

On selection of interface weights in domain decomposition methods

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joint work with

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Outline

Substructuring DD methods

Choice of the averaging operator

Numerical results

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Substructuring DD methods

Choice of the averaging operator

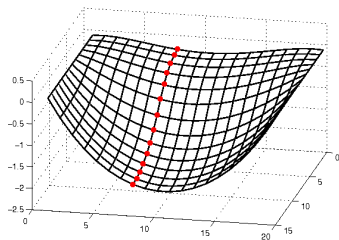
Numerical results

Model problem

Abstract problem:

$$A u = f$$

Example: 2D Poisson problem, 2 subdomains

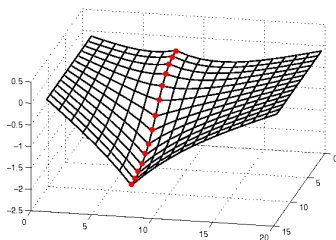


Reduction to the interface

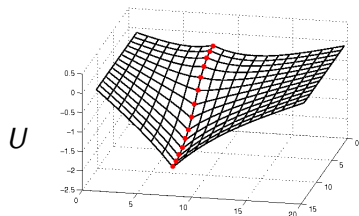
Schur complement with respect to the interface:

$$A u = f \quad \Rightarrow \quad \widehat{S} \widehat{u} = \widehat{g}$$

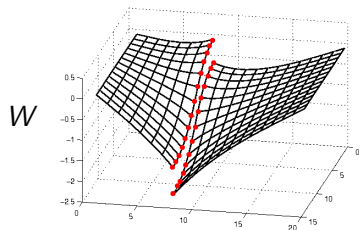
- ▶ $\widehat{S} : U \rightarrow U'$ symmetric positive definite
- ▶ $\dim U < \infty$
- ▶ visualization of function from U on the whole domain:



Primal methods (one level)



$R \downarrow \quad \uparrow E$

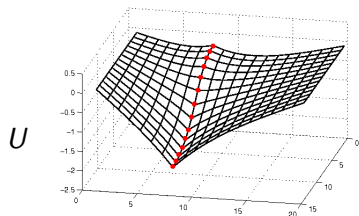


$$\widehat{S} \widehat{u} = \widehat{g}$$

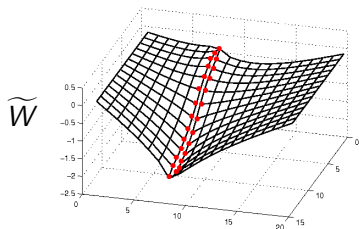
$$S u = g \quad S = \begin{bmatrix} S^1 & 0 \\ 0 & S^2 \end{bmatrix}$$

- ▶ R ... operator of injection
- ▶ E ... averaging
- ▶ $ER = I$, RE ... projection
- ▶ $\widehat{S} = R^T S R$, $\widehat{g} = R^T g$

Primal methods - BDDC



$R \downarrow \quad \uparrow E$



$$\hat{S} \hat{u} = \hat{g}$$

$$\tilde{S} u = \tilde{g} \quad \tilde{S} = \begin{bmatrix} S^1 & 0 & \tilde{S}^{1c} \\ 0 & S^2 & \tilde{S}^{2c} \\ \tilde{S}^{c1} & \tilde{S}^{c2} & \tilde{S}^c \end{bmatrix}$$

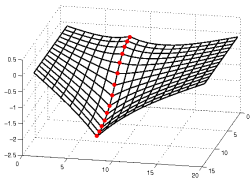
- ▶ R ... operator of injection
- ▶ E ... averaging
- ▶ $ER = I$, RE ... projection
- ▶ $\hat{S} = R^T \tilde{S} R$, $\hat{g} = R^T \tilde{g}$

Abstract primal preconditioner

$$\begin{array}{ccc} & \widehat{S} & \\ & U \longrightarrow U' & \\ E \uparrow & R \downarrow & \uparrow R^T \quad \downarrow E^T \\ & \widetilde{S}^{-1} & \\ & \widetilde{W} \longleftarrow \widetilde{W}' & \end{array}$$

