

On the Role of Reference Maps in hp -FEM

P. Šolín¹ T. Vejchodský²

¹ Department of Mathematical Sciences,
University of Texas at El Paso

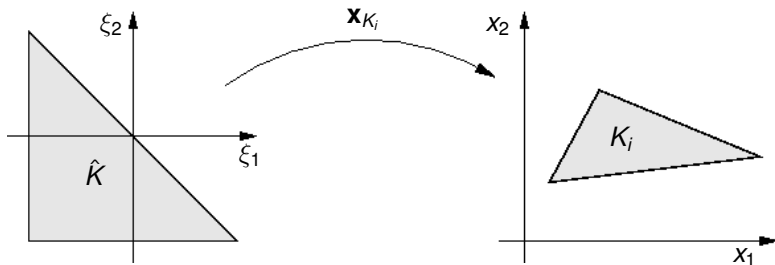
² Mathematical Institute,
Academy of Sciences of the Czech Republic, Prague

PANM 13, Prague, Czech Republic, May 28 - 31, 2006

Outline

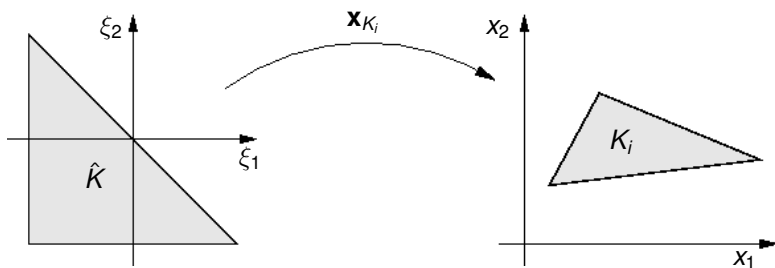
- 1 Introduction
- 2 Affine Concept
- 3 Problems
- 4 Non-Affine Concept
- 5 Conclusion

Affine concept: Reference domain & reference maps



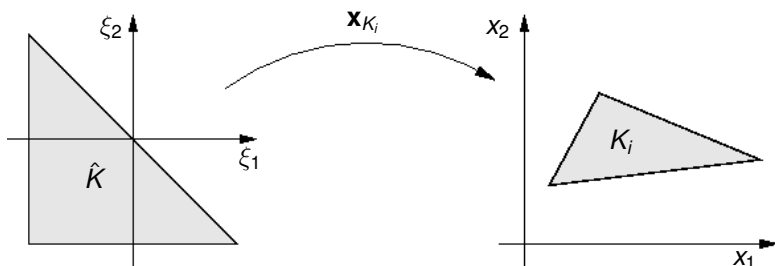
- Define shape functions on \hat{K}

Affine concept: Reference domain & reference maps



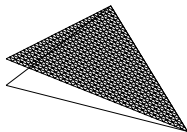
- Define shape functions on \hat{K}
- Define connectivity data

Affine concept: Reference domain & reference maps



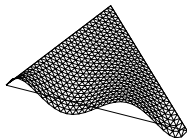
- Define shape functions on \hat{K}
- Define connectivity data
- Move weak formulation from K_i to \hat{K}

Hierarchical shape functions



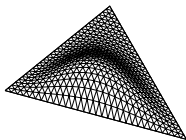
- Vertex functions

Hierarchical shape functions



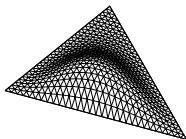
- Vertex functions
- Edge functions

Hierarchical shape functions



- Vertex functions
- Edge functions
- Bubble functions

Hierarchic shape functions



- Vertex functions
- Edge functions
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Number of shape functions

- Vertex: 3
- Edge: $(p - 1)$ on each edge
- Bubble: $(p - 1)(p - 2)/2$

Bubble functions

Monomial-based (Babuška et al, mid-1970s)

$$\varphi_{n_1, n_2}^b = \lambda_1 (\lambda_2)^{n_1} (\lambda_3)^{n_2}, \quad 1 \leq n_1, n_2, \quad n_1 + n_2 \leq p - 1$$

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Lobatto-based (Ainsworth, around 2000)

$$\varphi_{n_1, n_2, t}^b = \lambda_1 \lambda_2 \lambda_3 \phi_{n_1-1}(\lambda_3 - \lambda_2) \phi_{n_2-1}(\lambda_1 - \lambda_3)$$

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Jacobi-based (Beuchler, 2005)

L-shape domain problem

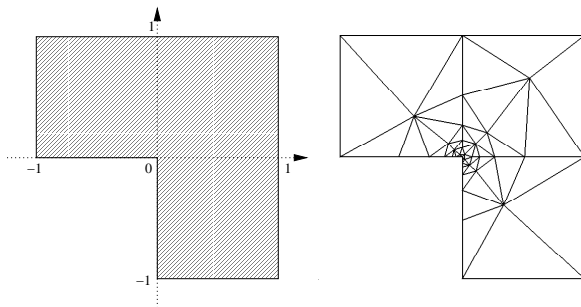


Figure: The L-shape domain and its partition.

