightarrow \infty} |u_n - U| \lim_{n \rightarrow \infty} f(u_n) \end{aligned}$$

### Conclusion

$$\lim_{n \rightarrow \infty} \left[ |u_n - U| \left( \overline{f(u)} - f(U) \right) \right] = (u - U) \overline{\operatorname{sgn}(u - U)(f(u) - f(U))}$$

## Application to scalar conservation laws, III

### Lebesgue points

$U = u(\tau, y)$ ,  $(\tau, y)$  – a Lebesgue point of  $u$

$$\lim_{r \rightarrow 0} \frac{1}{|B_r(\tau, y)|} \int_{B_r(\tau, y)} |u - u(\tau, y)| \, dxdt = 0.$$

$$\begin{aligned} & \lim_{r \rightarrow 0} \frac{1}{|B_r(\tau, y)|} \int_{B_r(\tau, y)} \left( \lim_{n \rightarrow \infty} |u_n - u| \right) \left( \overline{f(u)} - f(u) \right) dxdt \\ &= \lim_{r \rightarrow 0} \frac{1}{|B_r(\tau, y)|} \int_{B_r(\tau, y)} \left[ \lim_{n \rightarrow \infty} \left[ |u_n - u(\tau, y)| (\overline{f(u)} - f(u(\tau, y))) \right] \right] dxdt \\ &= \lim_{r \rightarrow 0} \frac{1}{|B_r(\tau, y)|} \int_{B_r(\tau, y)} (u - u(\tau, y)) \overline{\operatorname{sgn}(u - u(\tau, y))(f(u) - f(u(\tau, y)))} dxdt = 0 \end{aligned}$$

### Conclusion

For a.a.  $(\tau, y)$ :

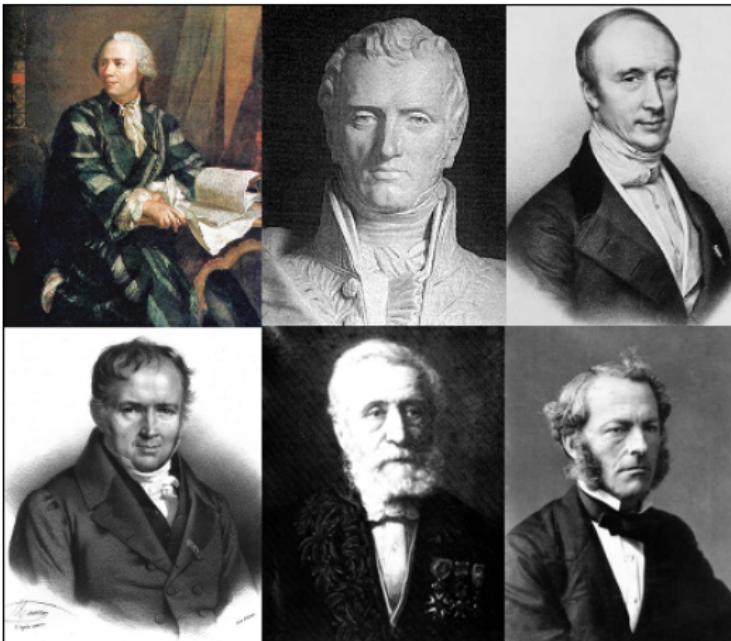
- either

$$(\text{weak}) - \lim_{n \rightarrow \infty} |u_n - u| = 0,$$

- or

$$\overline{f(u)} = f(u).$$

# Perfect fluids



Who is who in fluid mechanics...

# Iconic model of compressible inviscid fluid

**Equation of continuity**

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

**Momentum equation**

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho) = 0$$

**Impermeable boundary**

$$\mathbf{u} \cdot \mathbf{n}|_{\partial\Omega} = 0$$

**Initial conditions**

$$\varrho(0, \cdot) = \varrho_0, \quad \mathbf{u}(0, \cdot) = \mathbf{u}_0$$

# First and Second law – energy

## Energy

$$E = \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) = \frac{1}{2} \frac{|\mathbf{m}|^2}{\varrho} + P(\varrho), \quad \mathbf{m} = \varrho \mathbf{u}$$

$$P'(\varrho) \varrho - P(\varrho) = p(\varrho)$$

$$p' \geq 0 \Rightarrow [\varrho, \mathbf{m}] \mapsto \begin{cases} \frac{1}{2} \frac{|\mathbf{m}|^2}{\varrho} + P(\varrho) & \text{if } \varrho > 0 \\ P(\varrho) & \text{if } |\mathbf{m}| = 0 \\ \infty & \text{if } \varrho = 0, |\mathbf{m}| \neq 0 \end{cases} \quad \text{is convex l.s.c}$$

## Energy balance (conservation)

$$\partial_t E + \operatorname{div}_x(E \mathbf{u}) + \operatorname{div}_x(p \mathbf{u}) = 0$$

## Energy dissipation

$$\partial_t E + \operatorname{div}_x(E \mathbf{u}) + \operatorname{div}_x(p \mathbf{u}) \leq 0$$

$$\partial_t E \leq 0, \quad E(0+) = \int_{\Omega} \left[ \frac{1}{2} \frac{|\mathbf{m}_0|^2}{\varrho_0} + P(\varrho_0) \right] dx$$

# Possible singularities

## Toy model

$$\partial_t U + U \partial_x U = 0, \quad t > 0, \quad x \in R$$

$$U(0) = U_0$$

## Explicit solution

$$U(t, x + tU_0(x)) = U_0(x)$$

## Shock at finite time

$$U_0(x_1) > U_0(x_2), \quad x_1 < x_2 \Rightarrow U(t, x_1 + tU_0(x_1)) > U(t, x_2 + tU_0(x_2))$$

$$t_{\text{shock}} = \frac{x_2 - x_1}{U_0(x_1) - U_0(x_2)} \Rightarrow x_1 + tU_0(x_1) = x_2 + tU_0(x_2)$$

# Weak solutions

## Field equations

$$\int_0^\infty \int_\Omega [\varrho \partial_t \varphi + \mathbf{m} \cdot \nabla_x \varphi] \, dx dt = - \int_\Omega \varrho_0 \varphi(0, \cdot) \, dx, \quad \varphi \in C_c^1([0, \infty) \times \overline{\Omega})$$

$$\begin{aligned} & \int_0^\infty \int_\Omega \left[ \mathbf{m} \cdot \partial_t \varphi + \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} : \nabla_x \varphi + p(\varrho) \operatorname{div}_x \varphi \right] \, dx dt \\ &= - \int_\Omega \mathbf{m}_0 \cdot \varphi(0, \cdot) \, dx, \quad \varphi \in C_c^1([0, T) \times \overline{\Omega}; \mathbb{R}^N), \quad \varphi \cdot \mathbf{n}|_{\partial\Omega} = 0 \end{aligned}$$

## Dissipative weak solutions

$$\int_0^\infty \int_\Omega \left[ \frac{1}{2} \frac{|\mathbf{m}|^2}{\varrho} + P(\varrho) \right] \, dx \, \partial_t \psi \, dt \geq \psi(0) \int_\Omega \frac{1}{2} \frac{|\mathbf{m}_0|^2}{\varrho_0} + P(\varrho_0) \, dx$$

$$\psi \in C_c^1[0, \infty), \quad \psi \geq 0$$

# Admissible (dissipative) solutions

## Energy inequality

$$\begin{aligned} & \int_0^\infty \int_\Omega \left[ E(\varrho, \mathbf{m}) \partial_t \varphi + E(\varrho, \mathbf{m}) \frac{\mathbf{m}}{\varrho} \cdot \nabla_x \varphi + p(\varrho) \frac{\mathbf{m}}{\varrho} \cdot \nabla_x \varphi \right] dx dt \\ & \geq \int_\Omega \left[ \frac{1}{2} \frac{|\mathbf{m}_0|^2}{\varrho_0} + P(\varrho_0) \right] \varphi(0, \cdot) dx \\ & \varphi \in C_c^1([0, \infty) \times \bar{\Omega}), \quad \varphi \geq 0 \end{aligned}$$

# Well posedness

## Classical solutions [Matsumura–Nishida], [Tani]

$\varrho_0 \in W^{3,2}(\Omega)$ ,  $\varrho_0 > 0$ ,  $\mathbf{m}_0 \in W^{3,2}(\Omega; \mathbb{R}^N)$  + compatibility conditions

$\Rightarrow$

classical solution

$\varrho \in C([0, T_{\max}); W^{3,2}(\Omega))$ ,  $\mathbf{m} \in C([0, T_{\max}); W^{3,2}(\Omega; \mathbb{R}^N))$ ,  $N = 2, 3$

$T_{\max} < \infty$  for a “generic” class of initial data

## Weak–Strong uniqueness [Dafermos]

An *admissible* weak solution coincides with the strong solution emanating from the same initial data on the time interval  $[0, T_{\max})$

# Euler as symmetric hyperbolic system

Isentropic pressure

$$p(\varrho) = a\varrho^\gamma, \quad r = \sqrt{\frac{2a\gamma}{\gamma-1}}\varrho^{\frac{\gamma-1}{2}}$$

Symmetric hyperbolic system

$$\partial_t r + \mathbf{u} \cdot \nabla_x r + \frac{\gamma-1}{2} r \operatorname{div}_x \mathbf{u} = 0$$

$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla_x \mathbf{u} + \frac{\gamma-1}{2} r \nabla_x r = 0.$$

A priori bounds

$$\frac{d}{dt} \int_{\Omega} |\partial_x^\alpha \varrho|^2 + |\partial_x^\alpha \mathbf{u}|^2 \, dx \leq c + \left( \int_{\Omega} |\partial_x^\alpha \varrho|^2 + |\partial_x^\alpha \mathbf{u}|^2 \, dx \right)^M, \quad M > 0$$

$$\alpha = [N/2] + 1$$

## Well/ill posedness

### Global existence well/ill posedness [Chiodaroli, E.F.]

$$\varrho_0 \in C^3(\bar{\Omega}), \varrho_0 > 0, \mathbf{m}_0 \in C^3(\bar{\Omega}; \mathbb{R}^N), \mathbf{m}_0 \cdot \mathbf{n}|_{\partial\Omega} = 0$$

$\Rightarrow$

*infinitely many* weak solutions

$$\varrho \in L^\infty_{\text{loc}}([0, \infty) \times \Omega), \mathbf{m} \in L^\infty_{\text{loc}}([0, \infty) \times \Omega; \mathbb{R}^N)$$

$$\varrho > 0, \operatorname{div}_x \mathbf{m} \in L^\infty_{\text{loc}}([0, \infty) \times \Omega), \mathbf{m} \cdot \mathbf{n}|_{\partial\Omega} = 0$$

### Well/ill posedness of dissipative solutions [Chiodaroli, E.F.]

$$\varrho_0 \in C^3(\bar{\Omega}), \varrho_0 > 0, \nabla_x \Phi_0 \in C^3(\bar{\Omega}), \nabla_x \Phi_0 \cdot \mathbf{n}|_{\partial\Omega} = 0$$

$\Rightarrow$

there exist (*infinitely many*)  $\mathbf{v}_0 \in L^\infty(\Omega; \mathbb{R}^N)$ ,  $\operatorname{div}_x \mathbf{v}_0 = 0$

and *infinitely many* dissipative weak solutions

$$\varrho \in L^\infty_{\text{loc}}([0, \infty) \times \Omega), \mathbf{m} \in L^\infty_{\text{loc}}([0, \infty) \times \Omega; \mathbb{R}^N)$$

$$\varrho(0, \cdot) = \varrho_0, \mathbf{m}(0, \cdot) = \mathbf{v}_0 + \nabla_x \Phi_0$$

## Strong vs. weak continuity

### Strong discontinuities, A.Abbatiello, E.F.

Let  $\{\tau_n\}_{n=1}^{\infty} \subset (0, T)$  be an arbitrary (dense) countable family of times.

Let the initial data belong to the class

$$\varrho_0 \in C(\Omega), \quad \varrho_0 > 0, \quad \mathbf{u}_0 \in C(\Omega; \mathbb{R}^N), \quad \operatorname{div}_x \mathbf{u}_0 \in C(\Omega), \quad \Omega = \mathcal{T}^N, \quad N = 2, 3.$$

Then the compressible Euler system admits *infinitely many* weak solutions emanating from the initial state  $[\varrho_0, \mathbf{u}_0]$  such that the mapping

$$t \mapsto [\varrho(t, \cdot), \mathbf{m} = \varrho \mathbf{u}(t, \cdot)]$$

is not strongly  $L^1$ -continuous at any of the times  $\tau_n$ .

