# Method of lower and upper functions and the existence of solutions to singular periodic problems for second order nonlinear differential equations

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**Abstract.** We construct nonconstant lower and upper functions for the periodic boundary value problem u'' = f(t, u),  $u(0) = u(2\pi)$ ,  $u'(0) = u'(2\pi)$  and find their estimates. By means of these results we prove existence criteria for the problems  $u'' \pm g(u) = e(t)$ ,  $u(0) = u(2\pi)$ ,  $u'(0) = u'(2\pi)$ , where  $\limsup_{x\to 0+} g(x) = \infty$  is allowed and  $e \in \mathbb{L}[0, 2\pi]$  need not be essentially bounded. **Mathematics Subject Classification 2000.** 34 B 15, 34 C 25

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### 1. Introduction

In this paper we construct lower and upper functions to the periodic boundary value problem

(1.1) 
$$u'' = f(t, u), \quad u(0) = u(2\pi), \quad u'(0) = u'(2\pi).$$

By means of these results we prove existence criteria for the problems

$$u'' \pm g(u) = e(t), \quad u(0) = u(2\pi), \quad u'(0) = u'(2\pi),$$

where  $\limsup_{x\to 0+} g(x) = \infty$  is allowed and  $e \in \mathbb{L}[0, 2\pi]$  need not be essentially bounded. We assume that  $f: [0, 2\pi] \times \mathbb{R} \to \mathbb{R}$  fulfils the Carathéodory conditions on  $[0, 2\pi] \times \mathbb{R}$ , i.e. f has the following properties: (i) for each  $x \in \mathbb{R}$  the function f(., x) is measurable on  $[0, 2\pi]$ ; (ii) for almost every  $t \in [0, 2\pi]$  the function f(t, .) is continuous on  $\mathbb{R}$ ; (iii) for each compact set  $K \subset \mathbb{R}$  the function  $m_K(t) = \sup_{x \in K} |f(t, x)|$  is Lebesgue integrable on  $[0, 2\pi]$ .

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For a given subinterval J of  $\mathbb{R}$  (possibly unbounded),  $\mathbb{C}(J)$  denotes the set of functions continuous on J. Furthermore,  $\mathbb{L}[0, 2\pi]$  stands for the set of functions Lebesgue integrable on  $[0, 2\pi]$ ,  $\mathbb{L}_2[0, 2\pi]$  is the set of functions square Lebesgue integrable on  $[0, 2\pi]$  and  $\mathbb{AC}[0, 2\pi]$  denotes the set of functions absolutely continuous on  $[0, 2\pi]$ . For x bounded on  $[0, 2\pi]$ ,  $y \in \mathbb{L}[0, 2\pi]$  and  $z \in \mathbb{L}_2[0, 2\pi]$  we denote

$$\|x\|_{\mathbb{C}} = \sup_{t \in [0, 2\pi]} |x(t)|, \quad \overline{y} = \frac{1}{2\pi} \int_{0}^{2\pi} y(s) \, \mathrm{d}s,$$
$$\|y\|_{1} = \int_{0}^{2\pi} |y(t)| \, \mathrm{d}t \text{ and } \|z\|_{2} = \left(\int_{0}^{2\pi} z^{2}(t) \, \mathrm{d}t\right)^{\frac{1}{2}}.$$

By a solution of (1.1) we mean a function  $u : [0, 2\pi] \mapsto \mathbb{R}$  such that  $u' \in \mathbb{AC}[0, 2\pi], u(0) = u(2\pi), u'(0) = u'(2\pi)$  and

$$u''(t) = f(t, u(t))$$
 for a.e.  $t \in [0, 2\pi]$ .

**1.1. Definition.** A function  $\sigma_1$  is said to be a *lower function of the problem* (1.1) if  $\sigma'_1 \in \mathbb{AC}[0, 2\pi]$ ,

$$\sigma_1''(t) \ge f(t, \sigma_1(t)) \quad \text{for a.e.} \quad t \in [0, 2\pi], \\ \sigma_1(0) = \sigma_1(2\pi), \quad \sigma_1'(0) \ge \sigma_1'(2\pi).$$

Similarly, a function  $\sigma_2$  is said to be an upper function of the problem (1.1) if  $\sigma'_2 \in \mathbb{AC}[0, 2\pi],$ 

$$\sigma_2''(t) \le f(t, \sigma_2(t)) \quad \text{for a.e.} \quad t \in [0, 2\pi],$$
  
 $\sigma_2(0) = \sigma_2(2\pi), \quad \sigma_2'(0) \le \sigma_2'(2\pi).$ 

The lower and upper functions approach we will use here is based on the following theorem which is contained in [8, Theorems 4.1 and 4.2].

