

Computational homogenization for multiscale modeling of heterogeneous materials

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PANM 2008, Dolní Maxov, 4th June 2008



Homogenization of problems with scale-dependent parameters

scale dependent material parameters (s.d.m.p.)

- ▶ existence of underlying structures (micro-level)
- ▶ upscaling by " $\varepsilon \rightarrow 0$ " ... meso \rightarrow macro

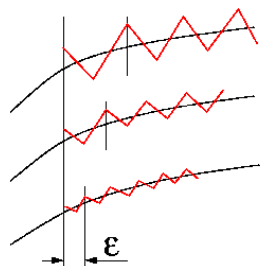
scale:	micro	meso	macro
description:	s.d.m.p.	heterogeneous description, of <i>micromodel</i>	homogenized model

- ▶ fluid saturated *double-porous* media (f.s.dp.m.) – s.d. permeability
 \Rightarrow **solids with microflow**
- ▶ phononic crystals – s.d. elasticity
 \Rightarrow **materials with negative mass** (gaps in wave propagation)

layered media – scale dependent thickness

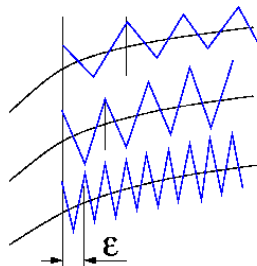
- ▶ perfusion in structured transversally periodic f.s.dp.m.
- ▶ acoustic transmission on perforated interfaces

Coefficient scaling – interactions & fluctuations



local fluctuations

$$|\text{grad}| \leq C$$



macro-micro interaction

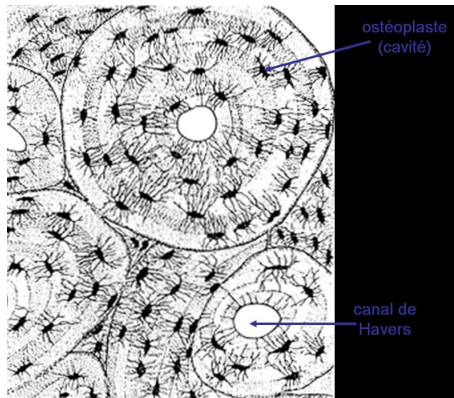
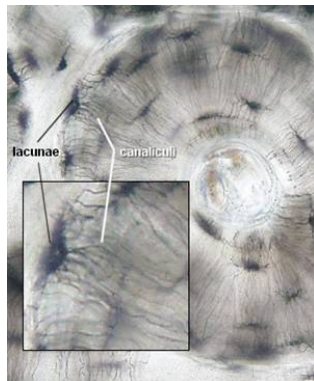
$$|\text{grad}| \leq \frac{C}{\epsilon}$$

... strong heterogeneity

Cortical bone — double porous medium?

3 scales — distinguishable porosities

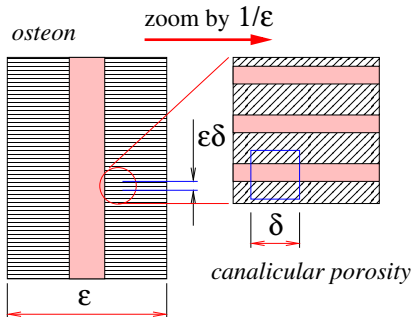
- ▶ Macro-scale: a piece of compact bone (10 mm)
- ▶ Meso-scale – level 1 – Haversian and Volkmann channels ($100\ \mu\text{m}$)
- ▶ Micro-scale – level 2 – canaliculi, lacunae in “solid matrix” ($1\ \mu\text{m}$)



3 scales – Dual porosity – a model of compact bone

Meso-scale \rightarrow micro-scale

scale	zoom to:	char. length	
macro-scale	piece of bone	L	$\approx 10 \text{ mm}$
meso-scale	osteon – Haversian porosity	εL	$\approx 100 \text{ }\mu\text{m}$
micro-scale	canalicular porosity	$\varepsilon \delta L$	$\approx 1 \text{ }\mu\text{m}$



\Rightarrow "absolute scale" of canaliculi:

$$\varepsilon\delta \approx \varepsilon^2$$

\Rightarrow one may deduce:

$$\varepsilon \approx \delta \approx 1/100$$

Seepage velocity in the matrix:

$$\begin{aligned} \mathbf{w}^{\varepsilon,\delta} &= \phi \bar{\mathbf{v}}^{\varepsilon,\delta} \\ &= -\delta^2 \mathbf{K}_v^0 \nabla p^\varepsilon, \end{aligned}$$

$$\delta = \delta(\varepsilon) \approx \varepsilon \quad \dots \text{proportional}$$

Biot model of porous fluid saturated solid

$$\begin{aligned}
 -\partial_j D_{ijkl} e_{kl}(\mathbf{u}^s) + \partial_j(\alpha_{ij} p) &= f_i && \text{elasticity} && D_{ijkl} \\
 \alpha_{ij} e_{ij}\left(\frac{d}{dt} \mathbf{u}^s\right) + \operatorname{div} \mathbf{w} + \frac{1}{\mu} \frac{d}{dt} p &= 0 && \text{permeability} && (K_{ij}) = \mathbf{K} \\
 \mathbf{K} \nabla p + \mathbf{w} &= 0, && \text{Biot coefficients} && \alpha_{ij} \\
 &&& \text{Biot modulus} && \frac{1}{\mu} = \frac{1}{\mathcal{N}} + \frac{\phi_0}{k_f}
 \end{aligned}$$

Boundary value problem – two field formulation

Find \mathbf{u}^s and p such that

$$\begin{aligned}
 -\partial_j D_{ijkl} e_{kl}(\mathbf{u}^s) + \partial_j(\alpha_{ij} p) &= f_i && \text{in } \Omega, \\
 \alpha_{ij} e_{ij}\left(\frac{d}{dt} \mathbf{u}^s\right) - \partial_i K_{ij} \partial_j p + \frac{1}{\mu} \frac{d}{dt} p &= 0 && \text{in } \Omega,
 \end{aligned}$$

and

$$\begin{aligned}
 \mathbf{u}^s(t, \cdot) &= \bar{\mathbf{u}}^s(t, \cdot) && \text{on } \partial\Omega, \text{ for } t \in]0, T[, \\
 \mathbf{w}(t, \cdot) &= 0 && \text{on } \partial\Omega, \text{ for } t \in]0, T[, \\
 \mathbf{u}^s(0, \cdot) &= 0 && \text{in } \Omega, \\
 p(0, \cdot) &= 0 && \text{in } \Omega.
 \end{aligned}$$

Geometry – domain decomposition

$$\Omega = \Omega_m \cup \Omega_c \cup \Gamma_{mc}, \quad \text{with} \quad \Omega_m \cap \Omega_c = \emptyset.$$

Representative periodic cell

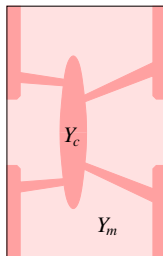
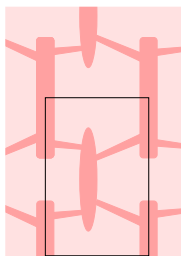
$$Y = \prod_{i=1}^3]0, \bar{y}_i[$$

$$Y_m = Y \setminus \bar{Y}_c,$$

$$\partial_m Y_c = \partial_c Y_m = \bar{Y}_c \cap \bar{Y}_m,$$

$$\partial_c Y_c = \bar{Y}_c \cap \partial Y,$$

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Periodic unfolding — macro-micro decomposition

$$x = \varepsilon \left[\frac{x}{\varepsilon} \right]_Y + \varepsilon \left\{ \frac{x}{\varepsilon} \right\}_Y \quad y = \left\{ \frac{x}{\varepsilon} \right\}_Y \in Y.$$

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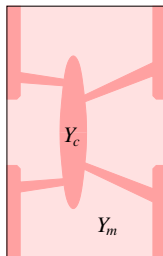
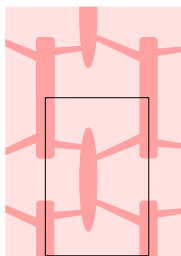
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Biot model with oscillating coefficients – dual porosity

Material coefficients

$$D_{ijkl}^\varepsilon(\mathbf{x}) = D_{ijkl}^c\left(\left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right)\chi_c^\varepsilon(\mathbf{x}) + D_{ijkl}^m\left(\left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right)\chi_m^\varepsilon(\mathbf{x}),$$

$$\alpha_{ij}^\varepsilon(\mathbf{x}) = \alpha_{ij}^c\left(\left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right)\chi_c^\varepsilon(\mathbf{x}) + \alpha_{ij}^m\left(\left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right)\chi_m^\varepsilon(\mathbf{x}),$$

$$K_{ij}^\varepsilon(\mathbf{x}) = K_{ij}^c\left(\left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right)\chi_c^\varepsilon(\mathbf{x}) + \varepsilon^2 K_{ij}^m\left(\left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right)\chi_m^\varepsilon(\mathbf{x}),$$

$$\mu^\varepsilon(\mathbf{x}) = \mu^c\left(\left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right)\chi_c^\varepsilon(\mathbf{x}) + \mu^m\left(\left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right)\chi_m^\varepsilon(\mathbf{x}).$$