## Admissible weak solutions

Global existence well/ill posedness [Chiocdaroli, E.F., Luo, Xie and Xin]

$\varrho_0$  piecewise Lipschitz,  $\varrho_0 > 0$

$\Rightarrow$

there exist (infinitely many)  $\mathbf{m}_0 \in L^\infty(\Omega; R^N)$

and *infinitely many* admissible weak solutions

$\varrho \in L^\infty_{\text{loc}}([0, \infty) \times \Omega)$ ,  $\mathbf{m} \in L^\infty_{\text{loc}}([0, \infty) \times \Omega; R^N)$

$\varrho(0, \cdot) = \varrho_0$ ,  $\mathbf{m}(0, \cdot) = \mathbf{m}_0$

Energy conserving solutions [Luo, Xie and Xin]

If  $\varrho_0$  is piecewise constant, one can find  $\mathbf{m}_0$  as above such that the solution satisfy the energy equation (energy conserving solutions).

## Lipschitz initial data

### III posedness for regular data [Chiodaroli, DeLellis, Kreml]

Let  $T > 0$  be given.

Then there exist (infinitely many) Lipschitz initial data  $\varrho_0, \mathbf{m}_0$  such that the barotropic Euler system admits infinitely many admissible weak solutions on the time interval  $[0, T]$ .

# III-posedness in fluid dynamics



Johann von Neumann  
[1903-1957]

## Motto

In mathematics you don't understand things. You just get used to them.

# Rewriting Euler system

## Helmholtz decomposition

$$\mathbf{m} = \mathbf{H}[\mathbf{m}] + \mathbf{H}^\perp[\mathbf{m}] = \mathbf{v} + \nabla_x \Phi$$

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\mathbf{H}^\perp[\mathbf{m}] = \nabla_x \Phi, \quad \Delta_x \Phi = \operatorname{div}_x \mathbf{m}, \quad (\nabla_x \Phi - \mathbf{m}) \cdot \mathbf{n}|_{\partial\Omega} = 0$$

## Euler system - volume preserving part

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\partial_t \mathbf{v} + \mathbf{H} \left[ \operatorname{div}_x \left( \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} - \frac{1}{N} \frac{|\mathbf{m}|^2}{\varrho} \mathbb{I} \right) \right] = 0$$

## Euler system - acoustic part

$$\partial_t \varrho + \Delta_x \Phi = 0$$

$$\partial_t \nabla_x \Phi + \nabla_x p(\varrho) + \nabla_x \left( \frac{1}{N} \frac{|\mathbf{m}|^2}{\varrho} \right) + \mathbf{H}^\perp \left[ \operatorname{div}_x \left( \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} - \frac{1}{N} \frac{|\mathbf{m}|^2}{\varrho} \mathbb{I} \right) \right] = 0$$

# Convex integration ansatz



This is a **BIG** crime...

## Volume preserving part

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\partial_t \mathbf{v} + \left[ \operatorname{div}_x \left( \frac{(\mathbf{v} + \nabla_x \Phi) \otimes (\mathbf{v} + \nabla_x \Phi)}{\varrho} - \frac{1}{N} \frac{|\mathbf{v} + \nabla_x \Phi|^2}{\varrho} \mathbb{I} \right) \right] = 0$$

## Acoustic part

$$\partial_t \varrho + \Delta_x \Phi = 0$$

$$\partial_t \nabla_x \Phi + \nabla_x p(\varrho) + \nabla_x \left( \frac{1}{N} \frac{|\mathbf{v} + \nabla_x \Phi|^2}{\varrho} \right) = 0$$

# Acoustic ansatz - continuing committing crimes

## Acoustic part - fixing the data

$$\partial_t \varrho + \Delta_x \Phi = 0$$

$$\varrho(0, \cdot) = \varrho_0, \quad \Phi(0, \cdot) = \Phi_0, \quad \nabla_x \Phi_0 = \mathbf{H}^\perp[\mathbf{m}_0]$$

$$\varrho = \varrho(t, \cdot), \quad \Phi(t, \cdot) = -\Delta_N^{-1}[\partial_t \varrho]$$

## Fixing kinetic energy

$$\partial_t \nabla_x \Phi + \nabla_x p(\varrho) + \nabla_x \left( \frac{1}{N} \frac{|\mathbf{v} + \nabla_x \Phi|^2}{\varrho} \right) = 0$$

$$\frac{1}{N} \frac{|\mathbf{v} + \nabla_x \Phi|^2}{\varrho} = -\partial_t \Phi - p(\varrho) + \boxed{\Lambda(t)}$$

## Solving the volume preserving part

Abstract “Euler system”

$$\begin{aligned}\operatorname{div}_x \mathbf{v} &= 0 \\ \partial_t \mathbf{v} + \left[ \operatorname{div}_x \left( \frac{(\mathbf{v} + \nabla_x \Phi) \otimes (\mathbf{v} + \nabla_x \Phi)}{\varrho} - \frac{1}{N} \frac{|\mathbf{v} + \nabla_x \Phi|^2}{\varrho} \mathbb{I} \right) \right] &= 0 \\ \mathbf{v}(0, \cdot) &= \mathbf{v}_0\end{aligned}$$

Given kinetic energy

$$\frac{1}{2} \frac{|\mathbf{v} + \nabla_x \Phi|^2}{\varrho} = E$$

Given “data”

$$\mathbf{v}_0, \operatorname{div}_x \mathbf{v}_0 = 0, \nabla_x \Phi, \varrho, E$$

# Solving a special case

Incompressible Euler system with given pressure

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \mathbf{v} \otimes \mathbf{v} - \frac{1}{N} |\mathbf{v}|^2 \mathbb{I} \right) = 0$$

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0$$

Given kinetic energy

$$\frac{1}{2} |\mathbf{v}|^2 = E$$

Weak solutions

$$\mathbf{v} \in C_{\text{weak}}([0, T]; L^2(\Omega; R^N)), \quad \mathbf{v} \in L^\infty((0, T) \times \Omega; R^N)$$

# Weak formulation of the basic problem

Regularity class

$$\mathbf{v} \in C_{\text{weak}}([0, T]; L^2(\Omega; \mathbb{R}^N)), \quad \mathbf{v} \in L^\infty((0, T) \times \Omega; \mathbb{R}^N)$$

Incompressibility condition

$$\int_0^T \int_\Omega \mathbf{v} \cdot \nabla_x \varphi \, dx = 0, \quad \text{for any } \varphi \in C^1([0, T] \times \bar{\Omega})$$

Field equations

$$\int_0^T \int_\Omega \left[ \mathbf{v} \cdot \partial_t \varphi + \mathbf{v} \otimes \mathbf{v} : \nabla_x \varphi - \frac{1}{N} |\mathbf{v}|^2 \operatorname{div}_x \varphi \right] \, dx dt = - \int_\Omega \mathbf{v}_0 \cdot \varphi(0, \cdot) \, dx$$

$$\text{for any } \varphi \in C^1([0, T] \times \bar{\Omega}; \mathbb{R}^N)$$

Energy

$$\frac{1}{2} |\mathbf{v}|^2 = E \quad \text{a.a. in } (0, T) \times \Omega$$

# Pasting together spatial domains

## Domain decomposition

$$\overline{\Omega} = \cup_{i \in L} \overline{\Omega}_i, \quad \Omega_i \cap \Omega_j = \emptyset, \quad i \neq j$$

## Incompressible Euler system with piece-wise constant density

$$\operatorname{div}_x \mathbf{v} = 0 \text{ in } \Omega$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{\mathbf{v} \otimes \mathbf{v}}{\varrho_i} - \frac{1}{N} \frac{|\mathbf{v}|^2}{\varrho_i} \mathbb{I} \right) = 0 \text{ in } \Omega_i, \quad \varrho_i > 0$$

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0$$

## Kinetic energy

$$\frac{1}{2} \frac{|\mathbf{v}|^2}{\varrho_i} = E_i \text{ a.a. in } \Omega_i$$

# Results for piecewise constant density

## Initial data

$$\overline{\Omega} = \cup_{i \in L} \overline{\Omega}_i, \quad \Omega_i \cap \Omega_j = \emptyset, \quad i \neq j, \quad \varrho = \varrho_i \in \Omega_i$$

## Incompressible Euler system with piecewise constant density

$$\partial_t \varrho + \operatorname{div}_x \mathbf{v} = 0 \text{ in } \Omega$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{\mathbf{v} \otimes \mathbf{v}}{\varrho} + \left( p(\varrho) - \frac{N}{2} \Lambda \right) \mathbb{I} \right) = 0 \text{ in } \Omega,$$

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0$$

## Kinetic energy

$$\frac{1}{2} \frac{|\mathbf{v}|^2}{\varrho_i} = E_i = \frac{N}{2} \Lambda - \frac{N}{2} p(\varrho_i) \text{ a.a. in } \Omega_i$$

## Solutions of the Euler system with given pressure



However beautiful the strategy, you should occasionally look at the results...  
**Sir Winston Churchill**  
[1874-1965]



# Reformulation

## Original problem

$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x \left( \mathbf{v} \otimes \mathbf{v} - \frac{1}{N} |\mathbf{v}|^2 \mathbb{I} \right) = 0$$

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0, \quad \frac{1}{2} |\mathbf{v}|^2 = E$$

## Reformulation

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \mathbb{U} = 0, \quad \mathbb{U}(t, x) \in R_{0, \text{sym}}^{N \times N}$$

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0$$

$$\mathbb{U} = \mathbf{v} \otimes \mathbf{v} - \frac{1}{N} |\mathbf{v}|^2 \mathbb{I}, \quad \frac{1}{2} |\mathbf{v}|^2 = E$$

## Relaxation

$$\frac{1}{2} |\mathbf{v}|^2 \leq \frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] < E$$

# Subsolutions

Regularity class

$$\mathbf{v} \in C_c^\infty([0, T] \times \Omega; \mathbb{R}^N), \quad \mathbb{U} \in C_c^\infty([0, T] \times \Omega; \mathbb{R}_{0,\text{sym}}^{N \times N})$$

System of equation

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \mathbb{U} = 0$$

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0$$

Convex constraint

$$\frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] < E$$

$$[\mathbf{v}, \mathbb{U}] \mapsto \frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] \text{ convex}$$

# Topology on the space of subsolutions

## Basic space

$$X_0 = \left\{ \mathbf{v} \mid \mathbf{v}, \mathbb{U} \text{ is a subsolution} \right\}$$

## Boundedness

$$\frac{1}{2}|\mathbf{v}|^2 \leq \frac{N}{2}\lambda_{\max}[\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] < E \Rightarrow X_0 \subset \text{bounded set in } L^\infty$$

## Metric on $X_0$

$$d[\mathbf{v}, \mathbf{w}] = \sup_{t \in [0, T]} \sum_n \frac{1}{2^n} \frac{\left| \int_{\Omega} (\mathbf{v}(t, \cdot) - \mathbf{w}(t, \cdot)) \cdot \varphi_n \, dx \right|}{1 + \left| \int_{\Omega} (\mathbf{v}(t, \cdot) - \mathbf{w}(t, \cdot)) \cdot \varphi_n \, dx \right|}$$

## Closure

$$X = \text{closure}_d[X_0] - \text{compact metric space}$$

# Closure of the subsolution space

## Regularity class

$\mathbf{v} \in X \Rightarrow \mathbf{v} \in C_{\text{weak}}([0, T]; L^2(\Omega; R^N)) \cap L^\infty((0, T) \times \Omega), \|\mathbf{v}\|_{L^\infty}^2 \lesssim E$

## System of equation

$$\int_0^T \int_{\Omega} \mathbf{v} \cdot \nabla_x \varphi \, dx dt = 0 \text{ for all } \varphi \in C_c^\infty([0, T] \times \overline{\Omega})$$

$$\int_0^T \int_{\Omega} [\mathbf{v} \cdot \partial_t \varphi + \mathbb{U} : \nabla_x \varphi] \, dx \, dt = - \int_{\Omega} \mathbf{v}_0 \cdot \varphi(0, \cdot) \, dx$$

for some  $\mathbb{U} \in L^\infty((0, T) \times \Omega; R_{0,\text{sym}}^{N \times N})$ , and for all  $\varphi \in C_c^\infty([0, T] \times \overline{\Omega}; R^N)$

## Convex constraint

$$\frac{1}{2} |\mathbf{v}|^2 \leq \frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] \leq E \text{ a.a. in } (0, T) \times \Omega$$

# Distance to “extremal” points

“Distance”

$$I[\mathbf{v}] = \int_0^T \int_{\Omega} \left( E - \frac{1}{2} |\mathbf{v}|^2 \right) dx dt, \mathbf{v} \in X$$