L-shape domain problem

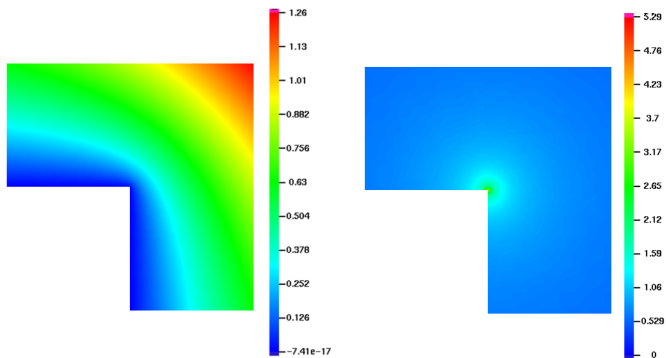
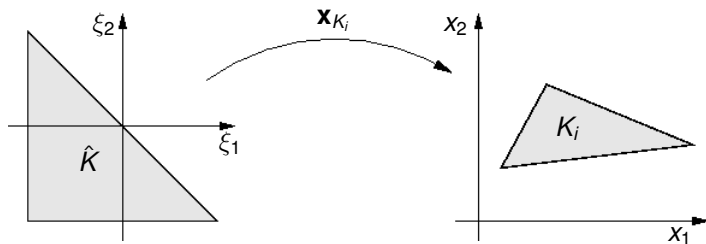


Figure: Exact solution u (left) and the norm of its gradient (right).

Problem #1



Several ways to map the central vertex of \hat{K} :

- vertex w. *lowest index* (“random”) in K_i
- vertex w. *minimum angle* in K_i
- vertex w. *medium angle* of K_i
- vertex w. *maximum angle* of K_i

Effect on Lobatto shape functions

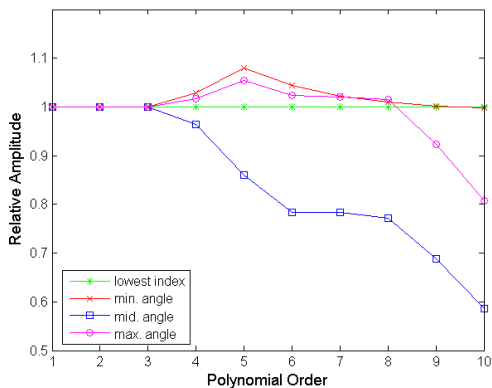


Figure: Condition number of stiffness matrix, $p = 1, 2, \dots, 10$.

Effect of Jacobi shape functions

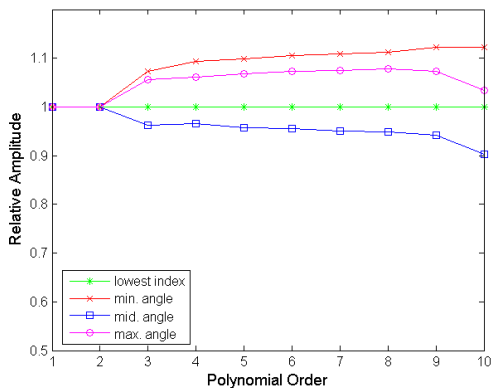


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Effect on generalized eigenfunctions

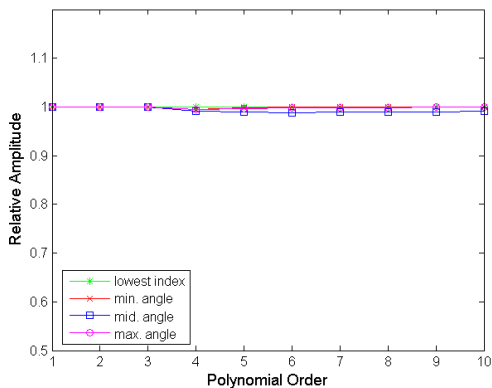


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Conditioning comparison

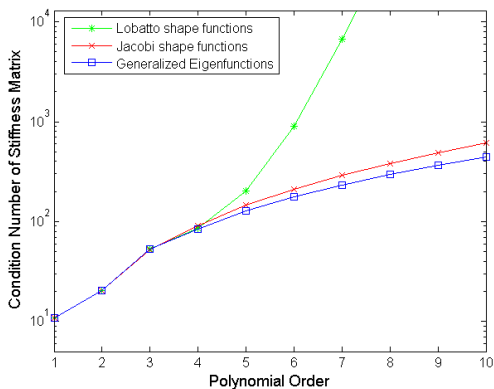


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Generalized eigenfunctions on \hat{K}

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$$\int_{\hat{K}} \psi'_m(x) v'(x) dx = \lambda_m \int_{\hat{K}} \psi_m(x) v(x) dx \quad \text{for all } v \in W$$

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$$\psi_k = \sum_{j=1}^{(p-1)(p-2)/2} y_{jk} g_j$$

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- Solution: LAPACK, Matlab

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- Transformation to reference domain:

$$\int_{K_i} \nabla u \cdot \nabla v \, d\mathbf{x} = \int_{\hat{K}} |J_{K_i}| \nabla \hat{u} \cdot \underbrace{\left(\frac{D\mathbf{x}_{K_i}}{D\xi} \right)^{-1} \left(\frac{D\mathbf{x}_{K_i}}{D\xi} \right)^{-T}}_{\text{symmetric positive definite}} \nabla \hat{v} \, d\xi$$

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- Energetic inner product cannot be fully exploited!