Weak formulation — time-integrated pressure P

$$\int_{\Omega} D_{ijkl}^\varepsilon e_{kl}(\mathbf{u}^\varepsilon) e_{ij}(\mathbf{v}) - \int_{\Omega} \frac{dP^\varepsilon}{dt} \alpha_{ij}^\varepsilon e_{ij}(\mathbf{v}) = \int_{\Omega} \mathbf{f} \cdot \mathbf{v}, \quad \forall \mathbf{v} \in V_0,$$
$$\int_{\Omega} q \alpha_{ij}^\varepsilon e_{ij}(\mathbf{u}^\varepsilon) + \int_{\Omega} K_{ij}^\varepsilon \partial_j P^\varepsilon \partial_i q + \int_{\Omega} \frac{1}{\mu^\varepsilon} \frac{dP^\varepsilon}{dt} q = 0, \quad \forall q \in H^1(\Omega),$$

where $P^\varepsilon(t, \mathbf{x}) = \int_0^t p^\varepsilon(t, \mathbf{x}) dt,$

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Homogenization $\varepsilon \rightarrow 0$, limit model

Periodic unfolding (*Cioranescu, Dambrani, Griso . . . 2002*)

oscillating function: $f^\varepsilon(x) \rightarrow \mathcal{T}_\varepsilon(f^\varepsilon)(x, y)$

Basic steps of the periodic unfolding method

1. weak formulation (WF)
2. a priori estimation of unknown functions
3. limit functions (gradients)
4. definition of test functions
5. unfolding the integrals in WF, passing to the limit
6. scale decoupling — microproblems, corrector basis functions, global functions
7. solving the microproblems
8. evaluation of homogenized coefficients (HC)
9. solving the macroscopic problem — defined in terms of HC
10. reconstruction for $\varepsilon > 0$ — given by formula

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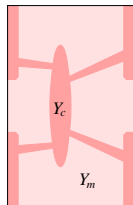
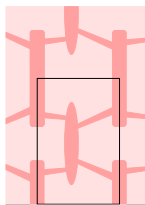
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Limit model — uncoupled scales

Phys. field	Function	Scale	Domain
displac.	$\mathbf{u}(x)$	Macro	Ω
displac.	$\mathbf{u}^1(x, y)$	micro	$\Omega \times Y$
press.	$P(x)$	Macro	Ω
press.	$P^1(x, y)$	micro	$\Omega \times Y_c$
press.	$\widehat{P}^0(x, y)$	micro	$\Omega \times Y_m$



Global equations:

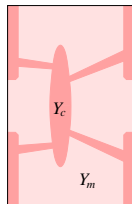
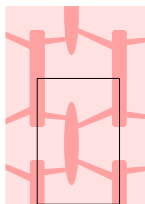
to be satisfied for all $\mathbf{w} \in V_0 = \mathbf{H}_0^1(\Omega)$ and $q^0 \in H^1(\Omega)$

$$\int_{\Omega \times Y} D_{ijkl} [e_{kl}^x(\mathbf{u}) + e_{kl}^y(\mathbf{u}^1)] e_{ij}^x(\mathbf{v}^0) - \int_{\Omega \times Y} \alpha_{ij} e_{ij}^x(\mathbf{v}^0) \left(\frac{dP}{dt} + \chi_m \frac{d\widehat{P}^0}{dt} \right) = \int_{\Omega} \mathbf{f} \cdot \mathbf{v}^0,$$

$$\int_{\Omega \times Y_c} K_{ij}^c [\partial_j^x P + \partial_j^y P^1] \partial_i^x q^0 + \int_{\Omega \times Y} \alpha_{ij} [e_{ij}^x(\mathbf{u}) + e_{ij}^y(\mathbf{u}^1)] q^0 + \int_{\Omega \times Y_c} \frac{1}{\mu^c} \frac{dP}{dt} q^0 + \int_{\Omega \times Y_m} \frac{1}{\mu^m} \left(\frac{dP}{dt} + \frac{d\widehat{P}^0}{dt} \right) q^0 = 0,$$

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$$\begin{aligned} & \int_{\Omega \times Y_c} K_{ij}^c [\partial_j^x P + \partial_j^y P^1] \partial_i^x q^0 + \int_{\Omega \times Y} \alpha_{ij} [e_{ij}^x(\mathbf{u}) + e_{ij}^y(\mathbf{u}^1)] q^0 \\ & + \int_{\Omega \times Y_c} \frac{1}{\mu^c} \frac{dP}{dt} q^0 + \int_{\Omega \times Y_m} \frac{1}{\mu^m} \left(\frac{dP}{dt} + \frac{d\widehat{P}^0}{dt} \right) q^0 = 0, \end{aligned}$$

Limit model — uncoupled scales

Phys. field	Function	Scale	Domain	space
displac.	$\mathbf{u}(x)$	Macro	Ω	$\mathbf{L}^2(0, T; \mathbf{H}_0^1(\Omega))$
displac.	$\mathbf{u}^1(x, y)$	micro	$\Omega \times Y$	$\mathbf{L}^2(0, T; \mathbf{L}^2(\Omega; \mathbf{H}_\#^1(Y)))$
press.	$P(x)$	Macro	Ω	$L^\infty(0, T; L^2(\Omega))$
press.	$P^1(x, y)$	micro	$\Omega \times Y_c$	$L^\infty(0, T; L^2(\Omega; H_\#^1(Y_c)))$
press.	$\widehat{P}^0(x, y)$	micro	$\Omega \times Y_m$	$L^\infty(0, T; L^2(\Omega; H^1(Y_m)))$

Local equation — diffusion in the channels

$$\int_{Y_c} K_{ij}^c \partial_j^y P^1 \partial_i^y \psi = -\partial_j^x P(x) \int_{Y_c} K_{ij}^c \partial_j^y \psi \quad \forall \psi \in H_\#^1(Y_c)$$

Local equation — diffusion-deformation in the marix

$$\int_Y D_{ijkl} [e_{kl}^x(\mathbf{u}) + e_{kl}^y(\mathbf{u}^1)] e_{ij}^y(\mathbf{w}) - \int_Y \alpha_{ij} e_{ij}^y(\mathbf{w}) \frac{dP}{dt} - \int_{Y_m} \alpha_{ij}^m e_{ij}^y(\mathbf{w}) \frac{d\widehat{P}^0}{dt} = 0,$$

$$\int_{Y_m} K_{ij}^m \partial_j^y \widehat{P}^0 \partial_i^y \phi + \int_{Y_m} \alpha_{ij}^m [e_{ij}^x(\mathbf{u}) + e_{ij}^y(\mathbf{u}^1)] \phi + \int_{Y_m} \frac{1}{\mu^m} \left(\frac{dP}{dt} + \frac{d\widehat{P}^0}{dt} \right) \phi = 0,$$

for all $\mathbf{w} \in \mathbf{H}_\#^1(Y)$ and $\phi \in H_{\#0}^1(Y_m)$.

Scale decoupling — Time dependent problem

Local fields $\mathbf{u}^1(t, x, y)$, $\widehat{P}^0(t, x, y)$ — convolution form

Introduce split using corrector basis functions:

$$\mathbf{u}^1(t, x, y) = \int_0^t \boldsymbol{\omega}^{rs}(t - \tau) \frac{d}{d\tau} e_{rs}^x(\mathbf{u}(\tau)) d\tau + \int_0^t \boldsymbol{\omega}^P(t - \tau) \frac{d}{d\tau} P(\tau) d\tau ,$$
$$\widehat{P}^0(t, x, y) = \int_0^t \pi^{rs}(t - \tau, y) \frac{d}{d\tau} e_{rs}^x(\mathbf{u}(\tau)) d\tau + \int_0^t \pi^P(t - \tau, y) \frac{d}{d\tau} P(\tau) d\tau .$$

Local problems – notation

$$a_Y(\mathbf{u}, \mathbf{v}) = \int_Y D_{ijkl}(y) e_{kl}^y(\mathbf{u}) e_{ij}^y(\mathbf{v}) ,$$
$$b_{Y_m}(\varphi, \mathbf{v}) = \int_{Y_m} \varphi \alpha_{ij}^m(y) e_{ij}^y(\mathbf{v}) ,$$
$$c_{Y_m}(\varphi, \psi) = \int_{Y_m} K_{ij}^m(y) \partial_j^y \varphi \partial_i^y \psi ,$$
$$d_{Y_m}(\varphi, \psi) = \int_{Y_m} (\mu^m)^{-1} \psi \varphi .$$

Microscopic problems — correctors w.r.t. $e_{rs}^x(\mathbf{u})$

The correctors $(\boldsymbol{\omega}^{rs}, \pi^{rs})$ can be expressed in the form

$$\begin{aligned}\boldsymbol{\omega}^{rs}(t) &= [\tilde{\boldsymbol{\omega}}^{rs}(t) + \bar{\boldsymbol{\omega}}^{rs}] H_+(t), \\ \pi^{rs}(t) &= [\tilde{\pi}^{rs}(t) + \bar{\pi}^{rs}] H_+(t).\end{aligned}$$

Steady problem correctors – compute $(\bar{\boldsymbol{\omega}}^{rs}, \bar{\pi}^{rs})$

$$\begin{aligned}a_Y(\bar{\boldsymbol{\omega}}^{rs}, \mathbf{v}) &= a_Y(\boldsymbol{\Pi}^{rs}, \mathbf{v}) \quad \forall \mathbf{v} \in \mathbf{H}_{\#}^1(Y), \\ c_{Y_m}(\bar{\pi}^{rs}, q) &= -b_{Y_m}(q, \bar{\boldsymbol{\omega}}^{rs} + \boldsymbol{\Pi}^{rs}) \quad \forall q \in H_{\#0}^1(Y_m),\end{aligned}$$

where $\boldsymbol{\Pi}^{rs} = (\Pi_i^{rs})$ is defined as $\Pi_i^{rs} = y_s \delta_{ir}$.