## Properties

- $I$  is a concave functional on  $X$ ; whence upper semi-continuous on  $X$
- 

$$I \geq 0 \text{ on } X$$

$$I[\mathbf{v}] = 0 \Rightarrow \mathbb{U} = \mathbf{v} \otimes \mathbf{v} - \frac{1}{N} |\mathbf{v}|^2 \mathbb{I}, \quad \frac{1}{2} |\mathbf{v}|^2 = E \text{ a.a. in } (0, T) \times \Omega$$
$$\Leftrightarrow$$

$\mathbf{v}$  solves the Euler system with given energy and pressure

## Baire category argument

Point of continuity of  $I$  on  $X$  form a residual set, in particular, they are dense in  $X$

# Existence of infinitely many solutions

**Existence of at least one subsolution**

$E > 0$  large enough  $\Rightarrow X_0$  is non-empty

**Points of continuity of  $I$**

**Claim:**

$v \in X$  – point of continuity of  $I \Rightarrow I[v] = 0$

# Oscillatory Lemma

## Hypotheses

$\mathbf{v} \in X_0$  with the associated flux  $\mathbb{U}$

## Conclusion

There exists a sequence  $\mathbf{w}_n, \mathbb{V}_n, n = 1, 2, \dots$  satisfying:

- $\mathbf{w}_n \in C_c^\infty((0, T) \times \Omega; \mathbb{R}^N), \mathbb{V}_n \in C_c^\infty((0, T) \times \Omega; \mathbb{R}_{0,\text{sym}}^{N \times N})$
- $(\mathbf{v} + \mathbf{w}_n) \in X_0$  with the flux  $\mathbb{U} + \mathbb{V}_n$
- $\mathbf{w}_n \rightarrow 0$  in  $C_{\text{weak}}([0, T]; L^2(\Omega; \mathbb{R}^N))$
- 

$$\liminf_{n \rightarrow \infty} \int_0^T \int_\Omega |\mathbf{w}_n|^2 \, dxdt \geq c(E, N) \int_0^T \int_\Omega \left( E - \frac{1}{2} |\mathbf{v}|^2 \right)^2 \, dxdt$$

## Infinitely many solutions via Oscillatory Lemma, I

**Claim:**  $\mathbf{v} \in X$  – point of continuity of  $I \Rightarrow I[\mathbf{v}] = 0$

■

$I[\mathbf{v}] = \delta > 0, \mathbf{v} \in X \Rightarrow \mathbf{v}_m \in X_0, \mathbf{v}_m \rightarrow \mathbf{v} \in X, I[\mathbf{v}_m] \rightarrow \delta$  as  $m \rightarrow \infty$

■

**Oscillatory lemma**  $\Rightarrow \mathbf{w}_{m,n} \in X_0, \mathbf{v}_m + \mathbf{w}_{m,n} \rightarrow \mathbf{v}_m$  in as  $n \rightarrow \infty$

■

$$\liminf_{n \rightarrow \infty} \int_0^T \int_{\Omega} |\mathbf{v}_m + \mathbf{w}_{m,n}|^2 \, dxdt$$

$$= \int_0^T \int_{\Omega} |\mathbf{v}_m|^2 \, dx + \liminf_{n \rightarrow \infty} \int_0^T \int_{\Omega} |\mathbf{w}_{m,n}|^2 \, dxdt$$

$$\geq \int_0^T \int_{\Omega} |\mathbf{v}_m|^2 \, dx \, dt + c(N, E) \int_0^T \int_{\Omega} \left( E - \frac{1}{2} |\mathbf{v}_m|^2 \right)^2 \, dxdt$$

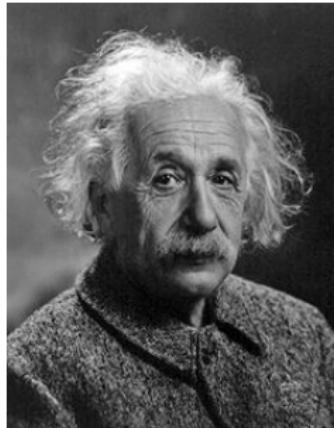
$$\geq \int_0^T \int_{\Omega} |\mathbf{v}_m|^2 \, dx + c(N, E, T, \Omega) I^2([\mathbf{v}_m])$$

## Infinitely many solutions via Oscillatory Lemma, II

### Convergence of functional

$$\begin{aligned} \lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} I[\mathbf{v}_m + \mathbf{w}_{m,n}] &= \int_0^T \int_{\Omega} E - \frac{1}{2} |\mathbf{v}_n + \mathbf{w}_{m,n}|^2 \, dxdt \\ &\leq \lim_{m \rightarrow \infty} \left( \int_0^T \int_{\Omega} E \, dx - \liminf_{n \rightarrow \infty} \int_0^T \int_{\Omega} \frac{1}{2} |\mathbf{v}_n + \mathbf{w}_{m,n}|^2 \, dxdt \right) \\ &\leq \lim_{m \rightarrow \infty} \left( \int_0^T \int_{\Omega} E - \frac{1}{2} |\mathbf{v}_m|^2 \, dxdt - c l^2[\mathbf{v}_m] \right) \end{aligned}$$

# Proof of Oscillatory Lemma



Albert Einstein [1879-1955]

Everything should be made as simple as possible, but not simpler...

- **Past:** What is not allowed is forbidden
- **Present:** What is not forbidden is allowed

# Oscillatory Lemma revisited

## Hypotheses



$$\mathbf{v} \in R^N, \mathbb{U} \in R_{0,\text{sym}}^{N \times N}, \frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] < E, Q = (-1, 1) \times (-1, 1)^N$$

## Conclusion



$$\mathbf{w}_n \in C_c^\infty(Q; R^N), \mathbb{V}_n \in C_c^\infty(Q; R_{0,\text{sym}}^{N \times N})$$

$$\operatorname{div}_x \mathbf{w}_n = 0, \partial_t \mathbf{w}_n + \operatorname{div}_x \mathbb{V}_n = 0$$

$$\frac{N}{2} \lambda_{\max} [(\mathbf{v} + \mathbf{w}_n) \otimes (\mathbf{v} + \mathbf{w}_n) - (\mathbb{U} + \mathbb{V}_n)] < E$$



$$\mathbf{w}_n \rightarrow 0 \text{ in } L^2(Q; R^N)$$

$$\liminf_{n \rightarrow \infty} \int_Q |\mathbf{w}_n|^2 \, dx \, dt \geq c(N, E) \int_Q \left( E - \frac{1}{2} |\mathbf{v}|^2 \right)^2 \, dx \, dt$$

# Oscillatory Lemma - Geometry, I

## Convex set

$$\mathfrak{C} = \left\{ \mathbf{v} \in R^N, \mathbb{U} \in R_{0,\text{sym}}^{N \times N} \mid \frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] < E \right\} \subset R^n$$

$$n = \frac{N(N+3)}{2} - 1$$

## Properties

- $\mathfrak{C} \subset R^n$  is a convex set
- $\frac{1}{2}|\mathbf{v}|^2 \leq \frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}]$
- $\frac{1}{2}|\mathbb{U}|^2 \leq \frac{N-1}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}]$
- $\text{ext}\bar{\mathfrak{C}} \subset \left\{ [\mathbf{v}, \mathbb{U}] \mid \frac{1}{2}|\mathbf{v}|^2 = E, \mathbb{U} = \mathbf{v} \otimes \mathbf{v} - \frac{1}{N}|\mathbf{v}|^2\mathbb{I} \right\}$

# Oscillatory Lemma - Geometry, II

## Extremal points

$$\frac{1}{2}|\mathbf{v}|^2 \leq \frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] = E$$

## Extremal points

$$\frac{1}{2}|\mathbf{v}|^2 < \frac{N}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] \Rightarrow \lambda_{\max} > \lambda_{\min}$$

$[\mathbf{e}_1, \dots, \mathbf{e}_N]$  the normalized eigenvectors of  $[\mathbf{v} \otimes \mathbf{v} - \mathbb{U}]$ ,  $\lambda_N = \lambda_{\min}$

$$\begin{aligned} & (\mathbf{v} + \varepsilon \mathbf{e}_N) \otimes (\mathbf{v} + \varepsilon \mathbf{e}_N) - \left[ \mathbb{U} + \varepsilon \sum_{i=1}^{N-1} v_i ((\mathbf{e}_i \otimes \mathbf{e}_N) + (\mathbf{e}_N \otimes \mathbf{e}_i)) \right] \\ &= \mathbf{v} \otimes \mathbf{v} - \mathbb{U} + (2\varepsilon v_N + \varepsilon^2) \mathbf{e}_N \otimes \mathbf{e}_N \end{aligned}$$

## Oscillatory Lemma - Geometry, III

### Segment Lemma

For any  $[\mathbf{v}, \mathbb{U}] \in \mathfrak{C}$  there exist  $\mathbf{a}, \mathbf{b}$  enjoying the following properties:



$$\frac{1}{2}|\mathbf{a}|^2 = \frac{1}{2}|\mathbf{b}|^2 = E, \quad |\mathbf{a} \pm \mathbf{b}| > 0$$

- there is  $L > 0$  such that

$$[\mathbf{v} + \lambda(\mathbf{a} - \mathbf{b}), \mathbb{U} + \lambda(\mathbf{a} \otimes \mathbf{a} - \mathbf{b} \otimes \mathbf{b})] \in \mathfrak{C},$$

$$\text{dist} [ [\mathbf{v} + \lambda(\mathbf{a} - \mathbf{b}), \mathbb{U} + \lambda(\mathbf{a} \otimes \mathbf{a} - \mathbf{b} \otimes \mathbf{b})] ; \partial \mathfrak{C} ]$$

$$\geq \frac{1}{2} \text{dist} [ [\mathbf{v}, \mathbb{U}] ; \partial \mathfrak{C} ]$$

for all  $-L \leq \lambda \leq L$



$$L|\mathbf{a} - \mathbf{b}| \geq C(N) \frac{1}{\sqrt{E}} \left( E - \frac{1}{2}|\mathbf{v}|^2 \right).$$

# Oscillatory Lemma - Geometry, IV

## Proof of Segment Lemma

1

$$[\mathbf{v}, \mathbb{U}] \in \mathfrak{C}, \mathfrak{C} \text{ convex} \Rightarrow [\mathbf{v}, \mathbb{U}] = \sum_{\text{fin}} \alpha_i \left[ \mathbf{a}_i, \mathbf{a}_i \otimes \mathbf{a}_i - \frac{1}{N} E \mathbb{I} \right]$$

2 Caratheodory Theorem:

$$[\mathbf{v}, \mathbb{U}] = \sum_{i=1}^n \alpha_i \left[ \mathbf{a}_i, \mathbf{a}_i \otimes \mathbf{a}_i - \frac{1}{N} E \mathbb{I} \right], \quad \alpha_1 \geq \alpha_2 \geq \dots \geq \alpha_n$$

$$[\mathbf{v} + \lambda(\mathbf{a}_j - \mathbf{a}_1), \mathbb{U} + \lambda(\mathbf{a}_j \otimes \mathbf{a}_j - \mathbf{a}_1 \otimes \mathbf{a}_1)], \quad \lambda \in [-\alpha_j, \alpha_j]$$

3

$$\alpha_j |\mathbf{a}_j - \mathbf{a}_1| \geq \alpha_k |\mathbf{a}_k - \mathbf{a}_1| \text{ for all } k > 1, \quad \mathbf{a} = \mathbf{a}_1, \quad \mathbf{b} = \mathbf{a}_j, \quad L = \frac{1}{2} \alpha_j$$

4

$$|\mathbf{a} - \mathbf{v}| = \left| \sum_{k=1}^n \alpha_k (\mathbf{a}_1 - \mathbf{a}_k) \right| \leq n \alpha_j |\mathbf{a}_j - \mathbf{a}_1| = 2nL |\mathbf{a} - \mathbf{b}|$$

$$2E - |\mathbf{v}|^2 \leq 2\sqrt{2E}(\sqrt{2E} - |\mathbf{v}|) = 2\sqrt{2E}(|\mathbf{a}| - |\mathbf{v}|) \leq 4\sqrt{2E}nL |\mathbf{a} - \mathbf{b}|$$

# Oscillatory Lemma - Fourier analysis, I

## Fourier transform

$$\widehat{\mathbf{w}}(\xi_0, \dots, \xi_N) = \mathcal{F}_{(t,x) \rightarrow (\xi_0, \xi_1, \dots, \xi_N)} \mathbf{w}(t, x)$$

$$\widehat{\mathbb{V}}(\xi_0, \dots, \xi_N) = \mathcal{F}_{(t,x) \rightarrow (\xi_0, \xi_1, \dots, \xi_N)} \mathbb{V}(t, x)$$