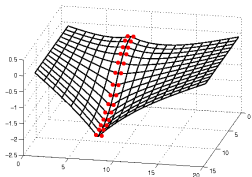
- ▶ R ... operator of injection
- ▶ E ... averaging, $ER = I$, RE ... projection
- ▶ $\widehat{S} = R^T \widetilde{S} R$, $\widehat{S}, \widetilde{S}$... symmetric positive definite
- ▶ $M := E \widetilde{S}^{-1} E^T \approx \widehat{S}^{-1}$
- ▶ $\text{cond}(M \widehat{S}) \leq \|RE\|_{\infty}^2$ [Mandel, Sousedík 2007]

Notation



U

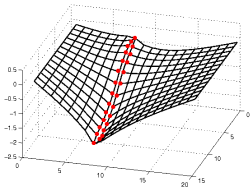
$R \downarrow \quad \uparrow E$



\widehat{W}

\subset

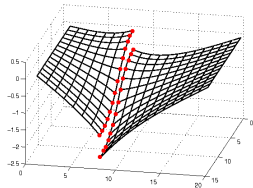
$$Bu = 0$$



\widetilde{W}

\subset

$$Cu = 0$$

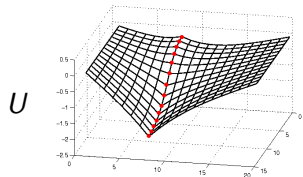


W

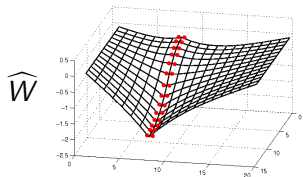
$B : W \rightarrow \Lambda$... a jump across the interface

C ... a jump at the coarse nodes

Formulation of the dual problem



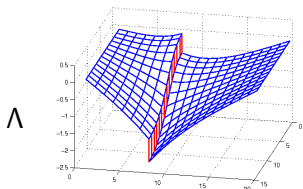
$$\widehat{S}\widehat{u} = \widehat{g} \quad , \quad \widehat{S} : U \rightarrow U'$$



$$Su = g, \quad u \in W, \quad Bu = 0$$

\Rightarrow saddle point problem:

$$\begin{bmatrix} S & B^T \\ B & 0 \end{bmatrix} \begin{bmatrix} u \\ \lambda' \end{bmatrix} = \begin{bmatrix} g \\ 0 \end{bmatrix}$$



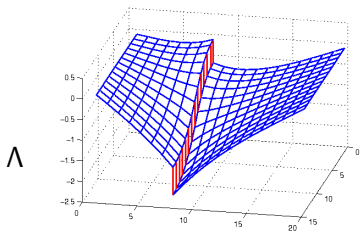
$$BS^{-1}B^T \lambda' = BS^{-1}g$$

$$S : W \rightarrow W'$$

$$B : W \rightarrow \Lambda \dots \text{a jump}$$

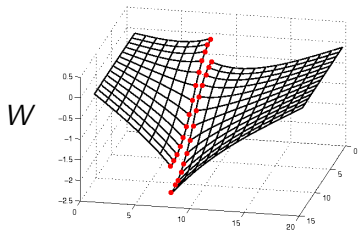
$$B^T : \Lambda' \rightarrow W'$$

Dual method (one level)



$$F \lambda' = v, \quad F : \Lambda' \rightarrow \Lambda$$

$$B_D^T \downarrow \quad \uparrow B$$



- ▶ B ... a jump
- ▶ B_D^T ... representation of a jump
- ▶ $B B_D^T = I$, $B_D^T B$... projection
- ▶ $F = B S^{-1} B^T$, $v = B S^{-1} g$

Abstract dual preconditioner

$$\begin{array}{ccc} & F & \\ & \longleftarrow & \\ \Lambda & & \Lambda' \\ B_D^T \downarrow & B \uparrow & \downarrow B^T \quad \uparrow B_D \\ & \tilde{S} & \\ \tilde{W} & \longrightarrow & \tilde{W}' \end{array}$$

- ▶ B_D^T ... jump representation
- ▶ B ... jump operator, $B B_D^T = I$, $B_D^T B$... projection
- ▶ $F = B \tilde{S}^{-1} B^T$, F, \tilde{S} ... symmetric positive definite
- ▶ $M := B_D \tilde{S} B_D^T \approx F^{-1}$
- ▶ $\text{cond}(MF) \leq \|B_D^T B\|_S^2$ [Mandel, Sousedík 2007]

Relationship between primal and dual methods

Let operators determining primal and dual method satisfy a relationship

$$B_D^T B + RE = I_{\widetilde{W}} .$$

Then both the preconditioned linear systems are spectrally equivalent.