Evolutionary problem correctors – compute $(\tilde{\boldsymbol{\omega}}^{rs}, \tilde{\pi}^{rs})$

$$\begin{aligned}a_Y(\tilde{\boldsymbol{\omega}}^{rs}, \mathbf{v}) - b_{Y_m}\left(\frac{d}{dt} \tilde{\pi}^{rs}, \mathbf{v}\right) &= 0 \quad \forall \mathbf{v} \in \mathbf{H}_{\#}^1(Y), \\ b_{Y_m}(q, \tilde{\boldsymbol{\omega}}^{rs}) + c_{Y_m}(\tilde{\pi}^{rs}, q) + d_{Y_m}\left(\frac{d}{dt} \tilde{\pi}^{rs}, q\right) &= 0 \quad \forall q \in H_{\#0}^1(Y_m),\end{aligned}$$

where $\tilde{\pi}^{rs}(0) = -\bar{\pi}^{rs}$.

Microscopic problems — correctors w.r.t. P

The correctors (ω^{rs}, π^{rs}) can be expressed in the form

$$\begin{aligned}\omega^P(t) &= \tilde{\omega}^P(t) H_+(t) + \omega^{*,P} \delta_+(t), \\ \pi^P(t) &= \tilde{\pi}^P(t) H_+(t),\end{aligned}$$

Steady problem correctors – compute $(\omega^{*,P}, \tilde{\pi}^P(0))$

$$\begin{aligned}a_Y(\omega^{*,P}, \mathbf{v}) - b_{Y_m}(\tilde{\pi}^P(0_+), \mathbf{v}) &= b_Y(1, \mathbf{v}) \quad \forall \mathbf{v} \in \mathbf{H}_{\#}^1(Y), \\ b_{Y_m}(q, \omega^{*,P}) + d_{Y_m}(\tilde{\pi}^P(0_+), q) &= -d_{Y_m}(1, q) \quad \forall q \in H_{\#0}^1(Y_m).\end{aligned}$$

Evolutionary problem correctors – compute $(\tilde{\omega}^P, \tilde{\pi}^P)$

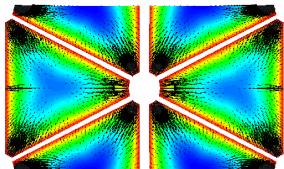
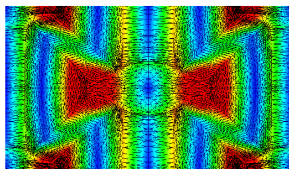
$$\begin{aligned}a_Y(\tilde{\omega}^P, \mathbf{v}) - b_{Y_m}\left(\frac{d}{dt}\tilde{\pi}^P, \mathbf{v}\right) &= 0 \quad \forall \mathbf{v} \in \mathbf{H}_{\#}^1(Y), \\ b_{Y_m}(q, \omega^{*,P}) + c_{Y_m}(\tilde{\pi}^P, q) + d_{Y_m}\left(\frac{d}{dt}\tilde{\pi}^P, q\right) &= 0 \quad \forall q \in H_{\#0}^1(Y_m).\end{aligned}$$

where $\tilde{\pi}^P(0)$ is given by the “steady problem”.

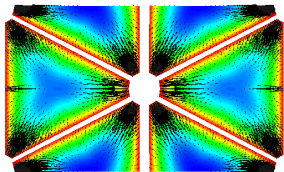
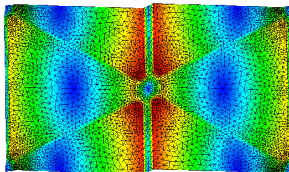
corrector shape functions

- ▶ steady correctors:

- ▶ left: $\bar{\omega}^{11}$, right: $\bar{p}^{11} \in [-0.673, 0]$ + perfusion velocities



- ▶ left: $\bar{\omega}^{21}$ (scaled 0.1x), right: $\bar{p}^{21} \in [-0.542, 0]$ + perfusion velocities



Homogenized coefficients

Defined in terms of the corrector basis functions

- ▶ the homogenized **elastic tensor**

$$\mathcal{E}_{ijkl} = a_Y \left(\mathbf{\Pi}^{kl} + \bar{\omega}^{kl}, \mathbf{\Pi}^{ij} + \bar{\omega}^{ij} \right),$$

- ▶ the homogenized **viscosity tensor** of the fading memory

$$\mathcal{H}_{ijkl}(t) = c_{Y_m} \left(\frac{d}{dt} \tilde{\pi}^{kl}, \tilde{\pi}^{ij} \right).$$

... *effects of microcirculation in the matrix*

- ▶ **Instantaneous** homogenized Biot coefficients

$$\mathcal{B}_{ij} = \int_Y \alpha_{ij} + b_Y (1, \bar{\omega}^{ij}),$$

- ▶ **transition** (“fading memory”) homogenized Biot coefficients

$$\mathcal{F}_{ij}(t) = b_{Y_m} (\tilde{\pi}^P - \tilde{\pi}^P(0), \tilde{\omega}^{ij}) + c_{Y_m} (\tilde{\pi}^{ij}, \tilde{\pi}^P).$$

- ▶ homogenized *reciprocal Biot modulus* – instantaneous response

$$\mathcal{M} = \int_Y \frac{1}{\mu} + d_{Y_m}(\tilde{\pi}^P(0_+), \mathbf{1}) + b_Y(\mathbf{1}, \boldsymbol{\omega}^{*,P}) ,$$

- ▶ fading memory part of the homogenized *reciprocal Biot modulus*

$$\mathcal{G}(t) = d_{Y_m} \left(\frac{d}{dt} \tilde{\pi}^P, \mathbf{1} \right) + b_Y(\mathbf{1}, \tilde{\boldsymbol{\omega}}^P) .$$

Effective permeability \mathcal{C}_{ij} — autonomous problem

correctors $\eta \in H_{\#}^1(Y_c)$ in channels

$$\mathcal{C}_{kl} = \int_{Y_c} K_{ij}^c \partial_j^y (\eta^l + y_l) \partial_i^y (\eta^k + y_k) ,$$

where $0 = \int_{Y_c} K_{ij}^c \partial_j^y (\eta^k + y_k) \partial_i^y \psi \quad \forall \psi \in H_{\#}^1(Y)$

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Macroscopic model — upscaled double porous medium

For a.a. $t \in]0, T[$ find $\mathbf{u} \in V$ and $P \in Q$ (with $P(0) = 0$) such that

$$\int_{\Omega} \mathcal{E}_{ijkl} e_{kl}(\mathbf{u}) e_{ij}(\mathbf{v}) + \int_{\Omega} \int_0^t \mathcal{H}_{ijkl}(t-\tau) e_{kl}\left(\frac{d}{dt} \mathbf{u}(\tau)\right) d\tau e_{ij}(\mathbf{v}) - \int_{\Omega} (\mathcal{B}_{ij} + \mathcal{F}_{ij}(0_+)) \frac{d}{dt} P e_{ij}(\mathbf{v}) - \int_{\Omega} \int_0^t \mathcal{F}_{ij}(t-\tau) \frac{d}{d\tau} P(\tau) d\tau e_{ij}(\mathbf{v}) = \int_{\Omega} \mathbf{f} \cdot \mathbf{v},$$

$$\int_{\Omega} \mathcal{B}_{ij} e_{ij}(\mathbf{u}) q + \int_{\Omega} \int_0^t \mathcal{F}_{ij}(t-\tau) e_{ij}\left(\frac{d}{d\tau} \mathbf{u}(\tau)\right) d\tau q + \int_{\Omega} \mathcal{C}_{ij} \partial_j P \partial_i q + \int_{\Omega} \mathcal{M} \frac{d}{dt} P q + \int_{\Omega} \int_0^t \mathcal{G}(t-\tau) \frac{d}{d\tau} P(\tau) d\tau q = 0,$$

for all $\mathbf{v} \in V_0$ and $q \in Q_0$.

Postprocessing the microflow in double-porous structure

Macro-level — overall flow

Due to interconnected network of Haversian and Volkmann canals

$$\mathbf{w}^M = -\mathbf{K}^M \nabla p^M \quad \dots \quad \text{from the homogenized macro-model}$$

Micro-level 1 — Haversian porosity flow

$$\begin{aligned} \mathbf{w}^{\mu 1} &= -\mathbf{K}^c (\nabla p)^{\mu 1, corr} \\ &= -\mathbf{K}^c (\nabla_x p^M(x) + \nabla_y p^1) \end{aligned}$$

Micro-level 2 — canalicular porosity flow

$$\mathbf{w}^{\mu 2, ref} = -\mathbf{K}^m \nabla_y \hat{p} \quad \dots \quad \hat{p} = \hat{p}(e_{rs}^x(\mathbf{u}^M), p^M) \text{ by the convolution}$$

Let ε_0 be the scale: $\varepsilon_0 = \mu 1 / M = \mu 2 / \mu 1 \approx 1 / 100$

an ϕ be the canalicular porosity (vol. frac.), then

$$\mathbf{w}^{\mu 2, real} = \varepsilon_0^2 \mathbf{w}^{\mu 2, ref}$$

$$\bar{\mathbf{v}}^{\mu 2, real} = \phi^{-1} \mathbf{w}^{\mu 2, real} \quad \dots \text{mean velocity of the Poiseuille flow}$$

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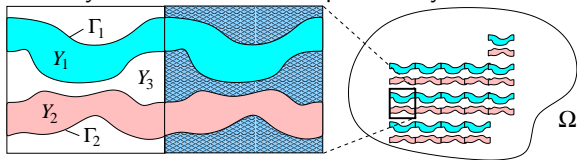
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Perfusion in deforming tissue – parallel flows

We consider *two systems of channels* separated by the matrix interface.