## Field equations

$$\operatorname{div}_x \mathbf{w} = 0 \Leftrightarrow \sum_{i=1}^N \xi_i \widehat{w}_i = 0$$

$$\partial_t \mathbf{w} + \operatorname{div}_x \mathbb{V} = 0 \Leftrightarrow \xi_0 \widehat{w}_i + \sum_{j=1}^N \xi_j \widehat{V}_{i,j} = 0, \quad i = 1, \dots, N$$

## Vector formulation

$$\operatorname{DIV}_{t,x} \begin{bmatrix} 0 & \mathbf{w} \\ \mathbf{w} & \mathbb{V} \end{bmatrix} = 0 \Leftrightarrow \boldsymbol{\xi} \cdot \begin{bmatrix} 0 & \widehat{\mathbf{w}} \\ \widehat{\mathbf{w}} & \widehat{\mathbb{V}} \end{bmatrix} = 0$$

# Oscillatory Lemma - Fourier analysis, II

## Operator ansatz

$$\xi = [\xi_0, \xi_1, \dots, \xi_N] \mapsto \mathbb{A}_{\mathbf{a}, \mathbf{b}}(\xi) \in R_{0, \text{sym}}^{(N+1) \times (N+1)},$$

$$\mathbb{A}_{\mathbf{a}, \mathbf{b}}(\xi) = \frac{1}{2} ((\mathbb{R} \cdot \xi) \otimes (\mathbb{Q}(\xi) \cdot \xi) + (\mathbb{Q}(\xi) \cdot \xi) \otimes (\mathbb{R} \cdot \xi))$$

where

$$\mathbb{Q} = \xi \otimes \mathbf{e}_0 - \mathbf{e}_0 \otimes \xi, \quad \mathbb{R} = ([0, \mathbf{a}] \otimes [0, \mathbf{b}]) - ([0, \mathbf{b}] \otimes [0, \mathbf{a}]),$$

$$\mathbf{e}_0 = [1, 0, \dots, 0], \quad \mathbf{a}, \mathbf{b} \in R^N, \quad \frac{1}{2}|\mathbf{a}|^2 = \frac{1}{2}|\mathbf{b}|^2 = E > 0, \quad |\mathbf{a} \pm \mathbf{b}| > 0.$$

## Third order differential operator

$$\mathbb{A}_{\mathbf{a}, \mathbf{b}}(\partial) = \mathbb{A}_{\mathbf{a}, \mathbf{b}}(\partial_t, \partial_{x_1}, \dots, \partial_{x_N})$$

# Oscillatory Lemma - Fourier analysis, III

## Properties of the differential operator

■

$$\begin{bmatrix} 0 & \mathbf{w} \\ \mathbf{w} & \mathbb{V} \end{bmatrix} = \mathbb{A}_{\mathbf{a}, \mathbf{b}}(\partial)[\varphi], \quad \varphi \in C_c^\infty(\mathbb{R}^{N+1})$$

$$\Rightarrow \operatorname{div}_x \mathbf{w} = 0, \quad \partial_t \mathbf{w} + \operatorname{div}_x \mathbb{V} = 0$$

■

$$\psi \in C_c^\infty(\mathbb{R})$$

$$\eta_{\mathbf{a}, \mathbf{b}} = -\frac{1}{(|\mathbf{a}||\mathbf{b}| + \mathbf{a} \cdot \mathbf{b})^{2/3}} \left[ [0, \mathbf{a}] + [0, \mathbf{b}] - (|\mathbf{a}||\mathbf{b}| + \mathbf{a} \cdot \mathbf{b}) \mathbf{e}_0 \right]$$
$$\Rightarrow$$

$$\mathbb{A}_{\mathbf{a}, \mathbf{b}}(\partial)[\psi([t, \mathbf{x}] \cdot \eta_{\mathbf{a}, \mathbf{b}})] = \psi'''([t, \mathbf{x}] \cdot \eta_{\mathbf{a}, \mathbf{b}}) \begin{bmatrix} 0 & \mathbf{a} - \mathbf{b} \\ \mathbf{a} - \mathbf{b} & \mathbf{a} \otimes \mathbf{a} - \mathbf{b} \otimes \mathbf{b} \end{bmatrix}$$

# Construction of the differential operator $N = 2$ , I

## Abstract ansatz

$$\mathbb{A}_{\mathbf{a}, \mathbf{b}}(\xi) = \begin{bmatrix} 0 & A^{0,1}(\xi) & A^{0,2}(\xi) \\ A^{1,0}(\xi) & A^{1,1}(\xi) & A^{1,2}(\xi) \\ A^{2,0}(\xi) & A^{2,1}(\xi) & A^{2,2}(\xi) \end{bmatrix}$$

## Symmetry properties

$$A^{1,1}(\xi) = -A^{2,2}(\xi), A^{0,1}(\xi) = A^{1,0}(\xi), A^{0,2}(\xi) = A^{2,0}(\xi), A^{1,2}(\xi) = A^{2,1}(\xi)$$

## Reduced form

$$B = \frac{A^{0,1}}{A^{1,1}}, C = \frac{A^{0,2}}{A^{1,1}}, D = \frac{A^{1,2}}{A^{1,1}}$$

$$\mathbb{A}_{\mathbf{a}, \mathbf{b}}(\xi) = \begin{bmatrix} 0 & B(\xi) & C(\xi) \\ B(\xi) & 1 & D(\xi) \\ C(\xi) & D(\xi) & -1 \end{bmatrix} A^{1,1}(\xi)$$

# Construction of the differential operator $N = 2$ , II

## Differential constraints

$$\xi_1 B + \xi_2 C = 0, \quad \xi_0 B + \xi_1 + \xi_2 D = 0, \quad \xi_0 C + \xi_1 D - \xi_2 = 0$$

unique solution

$$B(\xi) = \frac{1}{2} \frac{\xi_2^2 - \xi_1^2}{\xi_0 \xi_1} - \frac{\xi_2^2}{\xi_0 \xi_1}, \quad C(\xi) = \frac{\xi_2}{\xi_0} - \frac{1}{2} \frac{\xi_2^2 - \xi_1^2}{\xi_0 \xi_2}, \quad D(\xi) = \frac{1}{2} \frac{\xi_2^2 - \xi_1^2}{\xi_1 \xi_2}.$$

## Final form

$$\mathbb{A}_{\mathbf{a}, \mathbf{b}}(\xi) = A_{\mathbf{a}, \mathbf{b}} \begin{bmatrix} 0 & -\frac{\xi_2}{2}(\xi_1^2 + \xi_2^2) & \frac{\xi_1}{2}(\xi_1^2 + \xi_2^2) \\ -\frac{\xi_2}{2}(\xi_1^2 + \xi_2^2) & \xi_0 \xi_1 \xi_2 & \frac{\xi_0}{2}(\xi_2^2 - \xi_1^2) \\ \frac{\xi_1}{2}(\xi_1^2 + \xi_2^2) & \frac{\xi_0}{2}(\xi_2^2 - \xi_1^2) & -\xi_0 \xi_1 \xi_2 \end{bmatrix}.$$

# Construction of the differential operator $N = 2$ , III

## Fixing the coefficients

$$\begin{aligned} & \mathbb{A}_{\mathbf{a}, \mathbf{b}}(\partial) \psi([t, x] \cdot \eta) \\ &= A_{\mathbf{a}, \mathbf{b}} \psi'''([t, x] \cdot \eta) \begin{bmatrix} 0 & -\frac{\eta_2}{2}(\eta_1^2 + \eta_2^2) & \frac{\eta_1}{2}(\eta_1^2 + \eta_2^2) \\ -\frac{\eta_2}{2}(\eta_1^2 + \eta_2^2) & \eta_0 \eta_1 \eta_2 & \frac{\eta_0}{2}(\eta_2^2 - \eta_1^2) \\ \frac{\eta_1}{2}(\eta_1^2 + \eta_2^2) & \frac{\eta_0}{2}(\eta_2^2 - \eta_1^2) & -\eta_0 \eta_1 \eta_2 \end{bmatrix} \end{aligned}$$

$$\frac{A}{2}(\eta_1^2 + \eta_2^2) [-\eta_2, \eta_1] = \mathbf{a} - \mathbf{b},$$

$$A \eta_0 \begin{bmatrix} \eta_1 \eta_2 & \frac{1}{2}(\eta_2^2 - \eta_1^2) \\ \frac{1}{2}(\eta_2^2 - \eta_1^2) & -\eta_1 \eta_2 \end{bmatrix} = \mathbf{a} \otimes \mathbf{a} - \mathbf{b} \otimes \mathbf{b}, \quad \frac{1}{2}|\mathbf{a}|^2 = \frac{1}{2}|\mathbf{b}|^2 = E.$$

## Ansatz

$$[\eta_1, \eta_2] = \Lambda(\mathbf{a} + \mathbf{b})$$

find  $\Lambda$ ,  $A$ ,  $\eta_0$

# Proof of Oscillatory Lemma

## Ansatz

- 1 for given  $[\mathbf{v}, \mathbb{U}] \in \mathfrak{C}$  identify the vectors  $\mathbf{a}, \mathbf{b}$  via Segment Lemma
- 2 consider the operator  $\mathbb{A}_{\mathbf{a}, \mathbf{b}}(\partial)$  and the direction  $\eta_{\mathbf{a}, \mathbf{b}}$
- 3

$$\begin{bmatrix} 0 & \mathbf{w}_n \\ \mathbf{v}_n & \mathbb{V}_n \end{bmatrix} = \mathbb{A}_{\mathbf{a}, \mathbf{b}}(\partial) \left[ \varphi \frac{L}{n^3} \cos(n[t, x] \cdot \eta_{\mathbf{a}, \mathbf{b}}) \right], \quad \varphi \in C_c^\infty(Q)$$

$$0 \leq \varphi \leq 1, \quad \varphi(t, x) = 1$$

whenever  $-\frac{1}{2} \leq t \leq \frac{1}{2}, -\frac{1}{2} \leq x_j \leq \frac{1}{2}, j = 1, \dots, N$ .

## 4

$$\begin{aligned} & \mathbb{A}_{\mathbf{a}, \mathbf{b}}(\partial) \left[ \varphi \frac{L}{n^3} \cos(n[t, x] \cdot \eta_{\mathbf{a}, \mathbf{b}}) \right] \\ &= \varphi \sin(n[t, x] \cdot \eta_{\mathbf{a}, \mathbf{b}}) L \begin{bmatrix} 0 & (\mathbf{a} - \mathbf{b}) \\ (\mathbf{a} - \mathbf{b}) & \mathbf{a} \otimes \mathbf{a} - \mathbf{b} \otimes \mathbf{b} \end{bmatrix} + \frac{1}{n} R_n, \quad |R_n| \leq C \end{aligned}$$

# Oscillatory Lemma - piecewise constant functions

## Hypotheses

■

$$Q = \cup \overline{Q}_i, \quad Q_i \cap Q_j = \emptyset \text{ for } i \neq j, \quad Q_i = (-a_i, a_i) \times (-a_i, a_i)^N$$

$$\mathbf{v} = \sum \mathbf{v}^i 1_{Q_i}, \quad \mathbb{U} = \sum \mathbb{U}_i 1_{\Omega_i}$$

$$\mathbf{v}_i \in R^N, \quad \mathbb{U}_i \in R_{0,\text{sym}}^{N \times N}, \quad \frac{N}{2} \lambda_{\max} [\mathbf{v}_i \otimes \mathbf{v}_i - \mathbb{U}_i] < E_i$$

## Conclusion

■

$$\mathbf{w}_n \in C_c^\infty(Q; R^N), \quad \mathbb{V}_n \in C_c^\infty(Q; R_{0,\text{sym}}^{N \times N})$$

$$\operatorname{div}_x \mathbf{w}_n = 0, \quad \partial_t \mathbf{w}_n + \operatorname{div}_x \mathbb{V}_n = 0$$

$$\frac{N}{2} \lambda_{\max} [(\mathbf{v} + \mathbf{w}_n) \otimes (\mathbf{v} + \mathbf{w}_n) - (\mathbb{U} + \mathbb{V}_n)] < E$$

■

$$\mathbf{w}_n \rightarrow 0 \text{ in } L^2(Q; R^N))$$

$$\liminf_{n \rightarrow \infty} \int_Q |\mathbf{w}_n|^2 \, dx \, dt \geq c(N, E) \int_Q \left( E - \frac{1}{2} |\mathbf{v}|^2 \right)^2 \, dx \, dt$$