Abandon the affine concept?

- Orthogonalize bubbles on each K_i under

$$(u, v)_{H_0^1(K_i)} = \int_{\hat{K}} |J_{K_i}| \nabla \hat{u} \cdot \left(\frac{D\mathbf{x}_{K_i}}{D\xi} \right)^{-1} \left(\frac{D\mathbf{x}_{K_i}}{D\xi} \right)^{-T} \nabla \hat{v} \, d\xi$$

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Standard basis functions

VV	VE	VB
VE	EE	EB
VB	EB	BB

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Orthogonal basis functions

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0	0	I

- Excellent parallel preconditioner
- Note: **ON basis on K_i not unique**

How to choose ON bubbles on elements?

Generalized eigenfunctions in elements

- **BB block diagonal in both stiffness and mass matrices**

Mass matrix

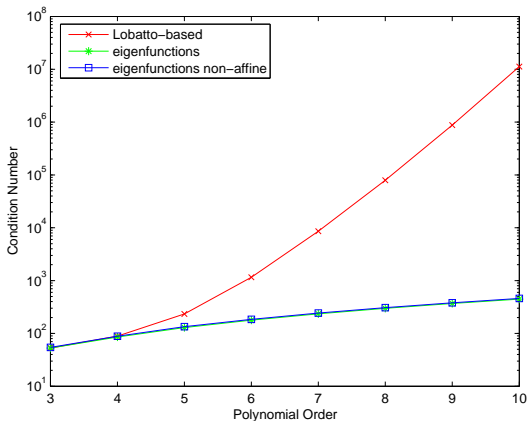
$$\begin{pmatrix} \text{VV} & \text{VE} & \text{VB} \\ \text{VE} & \text{EE} & \text{EB} \\ \text{VB} & \text{EB} & \text{D} \end{pmatrix}$$

- Needs further study

Stiffness matrix

$$\begin{pmatrix} \text{VV} & \text{VE} & \text{VB} \\ \text{VE} & \text{EE} & \text{BE} \\ \text{VB} & \text{EB} & \text{I} \end{pmatrix}$$

Affine vs. Non-Affine (Laplace operator)



Curl-Curl operator

■ Maxwell's equations

$$\begin{aligned} \nabla \times (\mu_r^{-1} \nabla \times \mathbf{E}) - \kappa^2 \epsilon_r \mathbf{E} &= \mathbf{F} && \text{in } \Omega, \\ \mathbf{E} \cdot \boldsymbol{\tau} &= 0 && \text{on } \Gamma_P, \\ \mu_r^{-1} \nabla \times \mathbf{E} - i\kappa \lambda \mathbf{E} \cdot \boldsymbol{\tau} &= \mathbf{g} \cdot \boldsymbol{\tau} && \text{on } \Gamma_I. \end{aligned}$$

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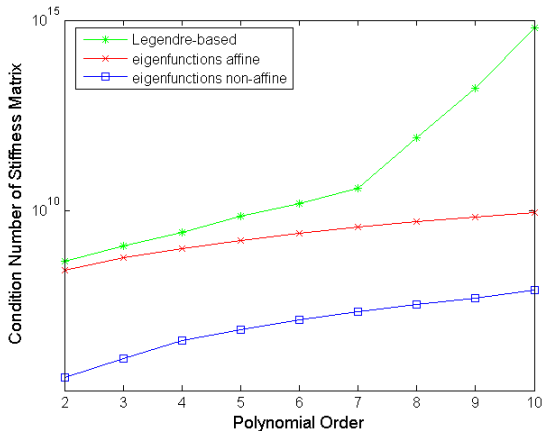
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- Indefinite problem \rightarrow no inner product \rightarrow no orthogonalization
- Use generalized eigenfunctions:
 - outstanding conditioning properties
 - minimal dependence on reference maps

Affine vs. Non-Affine (Maxwell's equations)



Conclusion and Outlook

- Choice of ref. maps influences discrete problem
 - ⇒ use generalized eigenfunctions
- Ref. maps incompatible with energetic inner product
 - ⇒ leave affine concept
 - ⇒ may not be needed for elliptic problems
 - ⇒ more serious for Maxwell's equations

Outlook

- Stokes, linear convection-diffusion, Navier-Stokes, etc.
- goal: monolithic hp -FEM for coupled problems

The End

Thank You!