Biot continuum:

- ▶ incompressible medium
- ▶ **Double porous matrix** $\rightarrow K_{ij}^\varepsilon \approx \varepsilon^2$ in the *matrix*.

Find $\mathbf{u}^\varepsilon(t) \in V$ and $p^\varepsilon(t) \in H^1(\Omega)$ such that

$$\int_{\Omega} D_{ijkl}^\varepsilon e_{kl}(\mathbf{u}^\varepsilon) e_{ij}(\mathbf{v}) - \int_{\Omega} p^\varepsilon \operatorname{div} \mathbf{v} = \int_{\Omega} \mathbf{f} \cdot \mathbf{v}, \quad \forall \mathbf{v} \in V_0,$$
$$\int_{\Omega} q \operatorname{div} \frac{d}{dt} \mathbf{u}^\varepsilon + \int_{\Omega} K_{ij}^\varepsilon \partial_j p^\varepsilon \partial_i q = 0, \quad \forall q \in H^1(\Omega),$$

where $\mathbf{u}(0, x) = 0$ and $p(0, x) = 0$.

Homogenized model

- ▶ macroscopic displacements $\mathbf{u}(t)$
- ▶ two macroscopic pressures $p_1(t), p_2(t)$

equilibrium of forces (virtual work):

$$\begin{aligned} & \int_{\Omega} \left[\mathcal{E}_{ijkl} e_{kl}^x(\mathbf{u}(t)) + \int_0^t \mathcal{H}_{ijkl}(t-\tau) \frac{d}{d\tau} e_{kl}^x(\mathbf{u}(\tau)) d\tau \right] e_{ij}^x(\mathbf{v}) \\ & - \int_{\Omega} e_{ij}^x(\mathbf{v}) \int_0^t \tilde{\mathcal{R}}_{ij}^1(t-\tau) [p_1(\tau) - p_2(\tau)] d\tau \\ & - \sum_{\alpha=1,2} \int_{\Omega} \left[\frac{|Y_{\alpha}|}{|Y|} \delta_{ij} + \bar{\mathcal{P}}_{ij}^{\alpha} \right] p_{\alpha}(t) e_{ij}^x(\mathbf{v}) = L(\mathbf{v}) \quad \forall \mathbf{v} \in \mathbf{V}_0, \end{aligned}$$

two balance-of-mass equations for $\alpha, \beta = 1, 2, \beta \neq \alpha$

$$\begin{aligned} & \int_{\Omega} \mathcal{C}_{ij}^{\alpha} \partial_j^x p_{\alpha}(t) \partial_i^x q \\ & + \int_{\Omega} q \mathcal{G}^* \frac{d}{dt} (p_{\alpha}(t) - p_{\beta}(t)) + \int_{\Omega} q \int_0^t \tilde{\mathcal{G}}_+(t-\tau) \frac{d}{d\tau} (p_{\alpha}(\tau) - p_{\beta}(\tau)) d\tau \\ & + \int_{\Omega} q \int_0^t \tilde{\mathcal{R}}_{ij}^{\alpha}(t-\tau) \frac{d}{d\tau} e_{ij}^x(\mathbf{u}(\tau)) d\tau + \int_{\Omega} q \left[\frac{|Y_{\alpha}|}{|Y|} \delta_{ij} + \bar{\mathcal{P}}_{ij}^{\alpha} \right] \frac{d}{dt} e_{ij}^x(\mathbf{u}(t)) = 0, \quad \forall q \in \end{aligned}$$

... *fluid flows in the two channels and its redistribution between them.*

Local problems for t -variant correctors

Find $(\tilde{\omega}^{rs}, \tilde{\pi}^{rs}) \in \mathbf{H}_{\#}^1(Y) \times H_{\#0}^1(Y_3)$

such that $\tilde{\pi}^{rs}(0) = -\bar{\pi}^{rs}$ and for $t > 0$

$$\begin{aligned} a_Y(\tilde{\omega}^{rs}(t), \mathbf{v}) - \left(\frac{d}{dt} \tilde{\pi}^{rs}(t), \operatorname{div}_Y \mathbf{v} \right)_{Y_3} &= 0 \quad \forall \mathbf{v} \in \mathbf{H}_{\#}^1(Y) \\ (\psi, \operatorname{div}_Y \tilde{\omega}^{rs}(t))_{Y_3} + c_{Y_3}(\tilde{\pi}^{rs}(t), \psi)_{Y_3} &= 0 \quad \forall \psi \in H_{\#0}^1(Y_3), \end{aligned}$$

Find $(\tilde{\omega}^{\alpha}, \tilde{\pi}^{\alpha}) \in \mathbf{H}_{\#}^1(Y) \times H_{\#}^1(Y_3)$

such that $\tilde{\pi}^{\alpha}(0)$ “is given” (a Lagrange multiplier) and for $t > 0$

$$\begin{aligned} a_Y(\tilde{\omega}^{\alpha}(t), \mathbf{v}) - \left(\frac{d}{dt} \tilde{\pi}^{\alpha}(t), \operatorname{div}_Y \mathbf{v} \right)_{Y_3} &= 0 \quad \forall \mathbf{v} \in \mathbf{H}_{\#}^1(Y) \\ (\psi, \operatorname{div}_Y \tilde{\omega}^{\alpha}(t))_{Y_3} + c_{Y_3}(\tilde{\pi}^{\alpha}(t), \psi)_{Y_3} &= 0 \quad \forall \psi \in H_{\#0}^1(Y_3), \\ \text{where } \tilde{\pi}^{\alpha}(t) &= \delta_{\alpha\beta} \text{ on } \Gamma_{\beta}, \beta = 1, 2. \end{aligned}$$

Corrector t -variant basis functions – Local problems

$\omega^{rs}(t, y)$ displacement in Y effect of macro-strain $e_{rs}^x(\mathbf{u})$

$\pi^{rs}(t, y)$ pressure in $Y_3 \subset Y$ effect of macro-strain $e_{rs}^x(\mathbf{u})$

$\omega^\alpha(t, y)$ displacement in Y effect of macro-pressure P_α

$\pi^\alpha(t, y)$ pressure in $Y_3 \subset Y$ effect of macro-pressure P_α

Microscopic Corrector Problems – generic form

FE approximation

$$\mathbf{A}\tilde{\mathbf{u}}^\spadesuit(t) - \mathbf{B}^T \frac{d}{dt} \tilde{\mathbf{p}}^\spadesuit(t) = 0$$

$$\mathbf{B}\tilde{\mathbf{u}}^\spadesuit(t) + \mathbf{C}\tilde{\mathbf{p}}^\spadesuit(t) = \mathbf{g}^\spadesuit$$

initial condition: $\tilde{\mathbf{p}}^\spadesuit(t=0)$

Matrix operators:

\mathbf{A} stiffness in Y

\mathbf{C} permeability in $Y_3 \subset Y$

\mathbf{B} $\text{div}(\cdot)$ op. in $Y_3 \subset Y$

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Efficient computing of microscopic correctors ???

Schur complement method: *eigenvalue problem*:

$$\mathbf{C}\mathbf{q}^k = \nu^k \mathbf{G}\mathbf{q}^k, \quad k = 1, \dots, N_p, \quad \text{where} \quad \mathbf{G} = \mathbf{B}\mathbf{A}^{-1}\mathbf{B}^T$$
$$\mathbf{E} := \text{diag}(\{\nu^k\}) \quad \mathbf{Q} := \{\mathbf{q}^k\}$$

Microscopic correctors ... [small/large] eigenvalues needed?

$$\tilde{\mathbf{p}}^\alpha(t) = \mathbf{Q} \left[\exp\{-\mathbf{E}t\} \tilde{\zeta}^\alpha(0) + \mathbf{E}^{-1}(\mathbf{I} - \exp\{-\mathbf{E}t\})\mathbf{Q}^T \tilde{\mathbf{g}}^\alpha \right],$$
$$\frac{d}{dt} \tilde{\mathbf{p}}^\alpha(t) = \mathbf{Q} \left[\underbrace{-\mathbf{E} \exp\{-\mathbf{E}t\}}_{\text{at } t \approx 0??} \tilde{\zeta}^\alpha(0) + \exp\{-\mathbf{E}t\} \mathbf{Q}^T \tilde{\mathbf{g}}^\alpha \right]$$

⇒ Initial singularity

$t \approx 0$... large eigenvalues dominate

$t > 0$... small eigenvalues are relevant ⇒ approximation

⇒ approximate computing of convolution kernels

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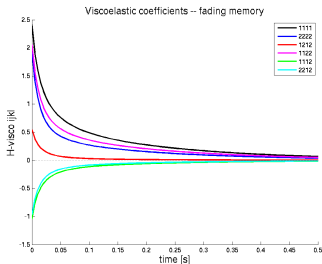
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$t > 0$... **small** eigenvalues are relevant ⇒ approximation

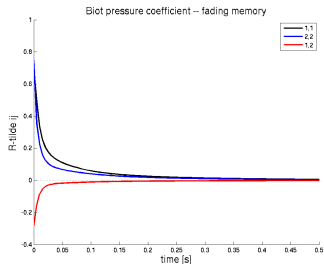
⇒ approximate computing of convolution kernels

Fading Memory Kernels – *synchronous decay* ???