# Oscillatory Lemma - continuous functions

## Decomposition

$$Q = \cup \overline{Q_i}, \quad Q_i \cap Q_j = \emptyset \text{ for } i \neq j, \quad Q_i = (-a_i, a_i) \times (-a_i, a_i)^N$$

$$\frac{3}{2} \lambda_{\max} [\mathbf{v}_i \otimes \mathbf{v}_i - \mathbb{U}_i] < E_i - \delta \text{ in } Q^i, \quad i = 1, \dots, m$$

for arbitrary constant quantities

$$\mathbf{v}_i = \mathbf{v}(t_{i,v}, x_{i,v}), \quad \mathbb{U}_i = \mathbb{U}(t_{i,u}, r_{i,u}), \quad E_i = E(t_{i,e}, x_{i,e}), \quad (t_{i,\cdot}, x_{i,\cdot}) \in Q^i.$$

$$\left| \frac{3}{2} \lambda_{\max} [(\mathbf{v}_i + \mathbf{w}) \otimes (\mathbf{v}_i + \mathbf{w}) - (\mathbb{U}_i + \mathbb{V})] - \left( -\frac{3}{2} \lambda_{\max} [(\mathbf{v} + \mathbf{w}) \otimes (\mathbf{v} + \mathbf{w}) - (\mathbb{U} + \mathbb{V})] \right) \right| < \frac{\delta}{2}$$

## Conclusion

$$\liminf_{n \rightarrow \infty} \int_Q |\mathbf{w}_n|^2 \, dx \, dt \geq c(N, E) \int_Q \left( E - \delta - \frac{1}{2} |\mathbf{v}|^2 \right)^2 \, dx \, dt$$

# Abstract formulation

Variable coefficients “Euler system”

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \mathbf{h}[\mathbf{v}]) \otimes (\mathbf{v} + \mathbf{h}[\mathbf{v}])}{r[\mathbf{v}]} - \frac{1}{N} \frac{|\mathbf{v} + \mathbf{h}[\mathbf{v}]|^2}{r[\mathbf{v}]} + \mathbb{M}[\mathbf{v}] \right) = 0$$

$$\operatorname{div}_x \mathbf{v} = 0,$$

Kinetic energy

$$\frac{1}{2} \frac{|\mathbf{v} + \mathbf{h}[\mathbf{v}]|^2}{r[\mathbf{v}]} = E[\mathbf{v}]$$

Data

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0, \quad \mathbf{v}(T, \cdot) = \mathbf{v}_T$$

# Abstract operators

## Boundedness

$b$  maps bounded sets in  $L^\infty((0, T) \times \Omega; R^N)$  on bounded sets in  $C_b(Q, R^M)$

## Continuity

$b[\mathbf{v}_n] \rightarrow b[\mathbf{v}]$  in  $C_b(Q; R^M)$  (uniformly for  $(t, x) \in Q$ )

whenever

$\mathbf{v}_n \rightarrow \mathbf{v}$  in  $C_{\text{weak}}([0, T]; L^2(\Omega; R^N))$

## Causality

$\mathbf{v}(t, \cdot) = \mathbf{w}(t, \cdot)$  for  $0 \leq t \leq \tau \leq T$  implies  $b[\mathbf{v}] = b[\mathbf{w}]$  in  $[(0, \tau] \times \Omega]$

# Results

## Result (A)

The set of subsolutions is non-empty  $\Rightarrow$  there exists infinitely many weak solutions of the problem with the same initial data

## Initial energy jump

$$\frac{1}{2} \frac{|\mathbf{v}_0 + \mathbf{h}[\mathbf{v}_0]|^2}{r[\mathbf{v}_0]} < \liminf_{t \rightarrow 0+} \frac{1}{2} \frac{|\mathbf{v} + \mathbf{h}[\mathbf{v}]|^2}{r[\mathbf{v}]}$$

## Result (B)

The set of subsolutions is non-empty  $\Rightarrow$  there exists a dense set of times  $\{t_i\}$  such that the values  $\mathbf{v}(t_i)$  give rise to non-empty subsolution set with

$$\frac{1}{2} \frac{|\mathbf{v}(t_i) + \mathbf{h}[\mathbf{v}](t_i)|^2}{r[\mathbf{v}](t_i)} = \lim_{t \rightarrow t_i+} \frac{1}{2} \frac{|\mathbf{v} + \mathbf{h}[\mathbf{v}]|^2}{r[\mathbf{v}]}$$

# Savage-Hutter model for avalanches

## Unknowns

- flow height .....  $h = h(t, x)$   
depth-averaged velocity .....  $\mathbf{u} = \mathbf{u}(t, x)$

$$\partial_t h + \operatorname{div}_x(h\mathbf{u}) = 0$$

$$\partial_t(h\mathbf{u}) + \operatorname{div}_x(h\mathbf{u} \otimes \mathbf{u}) + \nabla_x(ah^2) = h \left( -\gamma \frac{\mathbf{u}}{|\mathbf{u}|} + \mathbf{f} \right)$$

## Periodic boundary conditions

$$\Omega = ([0, 1]|_{\{0,1\}})^2$$

# Application to Savage-Hutter model

## Theorem

(joint work with P. Gwiazda and A. Świerczewska-Gwiazda)

- (i) Let the initial data

$$h_0 \in C^2(\Omega), \mathbf{u}_0 \in C^2(\Omega; \mathbb{R}^2), h_0 > 0 \text{ in } \Omega$$

be given, and let  $\mathbf{f}$  and  $a$  be smooth.

Then the Savage-Hutter system admits infinitely many weak solutions in  $(0, T) \times \Omega$ .

- (ii) Let  $T > 0$  and

$$h_0 \in C^2(\Omega), h_0 > 0$$

be given.

Then there exists

$$\mathbf{u}_0 \in L^\infty(\Omega; \mathbb{R}^2)$$

such that the Savage-Hutter system admits infinitely many weak solutions in  $(0, T) \times \Omega$  satisfying the energy inequality.

# Transformation - Step I

## Helmholtz decomposition

$$h\mathbf{u} = \mathbf{v} + \mathbf{V} + \nabla_x \Psi$$

where

$$\operatorname{div}_x \mathbf{v} = 0, \quad \int_{\Omega} \Psi \, dx = 0, \quad \int_{\Omega} \mathbf{v} \, dx = 0, \quad \mathbf{V} \in R^2$$

## Fixing $h$ and the potential $\Psi$

$$\partial_t h + \Delta \Psi = 0$$

$$h(0, \cdot) = h_0, \quad -\partial_t h(0, \cdot) = \Delta \Psi_0$$

# Problem I

## Equation

$$\begin{aligned} \partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \mathbf{V} + \nabla_x \Psi) \otimes (\mathbf{v} + \mathbf{V} + \nabla_x \Psi)}{h} + (\alpha h^2 + \partial_t \Psi) \mathbb{I} \right) \\ + \partial_t \mathbf{V} \\ = h \left( -\gamma \frac{\mathbf{v} + \mathbf{V} + \nabla_x \Psi}{|\mathbf{v} + \mathbf{V} + \nabla_x \Psi|} + \mathbf{f} \right), \end{aligned}$$

## Constraints and initial conditions

$$\operatorname{div}_x \mathbf{v} = 0, \quad \int_{\Omega} \mathbf{v}(t, \cdot) \, dx = 0$$

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0, \quad \mathbf{V}(0) = \mathbf{V}_0$$

## Transformation - Step II

Prescribing the kinetic energy

$$\frac{1}{2} \frac{|\mathbf{v} + \mathbf{V} + \nabla_x \Psi|^2}{h} = E \equiv \Lambda(t) - ah^2 - \partial_t \Psi$$

Problem II

$$\begin{aligned} & \partial_t \mathbf{v} + \partial_t \mathbf{V} \\ & + \operatorname{div}_x \left( \frac{(\mathbf{v} + \mathbf{V} + \nabla_x \Psi) \otimes (\mathbf{v} + \mathbf{V} + \nabla_x \Psi)}{h} - \frac{1}{2} \frac{|\mathbf{v} + \mathbf{V} + \nabla_x \Psi|^2}{h} \mathbb{I} \right) \\ & = -\gamma \left( \frac{h}{2E} \right)^{1/2} (\mathbf{v} + \mathbf{V} + \nabla_x \Psi) + h \mathbf{f} \end{aligned}$$

## Transformation - Step III

Determining function  $\mathbf{V}$

$$\begin{aligned}\partial_t \mathbf{V} - \left[ \frac{1}{|\Omega|} \int_{\Omega} \gamma \left( \frac{h}{2E} \right)^{1/2} dx \right] \mathbf{V} \\ = + \frac{1}{|\Omega|} \int_{\Omega} \left[ \gamma \left( \frac{h}{2E} \right)^{1/2} (\mathbf{v} + \nabla_x \Psi) + h \mathbf{f} \right] dx, \quad \mathbf{V}(0) = \mathbf{V}_0\end{aligned}$$

## Problem III

### Equation

$$\begin{aligned}\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \mathbf{V}[\mathbf{v}] + \nabla_x \Psi) \odot (\mathbf{v} + \mathbf{V}[\mathbf{v}] + \nabla_x \Psi)}{h} \right) \\ = -\gamma \left( \frac{h}{2E} \right)^{1/2} (\mathbf{v} + \mathbf{V}[\mathbf{v}] + \nabla_x \Psi) \\ + \frac{1}{|\Omega|} \int_{\Omega} \gamma \left( \frac{h}{2E} \right)^{1/2} (\mathbf{v} + \mathbf{V}[\mathbf{v}] + \nabla_x \Psi) \, dx + h \mathbf{f} - \frac{1}{|\Omega|} \int_{\Omega} h \mathbf{f} \, dx\end{aligned}$$

$$\mathbf{v} \odot \mathbf{w} = \mathbf{v} \otimes \mathbf{w} - \frac{1}{2} \mathbf{v} \cdot \mathbf{w} \mathbb{I}$$

## Transformation - Step IV

### Solving elliptic problem

$$\begin{aligned}\operatorname{div}_x \mathbb{M} &\equiv \operatorname{div}_x (\nabla_x \mathbf{m} + \nabla_x^t \mathbf{m} - \operatorname{div}_x \mathbf{m} \mathbb{I}) \\&= -\gamma \left( \frac{h}{2E} \right)^{1/2} (\mathbf{v} + \mathbf{V}[\mathbf{v}] + \nabla_x \Psi) \\&+ \frac{1}{|\Omega|} \int_{\Omega} \gamma \left( \frac{h}{2E} \right)^{1/2} (\mathbf{v} + \mathbf{V}[\mathbf{v}] + \nabla_x \Psi) \, dx + h \mathbf{f} - \frac{1}{|\Omega|} \int_{\Omega} h \mathbf{f} \, dx, \\&\quad \int_{\Omega} \mathbb{M}(t, \cdot) \, dx = 0 \text{ for any } t \in [0, T].\end{aligned}$$

# Abstract formulation

Variable coefficients “Euler system”

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \mathbf{H}[\mathbf{v}]) \odot (\mathbf{v} + \mathbf{H}[\mathbf{v}])}{h[\mathbf{v}]} + \mathbb{M}[\mathbf{v}] \right) = 0$$
$$\operatorname{div}_x \mathbf{v} = 0,$$

Kinetic energy

$$\frac{1}{2} \frac{|\mathbf{v} + \mathbf{H}[\mathbf{v}]|^2}{h[\mathbf{v}]} = E[\mathbf{v}]$$

Data

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0, \quad \mathbf{v}(T, \cdot) = \mathbf{v}_T$$

# Euler-Fourier system

(joint work with E. Chiodaroli and O.Kreml)

**Mass conservation**

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

**Momentum balance**

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x(\varrho \vartheta) = 0$$

**Internal energy balance**

$$\frac{3}{2} \left[ \partial_t(\varrho \vartheta) + \operatorname{div}_x(\varrho \vartheta \mathbf{u}) \right] - \Delta \vartheta = -\varrho \vartheta \operatorname{div}_x \mathbf{u}$$

# Transformation

## Ansatz

$$\varrho \mathbf{u} = \mathbf{v} + \nabla_x \Psi, \quad \operatorname{div}_x \mathbf{v} = 0$$

## Equations

$$\partial_t \varrho + \Delta \Psi = 0$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \nabla_x \Psi) \otimes (\mathbf{v} + \nabla_x \Psi)}{\varrho} \right) + \nabla_x (\partial_t \Psi + \varrho \vartheta) = 0$$

$$\frac{3}{2} \left( \partial_t (\varrho \vartheta) + \operatorname{div}_x (\vartheta (\mathbf{v} + \nabla_x \Psi)) \right) - \Delta \vartheta = -\varrho \vartheta \operatorname{div}_x \left( \frac{\mathbf{v} + \nabla_x \Psi}{\varrho} \right)$$