**1.2. Theorem.** Let  $\sigma_1$  and  $\sigma_2$  be respectively a lower and an upper function of the problem (1.1).

(I) Suppose  $\sigma_1(t) \leq \sigma_2(t)$  on  $[0, 2\pi]$ . Then there is a solution u of the problem (1.1) such that  $\sigma_1(t) \leq u(t) \leq \sigma_2(t)$  on  $[0, 2\pi]$ .

(II) Suppose  $\sigma_1(t) \ge \sigma_2(t)$  on  $[0, 2\pi]$  and there is  $m \in \mathbb{L}[0, 2\pi]$  such that

$$f(t,x) \ge m(t) \quad \text{for a.e.} \quad t \in [0,2\pi] \text{ and all } x \in \mathbb{R}$$
$$(or f(t,x) \le m(t) \quad \text{for a.e.} \quad t \in [0,2\pi] \text{ and all } x \in \mathbb{R}.)$$

Then there is a solution u of the problem (1.1) such that  $||u'||_{\mathbb{C}} \leq ||m||_1$  and

$$\sigma_2(t_u) \le u(t_u) \le \sigma_1(t_u)$$
 for some  $t_u \in [0, 2\pi]$ .

## 2. Construction of lower and upper functions

**2.1. Proposition.** Assume that there are  $A \in \mathbb{R}$  and  $b \in \mathbb{L}[0, 2\pi]$  such that

$$(2.1) \qquad \overline{b} = 0,$$

(2.2) 
$$f(t,x) \le b(t) \text{ for a.e. } t \in [0,2\pi] \text{ and all } x \in [A,B],$$

where

(2.3) 
$$B = A + \frac{\pi}{3} ||b||_1.$$

Then there exists a lower function  $\sigma$  of the problem (1.1) such that

(2.4) 
$$A \le \sigma(t) \le B \quad on \quad [0, 2\pi].$$

*Proof.* Define

$$\sigma_0(t) = c_0 + \int_0^{2\pi} g(t,s)b(s) \,\mathrm{d}s \,\mathrm{for} \ t \in [0,2\pi],$$

where

$$g(t,s) = \begin{cases} \frac{t(s-2\pi)}{2\pi} & \text{if } 0 \le t \le s \le 2\pi, \\ \frac{(t-2\pi)s}{2\pi} & \text{if } 0 \le s < t \le 2\pi \end{cases}$$

is the Green function of the problem v'' = 0,  $v(0) = v(2\pi) = 0$  and

$$c_0 = -\frac{1}{2\pi} \int_0^{2\pi} \left( \int_0^{2\pi} g(t,s)b(s) \, \mathrm{d}s \right) \mathrm{d}t.$$

Then

(2.5) 
$$\sigma_0''(t) = b(t)$$
 a.e. on  $[0, 2\pi]$ 

 $\quad \text{and} \quad$ 

(2.6)  $\sigma_0(0) = \sigma_0(2\pi).$ 

Furthermore, in virtue of (2.1) we have also

(2.7) 
$$\sigma'_0(0) = \sigma'_0(2\pi).$$

Multiplying the relation (2.5) by  $\sigma_0$ , integrating it over  $[0, 2\pi]$  and using the Hölder inequality we get

$$\|\sigma_0'\|_2^2 \le \|b\|_1 \|\sigma_0\|_{\mathbb{C}}.$$

Further, as  $\overline{\sigma_0} = 0$ , the Sobolev inequality (see [5, Proposition 1.3]) yields

$$\|\sigma_0'\|_2^2 \le \sqrt{\frac{\pi}{6}} \|b\|_1 \|\sigma_0'\|_2,$$

and so

 $\|\sigma_0'\|_2 \le \sqrt{\frac{\pi}{6}} \|b\|_1,$ 

wherefrom using again the Sobolev inequality we get

$$\|\sigma_0\|_{\mathbb{C}} \leq \frac{\pi}{6} \|b\|_1.$$

Thus, the function  $\sigma$  given by

(2.8) 
$$\sigma(t) = \frac{\pi}{6} \|b\|_1 + A + \sigma_0(t) \text{ for } t \in [0, 2\pi]$$

satisfies (2.4). Furthermore, according to (2.1), (2.2) and (2.6)-(2.8) we have

(2.9) 
$$\sigma''(t) = \sigma_0''(t) = b(t) \ge f(t, \sigma(t)) \text{ for a.e. } t \in [0, 2\pi]$$

and

(2.10) 
$$\sigma(0) = \sigma(2\pi), \quad \sigma'(0) = \sigma'(2\pi),$$

i.e.  $\sigma$  is a lower function of (1.1).