[Mandel, Dohrmann, Tezaur 2005]

We have $\|B_D^T B\|_{\widetilde{\mathfrak{S}}} = \|I - RE\|_{\widetilde{\mathfrak{S}}} = \|RE\|_{\widetilde{\mathfrak{S}}}$

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Substructuring DD methods

Choice of the averaging operator

Numerical results

Standard choices of E

α_i^k = weight of the i -th node in the k -th subdomain

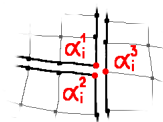
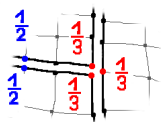
$$\sum_k \alpha_i^k = 1$$



U



\widetilde{W}



Standard choices of α_i^k :

- ▶ arithmetic average
- ▶ weighted average with weights derived from:
 - ▶ diagonal entries of local and global Schur compl.: $\alpha_i^k = s_{ii}^k / \widehat{s}_{ii}$
 - ▶ jumps at coefficients of the equation across the interface
 - ▶ diagonal entries of K , $K^{(i)}$

Our proposition of the choice of \mathbf{E}

Let \mathbf{d} is a probing vector, \mathbf{d}^k its restriction to k -th subdomain.

Weights for the k -th subdomain:

$$\alpha^k = (\mathbf{d}^k)^T \mathbf{S}^k \mathbf{d}^k / \mathbf{d}^T \widehat{\mathbf{S}} \mathbf{d}$$

Different probing vectors \mathbf{d} :

$$\mathbf{d} = \mathbf{e}_i = (0, \dots, 0, 1, 0 \dots 0) \implies \alpha_i^k = s_{ii}^k / \widehat{s}_{ii}$$

$$\mathbf{d} = (1, \dots, 1) \implies \alpha^k = \sum_{ij} s_{ij}^k / \sum_{ij} (\widehat{s}_{ij})$$

\mathbf{d} = a jump at the last approximation

...

(for more subdomains, \mathbf{d} is supposed to be nonzero only for selected face or edge or a part of it)

Derivation of the formula for 2 subdomains

minimization of RE in energetic norm for given vector u with respect to node weights α_i^1 , for 2 subdomains:

$$\| \mathbf{RE} \mathbf{u} \|_{\mathcal{S}}^2 \longrightarrow \min$$

$$\begin{bmatrix} \hat{s}_{11} d_1 d_1 & \hat{s}_{12} d_1 d_2 & \dots & \hat{s}_{1n} d_1 d_n \\ \dots & \dots & \dots & \dots \\ \hat{s}_{i1} d_i d_1 & \hat{s}_{i2} d_i d_2 & \dots & \hat{s}_{in} d_i d_n \\ \dots & \dots & \dots & \dots \\ \hat{s}_{n1} d_n d_1 & \hat{s}_{n2} d_n d_2 & \dots & \hat{s}_{nn} d_n d_n \end{bmatrix} \begin{bmatrix} \alpha_1^1 \\ \dots \\ \dots \\ \alpha_n^1 \end{bmatrix} = \begin{bmatrix} \sum_j s_{1j}^1 d_j d_1 \\ \dots \\ \sum_j s_{ij}^1 d_j d_i \\ \dots \\ \sum_j s_{nj}^1 d_j d_n \end{bmatrix},$$

where $\mathbf{d} = (d_1, d_2, \dots, d_n)^T$ is a jump in u across the interface.