## Energy

$$E = \Lambda(t) - \frac{3}{2} \varrho \vartheta [\mathbf{v}] - \frac{3}{2} \partial_t \Psi$$

# Solution

## Construction of solutions

- 1 Fix  $\varrho$  and compute the acoustic potential  $\Psi$

$$-\Delta\Psi = \partial_t\varrho$$

- 2 Compute  $\vartheta = \vartheta[\mathbf{v}]$  for  $\mathbf{v} \in L^\infty$

$$\frac{3}{2} \left( \partial_t(\varrho\vartheta) + \operatorname{div}_x \left( \vartheta(\mathbf{v} + \nabla_x \Psi) \right) \right) - \Delta\vartheta = -\varrho\vartheta \operatorname{div}_x \left( \frac{\mathbf{v} + \nabla_x \Psi}{\varrho} \right)$$

- 3 Observe that  $0 < \vartheta < \bar{\vartheta}$ ,  $\bar{\vartheta}$  independent of  $\mathbf{v}$

- 4 Take

$$E = \chi(t) - \frac{3}{2}\varrho\vartheta[\mathbf{v}]$$

and use the non-local variant of Oscillatory Lemma

# Euler-Korteweg-Poisson system

(joint work with D.Donatelli and P.Marcati)

Mass conservation - equation of continuity

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

Momentum equations - Newton's second law

$$\begin{aligned} & \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho) \\ &= \boxed{\varrho \nabla_x \left( K(\varrho) \Delta_x \varrho + \frac{1}{2} K'(\varrho) |\nabla_x \varrho|^2 \right) - \varrho \mathbf{u} + \varrho \nabla_x V} \end{aligned}$$

Poisson equation

$$\Delta_x V = \varrho - \bar{\varrho}$$

# Euler-Cahn-Hilliard system

Model by Lowengrub and Truskinovsky

## Mass conservation

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p_0(\varrho, c) = \operatorname{div}_x \left( \varrho \nabla_x c \otimes \nabla_x c - \frac{\varrho}{2} |\nabla_x c|^2 \mathbb{I} \right)$$

## Cahn-Hilliard equation

$$\partial_t(\varrho c) + \operatorname{div}_x(\varrho c \mathbf{u}) = \Delta \left( \mu_0(\varrho, c) - \frac{1}{\varrho} \operatorname{div}_x (\varrho \nabla_x c) \right)$$

# Models of collective behavior

(joint work with J.A. Carrillo, P.Gwiazda, A.Swierczewska-Gwiazda)

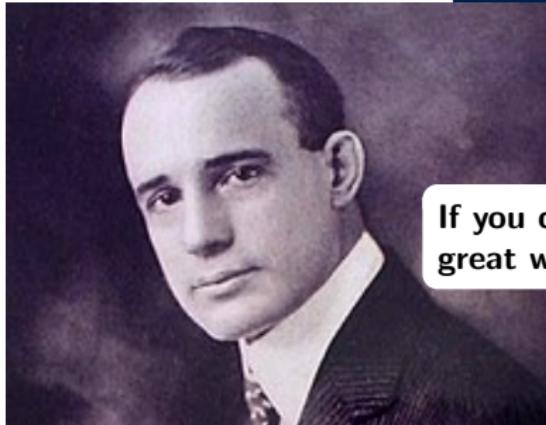
## Mass conservation

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\begin{aligned} & \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) \\ &= -\nabla_x p(\varrho) + \left(1 - H(|\mathbf{u}|^2)\right) \varrho \mathbf{u} \\ & \quad - \varrho \nabla_x K * \varrho + \varrho \psi * \left[\varrho (\mathbf{u} - \mathbf{u}(\cdot))\right] \end{aligned}$$

## Inviscid limits



If you cannot do great things, do small things in a great way

Napoleon Hill [1883-1970]

Oliver Napoleon Hill was an American self-help author

# Navier–Stokes system

## Field equations

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho) = \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u})$$

## Constitutive equations

$$p(\varrho) = a \varrho^\gamma, \quad a > 0, \quad \gamma > 1$$

$$\mathbb{S}(\nabla_x \mathbf{u}) = \mu \left( \nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{N} \operatorname{div}_x \mathbf{u} \mathbb{I} \right) + \eta \operatorname{div}_x \mathbf{u} \mathbb{I}$$

## Far field conditions

$$\varrho \rightarrow \varrho_\infty > 0, \quad \mathbf{u} \rightarrow 0 \text{ as } |x| \rightarrow \infty$$

# Finite energy solutions

## Energy inequality

$$\begin{aligned} & \int_{R^N} \left[ \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty) \right] (\tau, \cdot) \, dx \\ & \quad + \int_0^\tau \int_{R^N} \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} \, dx dt \\ & \leq \int_{R^N} \left[ \frac{1}{2} \frac{|\mathbf{m}_0|^2}{\varrho_0} + P(\varrho_0) - P'(\varrho_\infty)(\varrho_0 - \varrho_\infty) - P(\varrho_\infty) \right] \, dx \end{aligned}$$

## Bounded energy solutions

$$\begin{aligned} & \int_{R^N} \left[ \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty) \right] (\tau, \cdot) \, dx \\ & \quad + \int_0^\tau \int_{R^N} \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} \, dx dt \leq E_0 \end{aligned}$$

# Uniform bounds

## Pressure potential

$$P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty) \gtrsim \begin{cases} |\varrho - \varrho_\infty|^2 & \text{if } \frac{\varrho_\infty}{2} < \varrho < 2\varrho_\infty \\ 1 + P(\varrho) & \text{otherwise} \end{cases}$$

## Viscous stress

$$\mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} = \frac{\mu}{2} \left| \nabla_x \mathbf{u} + \nabla_x \mathbf{u}^t - \frac{2}{N} \operatorname{div}_x \mathbf{u} \right|^2 + \eta |\operatorname{div}_x \mathbf{u}|^2$$

# Vanishing viscosity limit

## Viscosity coefficients

$$\mu = \mu_n \searrow 0, \quad \eta = \eta_n \searrow 0$$

## Approximate solutions

$(\varrho_n - \varrho_\infty)$  bounded in  $L^\infty(0, T; (L^\gamma + L^2)(R^N))$

$\mathbf{m}_n \equiv \varrho_n \mathbf{u}_n$  bounded in  $L^\infty(0, T; (L^{\frac{2\gamma}{\gamma+1}} + L^2)(R^N))$

## Convergence in the sense of distributions

$\varrho_n \rightarrow \varrho$  in  $\mathcal{D}'((0, T) \times R^N), \quad \varrho - \varrho_\infty \in L^\infty(0, T; (L^\gamma + L^2)(R^N))$

$\mathbf{m}_n \rightarrow \mathbf{m}$  in  $\mathcal{D}'((0, T) \times R^N; R^N), \quad \mathbf{m} \in L^\infty(0, T; (L^{\frac{2\gamma}{\gamma+1}} + L^2)(R^N))$

## Strong convergence to weak solutions

### Theorem - EF, M.Hofmanová

Suppose that  $\varrho, \mathbf{m}$  is a weak solution of the Euler system in  $D'((0, T) \times R^N)$ .

Then

$$\begin{aligned} & \left[ \frac{1}{2} \frac{|\mathbf{m}_n|^2}{\varrho_n} + P(\varrho_n) - P'(\varrho_\infty)(\varrho_n - \varrho_\infty) - P(\varrho_\infty) \right] \\ & \rightarrow \left[ \frac{1}{2} \frac{|\mathbf{m}|^2}{\varrho} + P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty) \right] \end{aligned}$$

in  $L^1((0, T) \times R^N)$ , in particular

$$(\varrho_n - \varrho_\infty) \rightarrow (\varrho - \varrho_\infty) \text{ in } (L^\gamma + L^2)((0, T) \times R^N)$$

$$\mathbf{m}_n \rightarrow \mathbf{m} \text{ in } (L^{\frac{2\gamma}{\gamma+1}} + L^2)((0, T) \times R^N, R^N)$$

# Energy defect

## Bounded energy

$$e(\varrho_n, \mathbf{m}_n) \equiv \left[ \frac{1}{2} \frac{|\mathbf{m}_n|^2}{\varrho_n} + P(\varrho_n) - P'(\varrho_\infty)(\varrho_n - \varrho_\infty) - P(\varrho_\infty) \right]$$

bounded in  $L^\infty(0, T; L^1(\mathbb{R}^N))$ .

## Duality

$L^1(\mathbb{R}^N) \hookrightarrow \mathcal{M}(\mathbb{R}^N)$  – the space of **finite** Borel measures

$$\mathcal{M}(\mathbb{R}^N) = [C_0(\mathbb{R}^N)]^*$$

$$L^\infty(0, T; L^1(\mathbb{R}^N)) \hookrightarrow [L^1(0, T; C_0(\mathbb{R}^N))]^*$$

## Weak convergence

$$e(\varrho_n, \mathbf{m}_n) \rightarrow \overline{e(\varrho, \mathbf{m})}$$

$$P(\varrho_n) - P'(\varrho_\infty)(\varrho_n - \varrho_\infty) - P(\varrho_\infty) \rightarrow \overline{P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty)}$$

weakly-(\*) in  $L^\infty(0, T; \mathcal{M}(\mathbb{R}^N))$

# Pressure defect, I

Isentropic pressure, weak convergence

$$p(\varrho) = (\gamma - 1)P(\varrho)$$

$$\begin{aligned} p(\varrho_n) - p'(\varrho_\infty)(\varrho_n - \varrho_\infty) - p(\varrho_\infty) \\ \rightarrow (\gamma - 1)\overline{P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty)} \end{aligned}$$

weakly-(\*) in  $L^\infty(0, T; \mathcal{M}(R^N))$

Compatibility

$$\begin{aligned} & \lim_{n \rightarrow \infty} \int_0^T \int_{R^N} [p(\varrho_n) - p(\varrho)] \operatorname{div}_x \varphi \, dx dt \\ &= \lim_{n \rightarrow \infty} \int_0^T \int_{R^N} [p(\varrho_n) - p'(\varrho_\infty)(\varrho_n - \varrho_\infty) - p(\varrho_\infty)] \operatorname{div}_x \varphi \, dx dt \\ & \quad - \int_0^T \int_{R^N} [p(\varrho) - p'(\varrho_\infty)(\varrho - \varrho_\infty) - p(\varrho_\infty)] \operatorname{div}_x \varphi \, dx dt \\ & \varphi \in C_c^\infty((0, T) \times R^N; R^N) \end{aligned}$$

# Pressure defect, II

## Internal energy defect

$$\overline{P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty)} - \left[ P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty) \right] \geq 0$$

## Pressure defect

$$\begin{aligned}\mathfrak{R}_p &= (\gamma - 1) \overline{P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty)} \\ &\quad - (\gamma - 1) \left[ P(\varrho) - P'(\varrho_\infty)(\varrho - \varrho_\infty) - P(\varrho_\infty) \right] \geq 0 \\ \mathfrak{R}_p &\in L^\infty(0, T; \mathcal{M}^+(R^N))\end{aligned}$$

## Compatibility

$$\lim_{n \rightarrow \infty} \int_0^T \int_{R^N} [p(\varrho_n) - p(\varrho)] \operatorname{div}_x \varphi \, dx dt = \int_0^T \int_{R^N} \operatorname{div}_x \varphi \, d\mathfrak{R}_p$$

# Turbulent stress

Convective term

$$\frac{\mathbf{m}_n \otimes \mathbf{m}_n}{\varrho_n} \in L^\infty(0, T; L^1(\mathbb{R}^N; \mathbb{R}_{\text{sym}}^{N \times N}))$$

Weak convergence

$$\frac{\mathbf{m}_n \otimes \mathbf{m}_n}{\varrho_n} \rightarrow \overline{\frac{\mathbf{m} \otimes \mathbf{m}}{\varrho}}$$

weakly-(\*) in  $L^\infty(0, T; \mathcal{M}(\mathbb{R}^N; \mathbb{R}_{\text{sym}}^{N \times N}))$

Turbulent viscous stress (defect)

$$\mathfrak{R}_v = \overline{\frac{\mathbf{m} \otimes \mathbf{m}}{\varrho}} - \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} \in L^\infty(0, T; \mathcal{M}^+(\mathbb{R}^N; \mathbb{R}_{\text{sym}}^{N \times N}))$$