The following assertion is dual to Proposition 2.1 and its proof will be omitted. 2.2. Proposition. Assume that there are  $A \in \mathbb{R}$  and  $b \in \mathbb{L}[0, 2\pi]$  such that

$$\overline{b} = 0$$

and

$$f(t,x) \ge b(t)$$
 for a.e.  $t \in [0,2\pi]$  and all  $x \in [A,B]$ 

where B is given by (2.3). Then there exists an upper function  $\sigma$  of the problem (1.1) with the property (2.4).

## 3. Applications to Lazer-Solimini singular problems

In this section we will consider possibly singular problems of the attractive type

(3.1) 
$$u'' + g(u) = e(t), \quad u(0) = u(2\pi), \quad u'(0) = u'(2\pi)$$

and of the repulsive type

(3.2)  $u'' - g(u) = e(t), \quad u(0) = u(2\pi), \quad u'(0) = u'(2\pi),$ 

where

(3.3) 
$$g \in \mathbb{C}(0,\infty) \text{ and } e \in \mathbb{L}[0,2\pi]$$

and it is allowed that  $\limsup_{x\to 0+} g(x) = \infty$ .

The problem (3.1) has been studied by Lazer and Solimini in [6] for  $e \in \mathbb{C}[0, 2\pi]$ and g positive. In [9, Corollary 3.3], their existence result has been extended to  $e \in \mathbb{L}[0, 2\pi]$  essentially bounded from above. Here, we bring conditions for the existence of solutions to (3.1) without assuming boundedness of e.

**3.1. Theorem.** Assume (3.3) and let there exist  $A_1, A_2 \in (0, \infty)$  such that

(3.4) 
$$g(x) \ge \overline{e} \text{ for all } x \in [A_1, B_1],$$

(3.5) 
$$g(x) \le \overline{e} \text{ for all } x \in [A_2, B_2],$$

where

(3.6) 
$$B_1 - A_1 = B_2 - A_2 = \frac{\pi}{3} ||e - \overline{e}||_1$$

and  $A_2 \geq B_1$ .

Then the problem (3.1) has a solution u such that  $A_1 \leq u(t) \leq B_2$  on  $[0, 2\pi]$ .

*Proof.* Define, for a.e.  $t \in [0, 2\pi]$ ,

$$f(t, x) = e(t) - \begin{cases} g(A_1) & \text{if } x < A_1, \\ g(x) & \text{if } x \ge A_1. \end{cases}$$

Then f satisfies the Carathéodory conditions on  $[0, 2\pi] \times \mathbb{R}$ . Furthermore, by (3.4) and (3.6), f satisfies (2.1)-(2.3) with  $b(t) = e(t) - \overline{e}$  a.e. on  $[0, 2\pi]$  and  $[A, B] = [A_1, B_1]$ . Hence, by Proposition 2.1 there exists a lower function  $\sigma_1$  of (1.1) such that  $\sigma_1(t) \in [A_1, B_1]$  for all  $t \in [0, 2\pi]$ . Similarly, (3.5), (3.6) and Proposition 2.2 yield the existence of an upper function  $\sigma_2$  of (1.1) such that  $\sigma_2(t) \in [A_2, B_2]$  on  $[0, 2\pi]$ . Now, since  $A_2 \geq B_1$ , we have  $\sigma_1(t) \leq \sigma_2(t)$  on  $[0, 2\pi]$  and the assertion (I) of Theorem 1.2 gives the existence of the desired solution u to (1.1) which is also a solution to (3.1), of course.

Classical Lazer and Solimini's considerations [6] of the repulsive problem (3.2) have been extended by several authors (see e.g. [1], [2], [3], [4], [7] and [10]). Here we present a related result, where *e* need not be essentially bounded.

**3.2. Theorem.** Assume (3.3),

(3.7) 
$$\lim_{x \to 0+} \int_x^1 g(\xi) \,\mathrm{d}\xi = \infty,$$

and

(3.8) 
$$g_* := \inf_{x \in (0,\infty)} g(x) > -\infty.$$

Furthermore, let there exist  $A_1, A_2 \in (0, \infty)$  such that

(3.9) 
$$g(x) \le -\overline{e} \text{ for all } x \in [A_1, B_1],$$

(3.10) 
$$g(x) \ge -\overline{e} \text{ for all } x \in [A_2, B_2].$$

where (3.6) is true and  $A_1 \ge B_2$ .