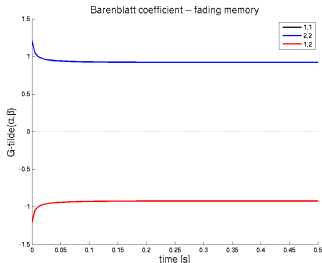
$$\mathcal{H}_{ijkl} \quad 2D$$



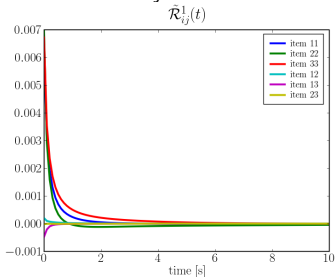
$$\tilde{\mathcal{R}}_{ij}^1 \quad 2D$$



$$\tilde{\mathcal{G}} \quad 2D$$



$$\tilde{\mathcal{R}}_{ij}^1 \quad 3D$$



Homogenized coefficients — Convolutions

Discrete convolution kernels

$$\int_0^{t_j} \mathcal{F}(t-s)f(s) ds \approx \sum_{k=1}^j F^{(j-k)} \bar{f}^{(k)}$$

Approximation of the initial singularity

$$\mathcal{F}(t) \approx \mathcal{F}^* \delta_+(t) + \tilde{\mathcal{F}}(t)$$

$$\mathcal{F}^* = \int_0^{t_\epsilon} \mathcal{A}_{\max \nu}(\mathcal{F}(t)) dt$$

$$\tilde{\mathcal{F}}(t) = \mathcal{A}_{\min \nu}(\mathcal{F}(t))$$

where

$\mathcal{A}_{\max \nu}(\cdot)$ approximation by **large eigenvalues**

$\mathcal{A}_{\min \nu}(\cdot)$ approximation by **small eigenvalues**

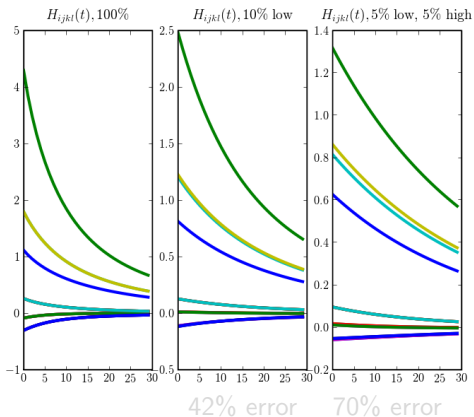
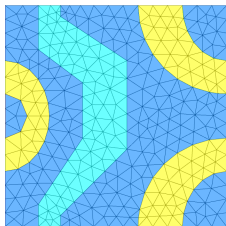
Reduced computation of eigenvalues – Approximation

Strategies

compute ??? % **smallest** and/or **largest** eigenvalues,
given *fine/coars* mesh

Viscoelasticity – fading memory kernels $\mathcal{H}_{ijkl}(t)$

Rough mesh
584 elements



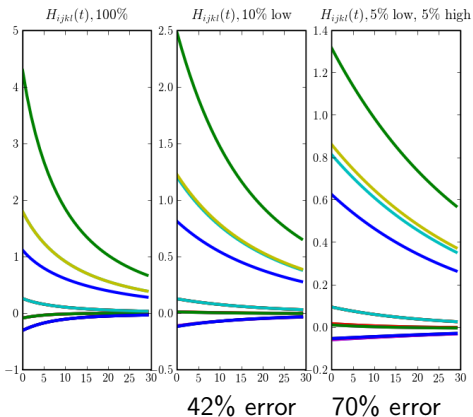
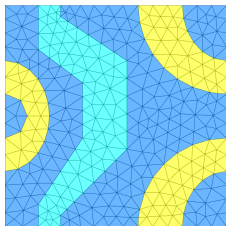
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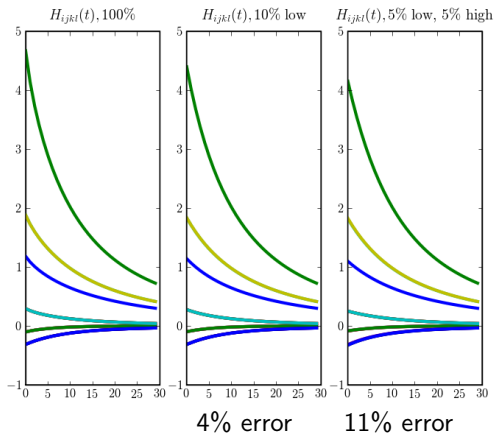
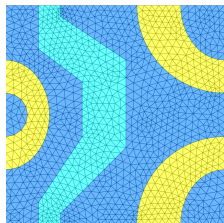
Rough mesh
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Reduced computation of eigenvalues – Approximation

Viscoelasticity – fading memory kernels $\mathcal{H}_{ijkl}(t)$

Fine mesh
2336 elements



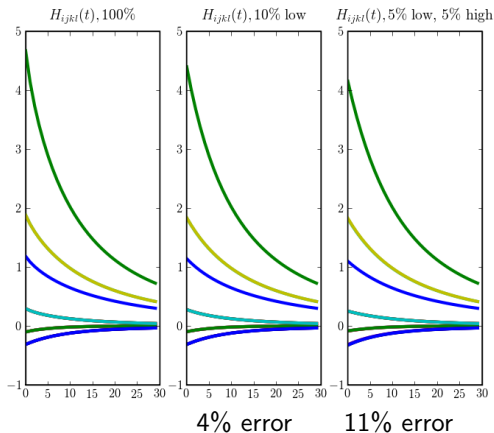
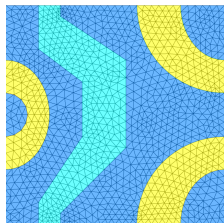
⇒ observation

- ▶ use finer mesh
- ▶ small eigenvalues more important than the large ones

Reduced computation of eigenvalues – Approximation

Viscoelasticity – fading memory kernels $\mathcal{H}_{ijkl}(t)$

Fine mesh
2336 elements



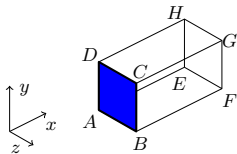
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3D Parallel Flows - Problem Setting

in orthogonal straight channels

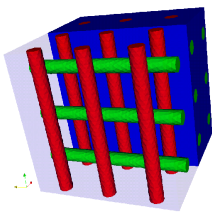
- ▶ macroscopic domain:



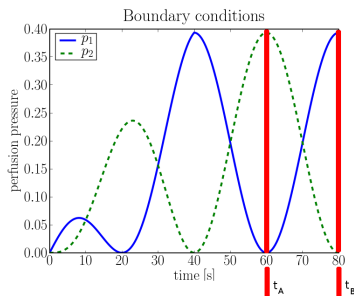
- ▶ BC on face:

- ▶ ABCD: fixed ($\mathbf{u} = 0$)
- ▶ BFGC: given $p_1(t)$
- ▶ CGHD: given $p_2(t)$

- ▶ microstructure:



- ▶ prescribed perfusion pressures:



- ▶ we will show:

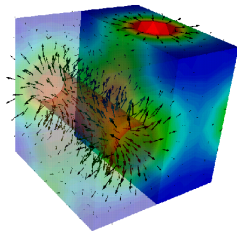
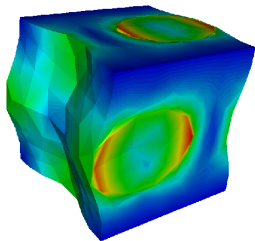
- ▶ some micro-corrector shape functions
- ▶ some fading memory coefficients
- ▶ macro solution snapshots for $t = t_A$, $t = t_B$

Microscopic Solution

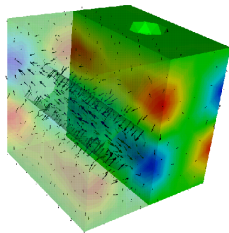
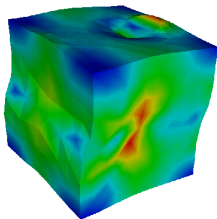
corrector shape functions

▶ steady correctors:

▶ left: $\bar{\omega}^{11}$, right: $\bar{p}^{11} \in [-53, 0]$ + perfusion velocities



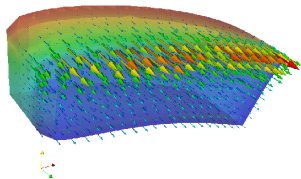
▶ left: $\bar{\omega}^{21}$, right: $\bar{p}^{21} \in [-0.41, 0.43]$ + perfusion velocities



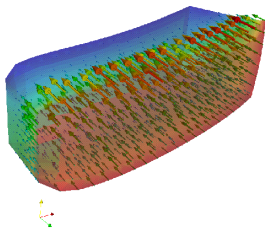
Macroscopic Solution

- ▶ perfused block: color = pressures, arrows = perfusion velocities
- ▶ deformation enlarged for visualization (10x)