# Positivity of the turbulent stress

## Positivity of a matrix valued measure

$$\mathbb{D} \in \mathcal{M}^+(R^N; R_{\text{sym}}^{N \times N}) \Leftrightarrow \int_{R^N} \varphi(\xi \otimes \xi) : d\mathbb{D} \geq 0$$

for any  $\varphi \in C_c^\infty(R^N)$ ,  $\varphi \geq 0$ ,  $\xi \in R^N$

## Positivity of the turbulent viscous stress

$$\begin{aligned} & \int_0^T \int_{R^3} \varphi(\xi \otimes \xi) : d\mathfrak{R}_v \\ &= \lim_{n \rightarrow \infty} \int_0^T \int_{R^N} \left[ \frac{\mathbf{m}_n \otimes \mathbf{m}_n}{\varrho_n} - \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} \right] : (\xi \otimes \xi) \varphi \, dx dt \\ &= \lim_{n \rightarrow \infty} \int_0^T \int_{R^N} \left[ \frac{|\mathbf{m}_n \cdot \xi|^2}{\varrho_n} - \frac{|\mathbf{m} \cdot \xi|^2}{\varrho} \right] \varphi \, dx dt \geq 0 \end{aligned}$$

# Limit process

## Consistency

$$\int_0^T \int_{R^N} [\varrho_n \partial_t \varphi + \mathbf{m}_n \cdot \nabla_x \varphi] \, dx dt \rightarrow 0$$

for any  $\varphi \in C_c^\infty((0, T) \times R^N)$

$$\int_0^T \int_{R^N} \left[ \mathbf{m}_n \cdot \partial_t \varphi + \frac{\mathbf{m}_n \otimes \mathbf{m}_n}{\varrho_n} : \nabla_x \varphi + p(\varrho_n) \operatorname{div}_x \varphi \right] \, dx dt \rightarrow 0$$

for any  $\varphi \in C_c^\infty((0, T) \times R^N; R^N)$

## Reorganizing

$$\begin{aligned} & \mathbf{m}_n \cdot \partial_t \varphi + \frac{\mathbf{m}_n \otimes \mathbf{m}_n}{\varrho_n} : \nabla_x \varphi + p(\varrho_n) \operatorname{div}_x \varphi \\ &= \left( \frac{\mathbf{m}_n \otimes \mathbf{m}_n}{\varrho_n} - \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} \right) : \nabla_x \varphi + (p(\varrho_n) - p(\varrho)) \operatorname{div}_x \varphi \\ &+ \mathbf{m}_n \cdot \partial_t \varphi + \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} : \nabla_x \varphi + p(\varrho) \operatorname{div}_x \varphi \end{aligned}$$

# Limit system (dissipative solutions)

## Equations

$$\partial_t \mathbf{m} + \operatorname{div}_x \left( \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} \right) + \nabla_x p(\varrho) = -\operatorname{div}_x (\mathfrak{R}_v + \mathfrak{R}_p \mathbb{I})$$

in  $\mathcal{D}'((0, T) \times \mathbb{R}^N)$

## Turbulent defect measures

$$\mathfrak{R}_v \in L^\infty(0, T; \mathcal{M}^+(\mathbb{R}^N; \mathbb{R}_{\text{sym}}^{N \times N}))$$

$$\mathfrak{R}_p \in L^\infty(0, T; \mathcal{M}^+(\mathbb{R}^N))$$

## Energy

$$\overline{e(\varrho, \mathbf{m})} = e(\varrho, \mathbf{m}) + \frac{1}{2} \operatorname{trace}[\mathfrak{R}_v] + \frac{1}{\gamma - 1} \mathfrak{R}_p$$

# Solvability of the problem

## Basic equation

$$\mathbb{D} = \mathfrak{R}_v(t) + \mathfrak{R}_p(t)\mathbb{I} \in \mathcal{M}^+(R^N; R_{\text{sym}}^{N \times N}) \text{ for a.a. } t \in (0, T)$$

$$\operatorname{div}_x \mathbb{D} = 0 \text{ in } \mathcal{D}'(R^N)$$

## Weak formulation

$$\int_{R^N} \nabla_x \varphi : d\mathbb{D} = 0 \text{ for any } \varphi \in C_c^\infty(R^N)$$

## Larger class of test functions

### Weak formulation

$$\int_{R^N} \nabla_x \varphi : d\mathbb{D} = 0 \text{ for any } \varphi \in C_c^\infty(R^N)$$

for any  $\varphi \in C_c^\infty(R^N)$

### Cut-off

$$0 \leq \psi_R \leq 1, \quad \psi_R \in C_c^\infty(R^N)$$

$$\psi_R(Y) = 1 \text{ if } |Y| < r, \quad \psi_R(Y) = 0 \text{ if } |Y| > 2r, \quad |\nabla_x \psi_R| \leq \frac{2}{R}$$

### Globally Lipschitz test functions

$$\begin{aligned} 0 &= \int_{R^N} \nabla_x (\psi_R \varphi) : d\mathbb{D} = \int_{R^N} \psi_R \nabla_x \varphi : d\mathbb{D} + \int_{R^N} (\nabla_x \psi_R \otimes \varphi) : d\mathbb{D} \\ &= \int_{|x| < R} \nabla_x \varphi : d\mathbb{D} + \int_{|x| \geq R} [\psi_R \nabla_x \varphi + (\nabla_x \psi_R \otimes \varphi)] : d\mathbb{D} \end{aligned}$$

# Conclusion

## Extending the class of test functions

$$\int_{R^N} \nabla_x \varphi : d\mathbb{D} = 0$$

for any  $\varphi \in C^\infty(R^N)$ ,  $|\nabla_x \varphi| \leq c$

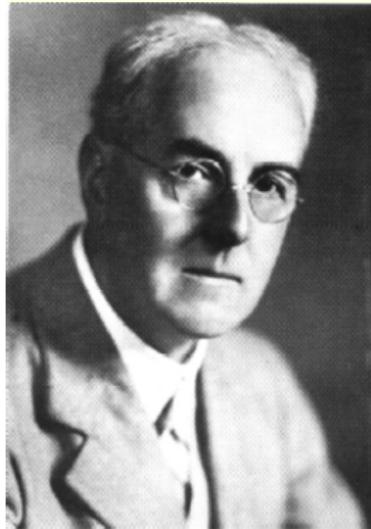
## Special test function

$$\varphi, \varphi_i = \sum_{j=1}^N \xi_i \xi_j x_j$$

## Conclusion

$$\int_{R^N} (\xi \otimes \xi) : d\mathbb{D} = 0 \Rightarrow (\xi \otimes \xi) : \mathbb{D} = 0 \Rightarrow \mathbb{D} = 0$$

## Solving ill-posed problems



L.F. Richardson [1881–1953]

Another advantage of a mathematical statement is that it is so definite that it might be definitely wrong. Some verbal statements have not this merit.

# ISENTROPIC EULER SYSTEM revisited

## Phase variables

- mass density .....  $\varrho = \varrho(t, x)$   
momentum .....  $\mathbf{m} = \mathbf{m}(t, x) \in \mathbb{R}^N$   
(total) energy .....  $E = E(t) \in \mathbb{R}$

## Mass conservation

$$\partial_t \varrho + \operatorname{div}_x \mathbf{m} = 0$$

## Balance of momentum

$$\partial_t \mathbf{m} + \operatorname{div}_x \left( \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} \right) + a \nabla_x \varrho^\gamma = 0$$

## Energy balance

$$\frac{d}{dt} E(t) \leq 0, \quad E = \int_{\mathbb{T}^N} \left[ \frac{1}{2} \frac{|\mathbf{m}|^2}{\varrho} + \frac{a}{\gamma - 1} \varrho^\gamma \right] dx$$

# Dissipative solutions

## Phase variables

- mass density .....  $\varrho = \varrho(t, x)$   
momentum .....  $\mathbf{m} = \mathbf{m}(t, x) \in R^N$   
“turbulent” defect measures .....  $\mathfrak{R}_e \in L^\infty(0, T; \mathcal{M}^+(\mathbb{T}^N)),$   
 $\mathfrak{R}_v \in L^\infty(0, T; \mathcal{M}^+(\mathbb{T}^N; R_{\text{sym}}^{N \times N}))$

## Euler system

$$\partial_t \varrho + \operatorname{div}_x \mathbf{m} = 0$$

$$\partial_t \mathbf{m} + \operatorname{div}_x \left( \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} \right) + \nabla_x p(\varrho) = -\operatorname{div}_x \mathfrak{R}_v - (\gamma - 1) \nabla_x \mathfrak{R}_e$$

$$\frac{d}{dt} E(t) \leq 0$$

$$E = \int_{\mathbb{T}^N} \left( \frac{1}{2} \frac{|\mathbf{m}|^2}{\varrho} + \frac{a}{\gamma - 1} \varrho^\gamma \right) dx + \int_{\mathbb{T}^N} \left( \frac{1}{2} \operatorname{tr}[\mathfrak{R}_v] + \mathfrak{R}_e \right)$$

# Dissipative solutions - existence

## Existence

Dissipative solutions can be constructed as limits of energy dissipating numerical schemes (Lax–Friedrichs and similar). They appear as zero viscosity limit for the Navier–Stokes system

## Dissipative–strong uniqueness

A dissipative solution coincides with a strong solution starting from the same initial data on the life–span of the latter (see also similar results on measure–valued solutions – Wiedemann et al.)

## Uniqueness - semigroup selection

For each initial data, one can select a global in time dissipative solution so that the resulting system forms a semigroup. The selected solutions maximize the energy dissipation

# Relative energy

## Relative energy

$$\begin{aligned}\mathcal{E}(\varrho, \mathbf{m} \mid r, \mathbf{U}) &\equiv \frac{1}{2} \varrho \left| \frac{\mathbf{m}}{\varrho} - \mathbf{U} \right|^2 + P(\varrho) - P'(r)(\varrho - r) - P(r) \\ &+ \frac{1}{2} \text{tr}[\mathfrak{R}_v] + \mathfrak{R}_e, \quad P(\varrho) = \frac{a}{\gamma - 1} \varrho^\gamma\end{aligned}$$

## Relative energy decomposition

$$\begin{aligned}& \int_{\mathbb{T}^N} \mathcal{E}(\varrho, \mathbf{m} \mid r, \mathbf{U}) \, dx \\&= \int_{\mathbb{T}^N} \left[ \frac{1}{2} \frac{|\mathbf{m}|^2}{\varrho} + P(\varrho) \right] \, dx + \int_{\mathbb{T}^N} \left[ \frac{1}{2} \text{tr}[\mathfrak{R}_v] + \mathfrak{R}_e \right] \\& \quad - \int_{\mathbb{T}^N} \mathbf{m} \cdot \mathbf{U} \, dx + \int_{\Omega} \varrho \left[ \frac{1}{2} |\mathbf{U}|^2 - P'(r) \right] \, dx \\& \quad + \int_{\mathbb{T}^N} [P'(r)r - P(r)] \, dx\end{aligned}$$

## Relative energy inequality

$$\begin{aligned} & \int_{\mathbb{T}^N} \mathcal{E}(\varrho, \mathbf{m} \mid r, \mathbf{U})(\tau, \cdot) \, dx - \int_{\mathbb{T}^N} \mathcal{E}(\varrho, \mathbf{m} \mid r, \mathbf{U})(0, \cdot) \, dx \\ & \leq - \int_0^\tau \int_{\mathbb{T}^N} \nabla_x \mathbf{U} : \varrho \left( \mathbf{U} - \frac{\mathbf{m}}{\varrho} \right) \otimes \left( \mathbf{U} - \frac{\mathbf{m}}{\varrho} \right) \, dx dt \\ & \quad - \int_0^\tau \int_{\mathbb{T}^N} \left( p(\varrho) - p'(r)(\varrho - r) - p(r) \right) \operatorname{div}_x \mathbf{U} \, dx dt \\ & + \int_0^\tau \int_{\mathbb{T}^N} \left[ \partial_t(r\mathbf{U}) + \operatorname{div}_x(r\mathbf{U} \otimes \mathbf{U}) + \nabla_x p(r) \right] \cdot \frac{1}{r} (\varrho \mathbf{U} - \mathbf{m}) \, dx dt \\ & + \int_0^\tau \int_{\mathbb{T}^N} \left[ \partial_t r + \operatorname{div}_x(r\mathbf{U}) \right] \left[ \left( 1 - \frac{\varrho}{r} \right) p'(r) + \frac{1}{r} \mathbf{U} \cdot (\mathbf{m} - \varrho \mathbf{U}) \right] \, dx dt \\ & - \int_0^\tau \left( \int_{\mathbb{T}^N} \nabla_x \mathbf{U} : d\mathfrak{R}^V(t) \right) dt - \int_0^\tau \left( \int_{\mathbb{T}^N} \operatorname{div}_x \mathbf{U} \, d\mathfrak{R}^P(t) \right) dt \end{aligned}$$