Then the problem (3.2) has a positive solution.

*Proof.* Denote

$$K = ||e||_1 + 2\pi |g_*|, \quad B = B_1 + 2\pi K \text{ and } K^* = K ||e||_1 + \int_{A_2}^B |g(x)| \, \mathrm{d}x.$$

It follows from (3.7) that  $\limsup_{x\to 0+} g(x) = \infty$  and there exists  $\varepsilon \in (0, A_2)$  such that

(3.11) 
$$\int_{\varepsilon}^{A_2} g(x) dx > K^* \text{ and } g(\varepsilon) > 0$$

Define

$$\widetilde{g}(x) = \begin{cases} g(x) & \text{if } x \ge \varepsilon, \\ g(\varepsilon) & \text{if } x < \varepsilon, \end{cases}$$

 $\operatorname{and}$ 

$$f(t,x) = e(t) + \widetilde{g}(x)$$
 for a.e.  $t \in [0, 2\pi]$  and all  $x \in \mathbb{R}$ .

Now, we can argue as in the proof of Theorem 3.1 obtaining a lower function  $\sigma_1$  and an upper function  $\sigma_2$  of (1.1) such that  $\sigma_1(t) \geq \sigma_2(t)$  on  $[0, 2\pi]$ . The assertion (II) of Theorem 1.2 (with  $m(t) = g_* + e(t)$  a.e. on  $[0, 2\pi]$ ) implies that (1.1) has a solution u such that  $u(t_u) \in [A_2, B_1]$  for some  $t_u \in [0, 2\pi]$  and  $||u'||_{\mathbb{C}} \leq K$ . It remains to show that  $u(t) \geq \varepsilon$  holds on  $[0, 2\pi]$ .

Let  $t_0$  and  $t_1 \in [0, 2\pi]$  be such that

$$u(t_0) = \min_{t \in [0,2\pi]} u(t)$$
 and  $u(t_1) = \max_{t \in [0,2\pi]} u(t)$ .

Clearly,  $A_2 \leq u(t_1) \leq B$ . With respect to the periodic boundary conditions we have  $u'(t_0) = u'(t_1) = 0$ . Now, multiplying the differential relation  $u''(t) = e(t) + \tilde{g}(u(t))$  by u'(t) and integrating over  $[t_0, t_1]$  we get

$$0 = \int_{t_0}^{t_1} u''(t) \, u'(t) \, \mathrm{d}t = \int_{t_0}^{t_1} e(t) \, u'(t) \, \mathrm{d}t + \int_{t_0}^{t_1} \widetilde{g}(u(t)) \, u'(t) \, \mathrm{d}t,$$

i.e.

$$\int_{u(t_0)}^{u(t_1)} \widetilde{g}(x) \, \mathrm{d}x = -\int_{t_0}^{t_1} e(t) \, u'(t) \, \mathrm{d}t \le K \, \|e\|_1.$$

Further,

$$\int_{u(t_0)}^{A_2} \widetilde{g}(x) \, \mathrm{d}x \le K \, \|e\|_1 + \int_{A_2}^{B} |\widetilde{g}(x)| \, \mathrm{d}x = K^*$$

which, with respect to (3.11), is possible only if  $u(t_0) \ge \varepsilon$ . Thus, u is a solution to (3.2).

**3.3. Example.** Let  $g(x) = \frac{1}{x^{\gamma}}$  on  $(0, \infty)$ . If  $\gamma > 0$ , then Theorem 3.1 ensures the existence of a positive solution to (3.1) for any  $e \in \mathbb{L}[0, 2\pi]$  such that

(3.12) 
$$\overline{e} > 0 \text{ and } \frac{\pi}{3} \overline{e}^{\frac{1}{\gamma}} \| e - \overline{e} \|_{\mathbb{L}} < 1.$$

The function  $e(t) = c + \frac{1}{\sqrt{2\pi t}} - \frac{1}{\pi}$  with  $c \in \mathbb{R}$  is not essentially bounded from above on  $[0, 2\pi]$ . However, it satisfies (3.12) if

$$0 < c < \left(\frac{3}{\pi}\right)^{\gamma}.$$

We should mention that provided  $e \in \mathbb{C}[0, 2\pi]$  or e is essentially bounded from above, the condition  $\overline{e} > 0$  is sufficient for the existence of a solution to (3.1) (cf. [6] or [9], respectively).