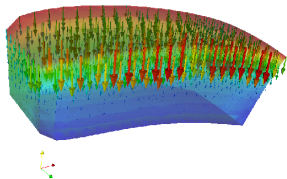
$t = t_A: p_1, \mathbf{w}_1$



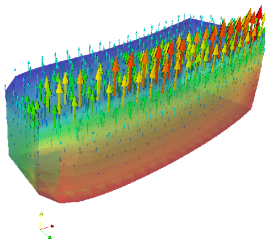
$t = t_B: p_1, \mathbf{w}_1$



$t = t_A: p_2, \mathbf{w}_2$



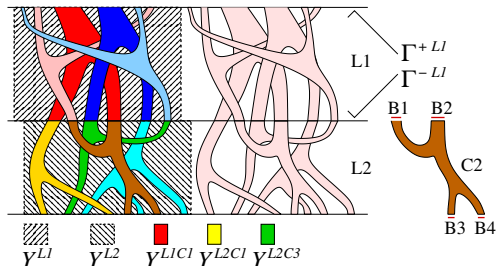
$t = t_B: p_2, \mathbf{w}_2$



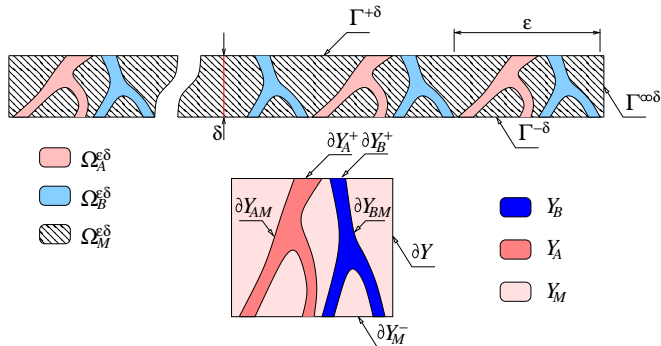
Perfusion of layered structure — model of *brain perfusion*

Idea:

- ▶ brain represented by “spherical” shells
- ▶ each shell has a periodic structures
- ▶ representation of disconnected **arterial** and **venous** trees



Geometry – Layered structure



channels $\Omega_A^{\varepsilon\delta}, \Omega_B^{\varepsilon\delta}$
& matrix $\Omega_M^{\varepsilon\delta}$

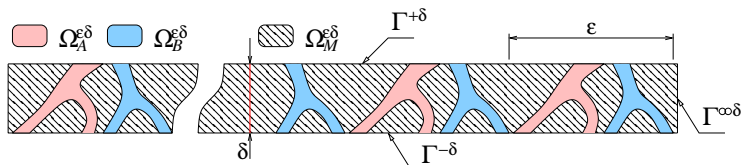
$$\Omega^\delta = \Omega_M^{\varepsilon\delta} \cup \Omega_A^{\varepsilon\delta} \cup \Omega_B^{\varepsilon\delta}$$

$$\emptyset = \Omega_A^{\varepsilon\delta} \cap \Omega_B^{\varepsilon\delta}$$

double-porous medium:
strongly heterogeneous permeability

$$\kappa_{ij}^\varepsilon(x) = \delta_{ij} \times \begin{cases} \kappa\left(\left\{\frac{x}{\varepsilon}\right\}\right) & x \in \Omega_A^{\varepsilon\delta} \cup \Omega_B^{\varepsilon\delta}, \\ \varepsilon^2 \bar{\kappa}\left(\left\{\frac{x}{\varepsilon}\right\}\right) & x \in \Omega_M^{\varepsilon\delta}, \end{cases}$$

Boundary value problem in Ω^δ



$$\begin{aligned} \nabla \cdot \kappa^\epsilon \nabla p^\epsilon &= 0 \quad \text{in } \Omega^\delta, \\ \mathbf{n} \cdot \nabla p^\epsilon &= 0 \quad \text{on } \Gamma^{\infty\delta}, \\ \mathbf{n} \cdot \nabla p^\epsilon &= g^{\epsilon\pm} \quad \text{on } \Gamma^{\delta+} \cup \Gamma^{\delta-}. \end{aligned}$$

$$\text{solvability: } \int_{\Gamma^{\pm\epsilon\delta}} g^{\epsilon\pm} dS = 0,$$

$$\text{uniqueness: } \int_{\Omega_A^{\epsilon\delta} \cup \Omega_B^{\epsilon\delta}} p^\epsilon = 0.$$

Weak formulation $\forall q \in H^1(\Omega^\delta)/\mathbb{R}$

$$\int_{\Omega_A^{\epsilon\delta} \cup \Omega_B^{\epsilon\delta}} \kappa \nabla p^\epsilon \cdot \nabla q + \int_{\Omega_M^{\epsilon\delta}} \epsilon^2 \bar{\kappa} \nabla p^\epsilon \cdot \nabla q = \int_{\Gamma^{\delta+} \cup \Gamma^{\delta-}} g^{\epsilon\pm} q dS,$$

Acoustic waves in ducts with perforated interfaces

Model

- ▶ Acoustic medium – air
- ▶ Perforated interface Γ_0

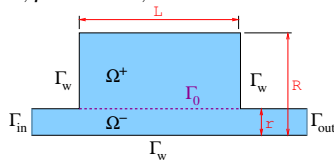
$$\Omega^G = \Omega^+ \cup \Omega^- \cup \Gamma_0$$

- ▶ Problem: Compute acoustic pressure p^+, p^- in Ω^+, Ω^-

$$c^2 \nabla^2 p^+ + \omega^2 p^+ = 0 \quad \text{in } \Omega^+,$$

$$c^2 \nabla^2 p^- + \omega^2 p^- = 0 \quad \text{in } \Omega^-,$$

+ boundary conditions on $\partial\Omega^G$,



Transmission condition on Γ_0 ???

semi-empirical formulae: impedance Z (complex number)

$$\frac{\partial p^+}{\partial n^+} = -i \frac{\omega \rho}{Z} (p^+ - p^-), \quad \frac{\partial p^-}{\partial n^-} = -i \frac{\omega \rho}{Z} (p^- - p^+),$$

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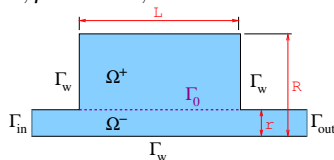
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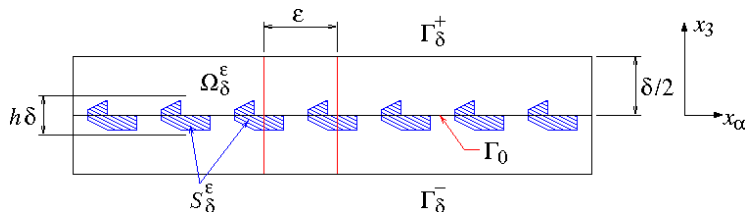
Treatment of transmission conditions

Existing approaches

- ▶ Quasi-empirical approach: $\frac{\partial p^\pm}{\partial n^\pm} = \mp i \frac{\omega \rho}{Z} (p^+ - p^-)$
- ▶ Homogenization – inner and outer expansions
[Sanchez-Hubert, Sanchez-Palencia, 1982], [Bonnet-Ben-Dhia et al., 2007]
- ▶ only “flat perforated thin sieve”

Homogenization of acoustic waves in *thin perforated layer*

- ▶ Arbitrary geometry in the layer
- ▶ thickness \approx period of perforation \approx scale of holes
- ▶ *Goal:* to replace the perforated layer by a “homogenized surface”



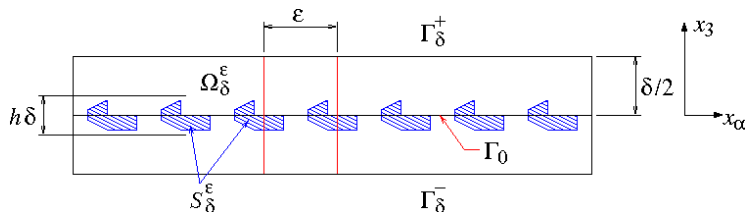
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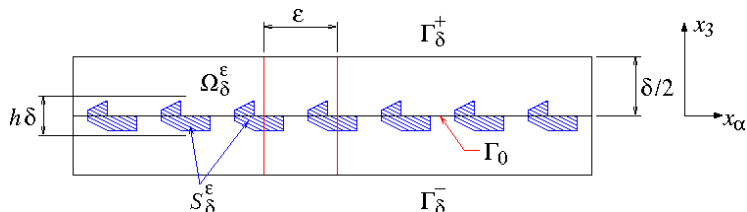
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Boundary value problem in the transmission layer



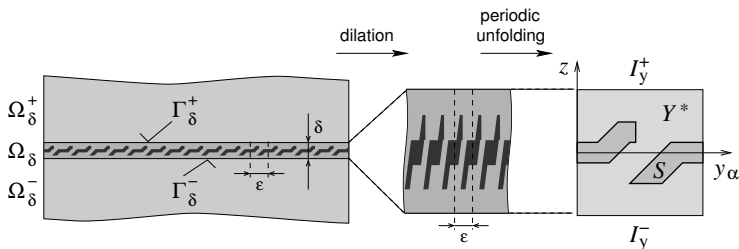
- ▶ thickness proportional to the perforation size: $\delta = \varkappa\varepsilon$
- ▶ low frequencies (ω independent of ε)
- ▶ Neumann problem:

$$c^2 \nabla^2 p^{\varepsilon\delta} + \omega^2 p^{\varepsilon\delta} = 0 \quad \text{in } \Omega_\delta^\varepsilon,$$

$$c^2 \frac{\partial p^{\varepsilon\delta}}{\partial n^\delta} = -i\omega g^{\varepsilon\delta\pm} \quad \text{on } \Gamma_\delta^\pm \quad \dots \text{transversal velocity}$$

$$\frac{\partial p^{\varepsilon\delta}}{\partial n^\delta} = 0 \quad \text{on } \partial S_\delta^\varepsilon \cup \partial \Omega_\delta^\infty \quad \dots \text{solid obstacle,}$$

Dilatation and Periodic unfolding



fluid representation: $\Omega_\delta^\epsilon \xrightarrow{\text{dilatation}} \Omega^\epsilon \xrightarrow{\text{unfolding}} Y^*$

Dilated weak formulation

Find $p^\epsilon \in H^1(\Omega^\epsilon)$ such that

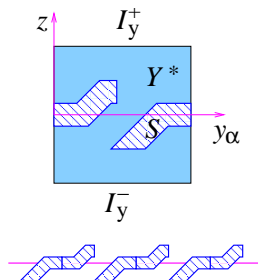
$$c^2 \int_{\Omega^\epsilon} \left(\partial_\alpha p^\epsilon \partial_\alpha q + \frac{1}{\delta^2} \partial_z p^\epsilon \partial_z q \right) - \omega^2 \int_{\Omega^\epsilon} p^\epsilon q = -i\omega \frac{1}{\delta} \left(\int_{\Gamma^+} g^{\epsilon\delta+} q dS + \int_{\Gamma^-} g^{\epsilon\delta-} q dS \right)$$

for all $q \in H^1(\Omega^\epsilon)$.