# Dispersive velocity weak solutions

## Besov spaces

$$v \in B_p^{\alpha, \infty}(Q) \Leftrightarrow \|v\|_{L^p(Q)} + \sup_{\xi} \frac{\|v(\cdot + \xi) - v(\cdot)\|_{L^p(Q \cap (Q-\xi))}}{|\xi|^\alpha} < \infty.$$

## Class $\mathcal{D}$

$$\varrho \in C([0, T]; L^1(\mathbb{T}^N)), \quad \mathbf{u} \in C([0, T]; L^1(\mathbb{T}^N; R^d))$$

$$0 < \underline{\varrho} \leq \varrho \leq \bar{\varrho}, \quad |\mathbf{u}| \leq \bar{\mathbf{u}} \text{ a.a. in } (0, T) \times \Omega$$

$$\varrho \in B_p^{\alpha, \infty}([\delta, T] \times \mathbb{T}^N), \quad \mathbf{u} \in B_p^{\alpha, \infty}([\delta, T] \times \mathbb{T}^N; R^d)$$

$$\text{for any } 0 < \delta < T, \quad \alpha > \frac{1}{2}, \quad p \geq \frac{4\gamma}{\gamma - 1}$$

$$\int_{\mathbb{T}^N} \left[ -\xi \cdot \mathbf{u}(\tau, \cdot) (\xi \cdot \nabla_x) \varphi + D(\tau) |\xi|^2 \varphi \right] dx \geq 0 \text{ for a.a. } \tau \in (0, T)$$

$$\text{for any } \xi \in R^d \text{ and any } \varphi \in C^1(\mathbb{T}^N), \quad \varphi \geq 0, \quad \text{where } D \in L^1(0, T)$$

## Weak (dissipative) – weak uniqueness

### Theorem

Let  $\varrho, \mathbf{m} = \varrho\mathbf{u}$  be a weak solution of the Euler system belonging to class  $\mathcal{D}$ , and let  $\tilde{\varrho}, \tilde{\mathbf{m}}$  be a dissipative solution of the same problem starting from the same initial data.

Then

$$\varrho = \tilde{\varrho}, \quad \mathbf{m} = \tilde{\mathbf{m}}.$$

# Commutator estimates

## Basic properties of Besov functions

$$[v]_\varepsilon = v * \vartheta_\varepsilon$$

$$\|[v]_\varepsilon - v\|_{L^p(Q)} \leq \varepsilon^\alpha \|v\|_{B_p^{\alpha,\infty}(Q)}, \quad \|\nabla_x [v]_\varepsilon\|_{L^p(Q)} \leq \varepsilon^{\alpha-1} \|v\|_{B_p^{\alpha,\infty}(Q)}$$

### Lemma

Let  $Q$  be a bounded domain in  $R^M$ . Suppose that  $\mathbb{V} : \tilde{Q} \rightarrow R^k$  belongs to the Besov space  $B_p^{\alpha,\infty}(Q, R^k)$ ,  $p \geq 2$ , where  $\tilde{Q} \subset R^M$  is another domain containing  $\overline{Q}$  in its interior. Let  $\eta^\varepsilon$  be a standard family of regularizing kernels,  $\text{supp}[\eta^\varepsilon] \subset \{|y| < \varepsilon\}$ . Let  $G : K \rightarrow R$  be a twice continuously differentiable function defined on an open set  $K \subset R^k$  containing the closure of the range of  $\mathbb{V}$ . Finally, set  $[v]_\varepsilon \equiv \eta^\varepsilon * v$ .

Then

$$\begin{aligned} & \|\nabla_y G([\mathbb{V}]_\varepsilon) - \nabla_y [G(\mathbb{V})]_\varepsilon\|_{L^{\frac{p}{2}}(Q; R^M)} \\ & \leq \varepsilon^{2\alpha-1} c(\|G\|_{C^2(K)}) \left(1 + \|\mathbb{V}\|_{B_p^{\alpha,\infty}(Q; R^k)}^2\right) \end{aligned}$$

for  $\nabla_y = (\partial_{y_1}, \dots, \partial_{y_M})$ .

# Semiflow selection

## Semiflow

$$U[t, \varrho_0, \mathbf{m}_0, E_0] \mapsto [\varrho(t), \mathbf{m}(t), E(t-)], \quad t > 0$$

## Semigroup property

$$U[t_1 + t_2, \varrho_0, \mathbf{m}_0, E_0] = U[t_2, U[t_1, \varrho_0, \mathbf{m}_0, E_0]] \text{ for any } 0 \leq t_1 \leq t_2$$

## Dissipative solution

$$\varrho \in C_{\text{weak,loc}}([0, \infty); L^\gamma(\mathbb{T}^N))$$

$$\mathbf{m} \in C_{\text{weak,loc}}([0, \infty); L^{\frac{2\gamma}{\gamma+1}}(\mathbb{T}^N; R^N))$$

$$E \in BV_{\text{loc}}([0, \infty); R), \text{ (non-increasing)}$$

## Initial data

$$\varrho(0, \cdot) = \varrho_0, \quad \mathbf{m}(0, \cdot) = \mathbf{m}_0, \quad E(0+) \leq E_0$$

## Basic properties

- **Stability of regular solutions.** Let  $\hat{\varrho}, \hat{\mathbf{m}}$  be a solution in the class  $\mathcal{D}$ ,

$$E_0 = \int_Q \left[ \frac{|\mathbf{m}_0|^2}{\varrho_0} + \frac{a}{\gamma - 1} \varrho_0^\gamma \right] dx,$$

defined on a maximal time interval  $[0, T_{\max})$ . Then

$$U[t, \varrho_0, \mathbf{m}_0, E_0] = [\hat{\varrho}, \hat{\mathbf{m}}, E_0](t) \text{ for all } t \in [0, T_{\max}).$$

- **Maximal dissipation.** Let  $\hat{\varrho}, \hat{\mathbf{m}}$  be a dissipative associated energy  $\hat{E}$  such that

$$\hat{E}(t) \leq E(t) \text{ for all } t \geq 0,$$

where  $E$  is the energy of the semiflow  $U[t, \varrho_0, \mathbf{m}_0, E_0]$ . Then

$$E(t) = \hat{E}(t) \text{ for all } t \geq 0.$$

- **Stability of stationary states.** Let  $\bar{\varrho} > 0$ ,  $\mathbf{m} \equiv 0$  a stationary solution. Then

$$\varrho(T, \cdot) = \bar{\varrho}, \quad \mathbf{m}(T, \cdot) = 0 \Rightarrow \varrho(t, \cdot) = \bar{\varrho}, \quad \mathbf{m}(t, \cdot) = 0 \text{ for all } t \geq T$$

# Abstract setting

## Phase space

$$X = W^{-\ell,2}(\mathbb{T}^N) \times W^{-\ell,2}(\mathbb{T}^N; R^N) \times R$$

## Data space

$$D = \left\{ [\varrho_0, \mathbf{m}_0, E_0] \in X \mid \varrho_0 \geq 0, \int_{\mathbb{T}^N} \left[ \frac{1}{2} \frac{|\mathbf{m}_0|^2}{\varrho_0} + \frac{a}{\gamma - 1} \varrho_0^\gamma \right] dx \leq E_0 \right\}.$$

## Trajectory space

$$\Omega = C_{\text{loc}}([0, \infty); W^{-\ell,2}(\mathbb{T}^N)) \times C_{\text{loc}}([0, \infty); W^{-\ell,2}(\mathbb{T}^N; R^N)) \times L^1_{\text{loc}}(0, \infty)$$

# Method by Krylov adapted by Cardona and Kapitanski

**Multi-valued solution mapping**

$$\mathcal{U} : [\varrho_0, \mathbf{m}_0, E_0] \mapsto [\varrho, \mathbf{m}, E] \in 2^\Omega$$

**Time shift**

$$S_T \circ \xi, \quad S_T \circ \xi(t) = \xi(T + t), \quad t \geq 0.$$

**Continuation**

$$\xi_1 \cup_T \xi_2(\tau) = \begin{cases} \xi_1(\tau) & \text{for } 0 \leq \tau \leq T, \\ \xi_2(\tau - T) & \text{for } \tau > T. \end{cases}$$

## Basic ansatz

- **(A1) Compactness:** For any  $[\varrho_0, \mathbf{m}_0, E_0] \in D$ , the set  $\mathcal{U}[\varrho_0, \mathbf{m}_0, E_0]$  is a non-empty compact subset of  $\Omega$
- **(A2)** The mapping

$$D \ni [\varrho_0, \mathbf{m}_0, E_0] \mapsto \mathcal{U}[\varrho_0, \mathbf{m}_0, E_0] \in 2^\Omega$$

is **Borel measurable**, where the range of  $\mathcal{U}$  is endowed with the Hausdorff metric on the subspace of compact sets in  $2^\Omega$

- **(A3) Shift invariance:** For any

$$[\varrho, \mathbf{m}, E] \in \mathcal{U}[\varrho_0, \mathbf{m}_0, E_0],$$

we have

$$S_T \circ [\varrho, \mathbf{m}, E] \in \mathcal{U}[\varrho(T), \mathbf{m}(t), E(T-)] \text{ for any } T > 0.$$

- **(A4) Continuation:** If  $T > 0$ , and

$$[\varrho^1, \mathbf{m}^1, E^1] \in \mathcal{U}[\varrho_0, \mathbf{m}_0, E_0], [\varrho^2, \mathbf{m}^2, E^2] \in \mathcal{U}[\varrho^1(T), \mathbf{m}^1(T), E^1(T-)],$$

then

$$[\varrho^1, \mathbf{m}^1, E^1] \cup_T [\varrho^2, \mathbf{m}^2, E^2] \in \mathcal{U}[\varrho_0, \mathbf{m}_0, E_0].$$

## Induction argument

### System of functionals

$$I_{\lambda,F}[\varrho, \mathbf{m}, E] = \int_0^\infty \exp(-\lambda t) F(\varrho, \mathbf{m}, E) \, dt, \quad \lambda > 0$$

where

$$F : X = W^{-\ell,2}(Q) \times W^{-\ell,2}(Q; R^N) \times R \rightarrow R$$

is a bounded and continuous functional

### Semiflow reduction

$$\begin{aligned} I_{\lambda,F} \circ \mathcal{U}[\varrho_0, \mathbf{m}_0, E_0] \\ = \left\{ [\varrho, \mathbf{m}, E] \in \mathcal{U}[\varrho_0, \mathbf{m}_0, E_0] \mid \right. \\ \left. I_{\lambda,F}[\varrho, \mathbf{m}, E] \leq I_{\lambda,F}[\tilde{\varrho}, \tilde{\mathbf{m}}, \tilde{E}] \text{ for all } [\tilde{\varrho}, \tilde{\mathbf{m}}, \tilde{E}] \in \mathcal{U}[\varrho_0, \mathbf{m}_0, E_0] \right\} \end{aligned}$$

### Induction argument

$$\mathcal{U} \text{ satisfies (A1) - (A4)} \Rightarrow I_{\lambda,F} \circ \mathcal{U} \text{ satisfies (A1) - (A4)}$$

# Testing functionals

## Abstract ansatz

A countable  $\{\mathbf{w}_m\}_{m=1}^{\infty}$  in  $L^2(\mathbb{T}^N; \mathbb{R}^N)$ , a countable set  $\{\lambda_k\}_{k=1}^{\infty}$  which is dense in  $(0, \infty)$ ,  $\beta : \mathbb{R} \rightarrow \mathbb{R}$  bounded strictly increasing function

## Functionals

$$I_{k,0,0}[\varrho, \mathbf{m}, E] = \int_0^{\infty} \exp(-\lambda_k t) \beta(E(t)) dt,$$

$$I_{k,0,m}[\varrho, \mathbf{m}, E] = \int_0^{\infty} \exp(-\lambda_k t) \beta \left( \int_{\mathbb{T}^N} \mathbf{m} \cdot \mathbf{w}_m dx \right) dt,$$

## Lerch theorem

$$\int_0^{\infty} \exp(-\lambda_k t) a(t) dt = \int_0^{\infty} \exp(-\lambda_k t) b(t) dt \text{ for all } \lambda_k$$
$$\Rightarrow$$

$$a(t) = b(t) \text{ for a.a. } t > 0$$