**3.4. Example.** Let  $e \in \mathbb{L}[0, 2\pi]$  be essentially unbounded from below and let

$$g(x) = \frac{1 + \sin(\frac{\pi}{x})}{x} - \arctan(x), \quad x \in (0, \infty).$$

Then g verifies the assumptions (3.3), (3.7) and (3.8) of Theorem 3.2. Let us suppose that  $\overline{e} = -5$ . Then the equation g(x) = 5 has exactly 5 roots in the interval  $[0.125, \infty)$ . In particular, we have (see Figures 1 and 2)

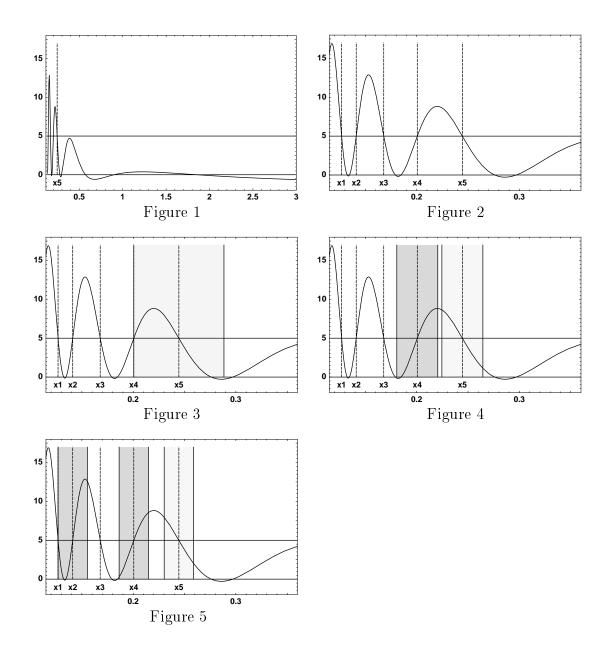
$$\begin{aligned} x_1 &\approx 0.126804, \, x_2 \approx 0.141071, \, x_3 \approx 0.167853, \, x_4 \approx 0.200541, \, x_5 \approx 0.244461, \\ g(x) &> 5 \text{ on } (x_2, x_3) \cup (x_4, x_5) \text{ and } g(x) < 5 \text{ on } (x_1, x_2) \cup (x_3, x_4) \cup (x_5, \infty). \end{aligned}$$

Therefore, by Theorem 3.2, if

$$\|e - \overline{e}\|_{\mathbb{L}} \leq \frac{3}{\pi} \left( x_5 - x_4 \right) \approx 0.0419392,$$

the problem

(3.13) 
$$u'' = \frac{1 + \sin(\frac{\pi}{u})}{u} - \arctan(u) + e(t), \quad u(0) = u(2\pi), \quad u'(0) = u'(2\pi)$$



has a solution  $u_1$  such that  $u_1(t^*) \in [x_4, x_5 + d_1]$  for some  $t^* \in [0, 2\pi]$ , where  $d_1 = x_5 - x_4$  (see Figure 3).

Similarly, by Theorems 3.1 and 3.2, if

$$||e - \overline{e}||_{\mathbb{L}} < \frac{3}{2\pi} (x_5 - x_4) \approx 0.0209699,$$

the problem (3.13) has at least 2 different solutions  $u_1$  and  $u_2$ , where  $u_1(t^*) \in (x_5 - d_2, x_5 + d_2)$  for some  $t^* \in [0, 2\pi]$  and  $u_2(t) \in (x_4 - d_2, x_4 + d_2)$  for all  $t \in [0, 2\pi]$ , where  $d_2 = \frac{1}{2}(x_5 - x_4)$  (see Figure 4).

Finally, if

$$||e - \overline{e}||_{\mathbb{L}} \le \frac{3}{\pi} (x_2 - x_1) \approx 0.0136238$$

the problem (3.13) has at least 3 different solutions  $u_1, u_2$  and  $u_3$ , where  $u_1(t^*) \in [x_5 - d_3, x_5 + d_3]$  for some  $t^* \in [0, 2\pi], u_2(t) \in [x_4 - d_3, x_4 + d_3]$  for all  $t \in [0, 2\pi]$  and  $u_3(t) \in [x_1, x_2]$  for all  $t \in [0, 2\pi]$ , where  $d_3 = x_2 - x_1$  (see Figure 5).

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