Geometry of the perforated interface layer

Microscopic scale — periodic perforation

- ▶ representative cell
 $Y = I_y \times]-1/2, +1/2[$
where
 $I_y = \{(y_\alpha, 0) : y_\alpha \in]0, 1[, \alpha = 1, 2\}$
- ▶ solid (rigid) part: S
- ▶ air in $Y^* = Y \setminus S$
- ▶ functions periodic in $y_\alpha, \alpha = 1, 2$



Limit interface fluxes (\approx velocities)

r.h.s. terms

$$\dots = -i\omega \frac{1}{\delta} \left(\int_{\Gamma^+} g^{\varepsilon\delta^+} q \, dS + \int_{\Gamma^-} g^{\varepsilon\delta^-} q \, dS \right)$$

$g^{\varepsilon\delta^\pm}$ must be specified:

- ▶ assume existence of $g^{0-}, g^{0+} \in L^2(\Gamma_0)$ such that

$$\mathcal{T}_\varepsilon^b(g^{\varepsilon^+}) \rightharpoonup g^{0+} \text{ and } \mathcal{T}_\varepsilon^b(g^{\varepsilon^-}) \rightharpoonup g^{0-} \text{ weakly in } L^2(\Gamma_0 \times I_y^\pm).$$

- ▶ transversal acoustic velocity does not change when passing the perforated layer, thus, we require

$$\frac{1}{\varepsilon} \left(\int_{\Gamma^+} \phi g^{\varepsilon^+} + \int_{\Gamma^-} \phi g^{\varepsilon^-} \right) \rightarrow 0 \quad \forall \phi \in \mathcal{D}(\Gamma_0).$$

- ▶ ... therefore $g^{0\pm} \equiv g^{0+} = -g^{0-}$.

Limit equation – tangent acoustic wave in plane Γ_0

$$c^2 \int_{\Gamma_0 \times Y^*} (\partial_\alpha^x p^0 + \partial_\alpha^y p^1) (\partial_\alpha^x q^0 + \partial_\alpha^y q^1) + c^2 \frac{1}{\varkappa^2} \int_{\Gamma_0 \times Y^*} \partial_z p^1 \partial_z q^1 \\ - \omega^2 \int_{\Gamma_0 \times Y^*} p^0 q^0 = -\frac{i\omega}{\varkappa} \int_{\Gamma_0} g^{0\pm} \left[\int_{I_y^+} q^1 dS_y - \int_{I_y^-} q^1 dS_y \right]$$

- ▶ local (microscopic) problem: $q^0 \equiv 0$,
 $q^1(x_\alpha, y) = \theta(x_\alpha)\phi(y)$
- ▶ global (macroscopic) problem: $q^1 \equiv 0$,
 $q^0 = q^0(x_\alpha)$

Acoustic pressure jump on Γ_0 – acoustic impedance X

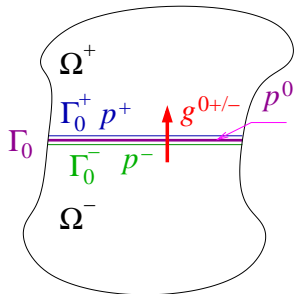
Coupling the limit interface acoustic pressures $p^+, p^- \in L^2(\Gamma_0)$ and the “transversal velocity” such that for any $\phi \in \mathcal{D}(\Gamma_0)$

$$\frac{1}{\varepsilon_0} \int_{\Gamma_0} \phi(p^+ - p^-) \approx \int_{\Gamma_0} \phi \frac{1}{|I_y|} \left[\int_{I_y^+} p^1 d\Gamma_y - \int_{I_y^-} p^1 d\Gamma_y \right].$$

Acoustic impedance (implicit)

$$p^+ - p^- = X g^{0\pm}$$

- ▶ pressure jump $p^+ - p^-$
- ▶ transversal velocity $g^{0\pm}$



Local microscopic problems — pressure correctors

- ▶ Scale decoupling — corrector functions:

$$p^1(x_\alpha, y) = \pi^\beta(y) \partial_\beta p^0(x_\alpha) + i\omega \xi^\pm(y) g^{0\pm}(x_\alpha),$$

- ▶ Corrector of the **tangent interface velocity** $v_t \approx \partial_\alpha p^0$
find $\pi^\beta \in H_{\#(1,2)}^1(Y)$, $\beta = 1, 2$, such that

$$\int_{Y^*} \left[\partial_\alpha^y \pi^\beta \partial_\alpha^y q + \frac{1}{\varkappa^2} \partial_z \pi^\beta \partial_z q \right] = - \int_{Y^*} \partial_\beta^y q \quad \forall q \in H_{\#(1,2)}^1(Y)$$

- ▶ Corrector of the **normal interface velocity** $v_n \approx g^{0\pm}$
find $\xi^\pm \in H_{\#(1,2)}^1(Y)/\mathbb{R}$, such that

$$\int_{Y^*} \left[\partial_\alpha^y \xi^\pm \partial_\alpha^y q + \frac{1}{\varkappa^2} \partial_z \xi^\pm \partial_z q \right] = - \frac{|Y|}{c^2 \varkappa} \left(\int_{I_y^+} q dS_y - \int_{I_y^-} q dS_y \right),$$

for all $q \in H_{\#(1,2)}^1(Y)/\mathbb{R}$

Homogenized interface conditions

Homogenized coefficients

- ▶ Tangent acoustic diffusion coefficients

$$A_{\alpha\beta} = \frac{c^2}{|Y|} \int_{Y^*} \partial_\gamma^y (y^\beta + \pi^\beta) \partial_\gamma^y (y^\alpha + \pi^\alpha) + \frac{c^2}{\varkappa^2 |Y|} \int_{Y^*} \partial_z \pi^\beta \partial_z \pi^\alpha .$$

- ▶ Coefficients of transversal-to-tangent coupling of velocity

$$B_\alpha = \frac{c^2}{|Y|} \int_{Y^*} \partial_\alpha^y \xi^\pm ,$$
$$\frac{\varkappa}{|I_y|} B_\alpha = D_\alpha = \frac{1}{|I_y|} \left(\int_{I_y^+} \pi^\alpha dS_y - \int_{I_y^-} \pi^\alpha dS_y \right) ,$$

- ▶ Local transversal impedance

$$F = \frac{1}{|I_y|} \left(\int_{I_y^+} \xi^\pm dS_y - \int_{I_y^-} \xi^\pm dS_y \right)$$

Homogenized interface conditions

Acoustic transmission

- ▶ Given pressure jump $[p^+ - p^-]$
- ▶ Find $p^0 \in H^1(\Gamma_0)$ and $g^{0\pm} \in L^2(\Gamma_0)$ such that

$$\int_{\Gamma_0} A_{\alpha\beta} \partial_{\beta}^x p^0 \partial_{\alpha}^x q - \frac{|Y^*|}{|Y|} \omega^2 \int_{\Gamma_0} p^0 q + i\omega \int_{\Gamma_0} g^{0\pm} B_{\alpha} \partial_{\alpha}^x q = 0$$
$$-i\omega \int_{\Gamma_0} \psi D_{\beta} \partial_{\beta}^x p^0 + \omega^2 \int_{\Gamma_0} F g^{0\pm} \psi = -\frac{i\omega}{\varepsilon_0} \int_{\Gamma_0} (p^+ - p^-) \psi$$

for all $q \in H^1(\Gamma_0)$ and $\psi \in L^2(\Gamma_0)$

Explanation

- ▶ transversal **pressure jump** induces transversal and in-plane fluxes (velocities)
- ▶ in-plane waves – $A_{\alpha\beta} \approx c^2$ anisotropic velocity² of propagation
in-plane resonance: eigenpairs $(\hat{\omega}^2, \hat{p})$ satisfy

$$-\partial_{\alpha} A_{\alpha\beta} \partial_{\beta} \hat{p} = \frac{|Y^*|}{|Y|} \hat{\omega}^2 \hat{p} \quad \text{in } \Gamma_0$$

Homogenized interface conditions

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- ▶ Find $p^0 \in H^1(\Gamma_0)$ and $g^{0\pm} \in L^2(\Gamma_0)$ such that

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Acoustic problem with homogenized perforation

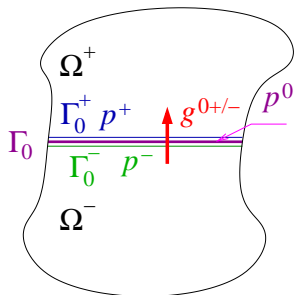
Acoustic behaviour in $\Omega^+ \cup \Omega^-$

$$c^2 \nabla^2 p^+ + \omega^2 p^+ = 0 \quad \text{in } \Omega^+,$$

$$c^2 \nabla^2 p^- + \omega^2 p^- = 0 \quad \text{in } \Omega^-,$$

+ boundary conditions on $\partial\Omega^G$,

$$\Omega^G = \Omega^+ \cup \Omega^- \cup \Gamma_0$$



Transmission condition — in terms of p^0 and $g^{0\pm}$

$$c^2 \frac{\partial p^+}{\partial n^+} = i\omega g^{0\pm} \quad \text{on } \Gamma_0,$$

$$c^2 \frac{\partial p^-}{\partial n^-} = -i\omega g^{0\pm} \quad \text{on } \Gamma_0,$$

Interface problem for p^0 and $g^{0\pm}$ be satisfied

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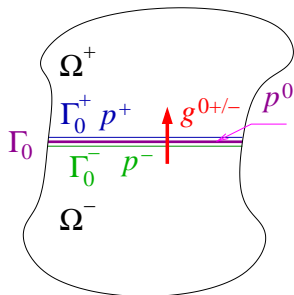
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Interface problem for p^0 and $g^{0\pm}$ be satisfied

Discretized interface problem

$$\mathbf{A}\mathbf{p}^0 - \phi^* \omega^2 \mathbf{M}\mathbf{p}^0 + i\omega \mathbf{B}^T \mathbf{g}^0 = 0$$

$$-i\omega \mathbf{D}\mathbf{p}^0 + \omega^2 \mathbf{F}\mathbf{g}^0 = -i\omega \mathbf{M}(\mathbf{p}^+ - \mathbf{p}^-) \frac{1}{\epsilon_0}$$

- ▶ Schur complement (for ω out-of-resonance)

$$\mathbf{p}^0 = -i\omega (\mathbf{A} - \phi^* \omega^2 \mathbf{M})^{-1} \mathbf{B}^T \mathbf{g}^0,$$

$$\omega^2 [\mathbf{F} - \mathbf{D}(\mathbf{A} - \phi^* \omega^2 \mathbf{M})^{-1} \mathbf{B}^T] \mathbf{g}^0 = -i\omega \mathbf{M}(\mathbf{p}^+ - \mathbf{p}^-) \frac{1}{\epsilon_0}$$

- ▶ Coupled impedance $\mathbf{X}(\omega^2) = \omega^2 [\mathbf{F} - \mathbf{D}(\mathbf{A} - \phi^* \omega^2 \mathbf{M})^{-1} \mathbf{B}^T]$

$$\epsilon_0 \mathbf{X}(\omega^2) \mathbf{g}^0 = -i\omega \mathbf{M}(\mathbf{p}^+ - \mathbf{p}^-)$$

- ▶ ... resembles the structure of the standard conditions, since $\mathbf{g}^0 \approx \partial \mathbf{p}^+ / \partial n^+ = -\partial \mathbf{p}^- / \partial n^-$.

Global problem – FEM discretization

notation	explanation
\mathbf{p}	... pressure in $\Omega^+ \cup \Omega^- \cup \partial\Omega$
$\mathbf{p}^{+/-}$... pressure on $\Gamma_0^+ \cup \Gamma_0^-$
$\mathbf{C}(\omega), \mathbf{Q}^+(\omega), \mathbf{Q}^-(\omega)$... matrices assoc. with $c^2 \nabla^2 p + \omega^2 p$ and with B.C. in $\bar{\Omega} \setminus \Gamma_0^{+/-}$
$\bar{\mathbf{C}}^{+/-}(\omega)$... matrix assoc. with $c^2 \nabla^2 p + \omega^2 p$ on $\Gamma_0^+ \cup \Gamma_0^-$
$\bar{\mathbf{h}}$... r.h.s. (boundary conditions)

$$\begin{bmatrix} \mathbf{C}(\omega), & (\mathbf{Q}^+)^H(\omega), & (\mathbf{Q}^-)^H(\omega), & 0 \\ \mathbf{Q}^+(\omega), & \bar{\mathbf{C}}^+(\omega) & 0, & -i\omega\mathbf{M} \\ \mathbf{Q}^-(\omega), & 0, & \bar{\mathbf{C}}^-(\omega), & +i\omega\mathbf{M} \\ 0, & +i\omega\mathbf{M}, & -i\omega\mathbf{M}, & \varepsilon\mathbf{X}(\omega^2) \end{bmatrix} \cdot \begin{bmatrix} \mathbf{p} \\ \mathbf{p}^+ \\ \mathbf{p}^- \\ \mathbf{g}^0 \end{bmatrix} = i\omega \begin{bmatrix} \bar{\mathbf{h}} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$\varepsilon\mathbf{X}(\omega^2)$... coupled impedance for finite scale of the perforation

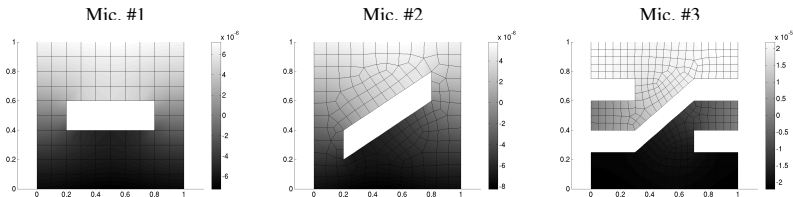
$$\varepsilon\kappa = \delta = \text{layer thickness [m]} \quad \kappa \approx 1$$

Influence of the perforation geometry

TEST:

- ▶ 3 microstructures (2D acoustics problem)
- ▶ Variation of homogenized transmission parameters

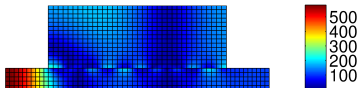
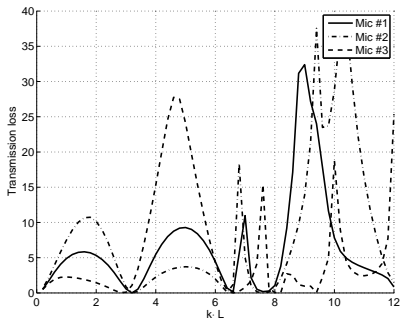
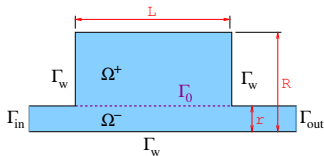
Mic.	$A[(\text{m/s})^2]$	$B[\text{m}]$	$F[\text{s}^2]$
#1	$1.155 \cdot 10^5$	0	$1.391 \cdot 10^{-5}$
#2	$1.704 \cdot 10^5$	-0.251	$1.324 \cdot 10^{-5}$
#3	$2.186 \cdot 10^5$	-0.897	$4.265 \cdot 10^{-5}$



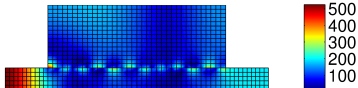
Distribution of ξ^\pm in Y^* .

Transmission loss TL – Global response – 3 microstructures

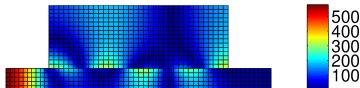
- ▶ $TL = 20 \log (|\bar{p}|_{\Gamma_{in}}|/|p|_{\Gamma_{out}}|)$
- ▶ test wave guide (2D):
 $\Gamma_0 \dots$ thickness $0.007 \cdot L$



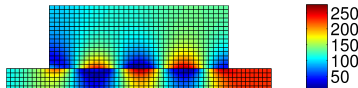
Mic. #1; $k \cdot L = 5$



Mic. #2; $k \cdot L = 5$



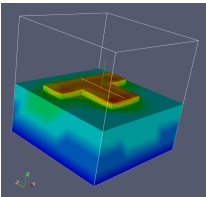
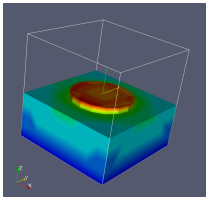
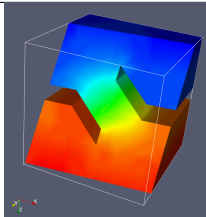
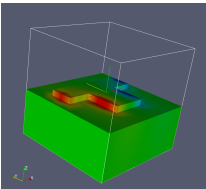
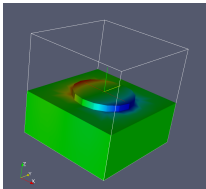
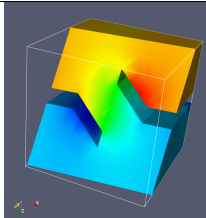
Mic. #3; $k \cdot L = 5$



Mic. #3; $k \cdot L = 1$

Modulus of the acoustic pressure in Ω^G for $k \cdot L = 5$ (1 in the last picture)

3D micro-problems – periodic microstructures

	isotropic “flat”	anisotropic “flat”	anisotropic “relief”
ξ^\pm			
π^1			
coupl.:	$B_\alpha = 0$	$B_\alpha = 0$	$B_\alpha = [0.303, -0.011]$
imped.:	$F = 1.32 \cdot 10^{-5}$	$F = 1.42 \cdot 10^{-5}$	$F = 2.56 \cdot 10^{-5}$
sound velo.:	$A = 10^5 \begin{bmatrix} 1.19, & 0.0 \\ 0.0, & 1.2 \end{bmatrix}$	$A = 10^5 \begin{bmatrix} 1.19, & 0.0 \\ 0.0, & 1.19 \end{bmatrix}$	$A = 10^5 \begin{bmatrix} 1.44, & -0.01 \\ -0.01, & 1.80 \end{bmatrix}$



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