Simplifying choices:

$$\mathbf{d} = (0, \dots, 0, d_i, 0, \dots, 0) \implies \alpha_i^1 = s_{ii}^1 / (s_{ii}^1 + s_{ii}^2) = s_{ii}^1 / \hat{s}_{ii}$$

$$\alpha_1^1 = \dots = \alpha_n^1 = \alpha^1 \implies \alpha^1 = \mathbf{d}^T \mathbf{S}^1 \mathbf{d} / \mathbf{d}^T (\mathbf{S}^1 + \mathbf{S}^2) \mathbf{d}$$

Outline

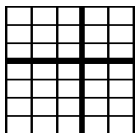
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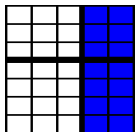
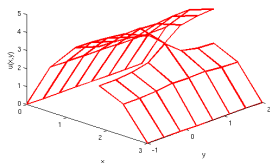
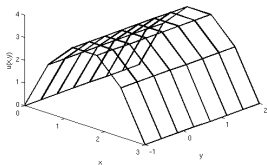
Numerical results

Test problem: 2D Poisson equation (stationary heat problem)

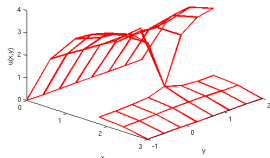
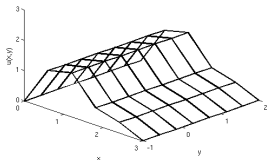
bilinear elements, 4 subdomains, 1 coarse node (at crosspoint)



no jumps

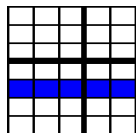


jump 1:9

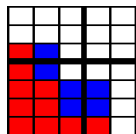
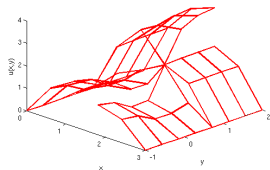
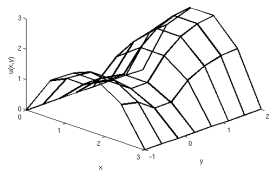


Test problem: 2D Poisson equation (stationary heat problem)

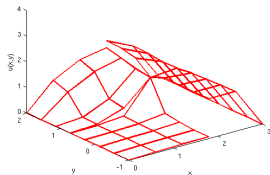
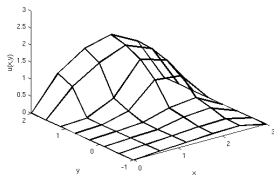
bilinear elements, 4 subdomains, 1 coarse node (at crosspoint)



jumps 1:10



jumps 1:10:100



Errors in the first 5 iterations

Richardson method: $u_{i+1} = u_i + M r_i$

no jumps

jump 1:9

$\alpha = 1/2$	α_j diag. Sch.	$d = (1, \dots, 1)$	$\alpha = 1/2$	α_j diag. Sch.	$d = (1, \dots, 1)$
9.67e-01	9.52e-01	8.62e-01	1.91e+01	1.14	1.08
2.46e-01	2.42e-01	2.18e-01	5.57e+01	3.47e-01	3.28e-01
6.18e-02	6.04e-02	5.44e-02	1.62e+02	1.05e-01	9.88e-02
1.55e-02	1.51e-02	1.36e-02	4.68e+02	3.15e-02	2.97e-02
3.89e-03	3.78e-03	3.41e-03	1.35e+03	9.50e-03	8.96e-03

jumps 1:10

jumps 1:10:100

$\alpha = 1/2$	α_j diag. Sch.	$d = (1, \dots, 1)$	$\alpha = 1/2$	α_j diag. Sch.	$d = (1, \dots, 1)$
1.08	9.35e-01	8.06e-01	1.76e+01	1.44e+01	5.44e-01
3.25e-01	2.46e-01	1.85e-01	6.33e+01	4.14e+01	1.17e-01
9.58e-02	6.37e-02	4.23e-02	2.27e+02	1.19e+02	5.66e-02
2.82e-02	1.65e-02	9.70e-03	8.16e+02	3.44e+02	3.75e-02
8.30e-03	4.29e-03	2.23e-03	2.93e+03	9.91e+02	2.58e-02

Errors in the first 5 iterations

PCG

no jumps

jump 1:9

$\alpha = 1/2$	α_j diag. Sch.	$d = (1, ..1)$	$\alpha = 1/2$	α_j diag. Sch.	$d = (1, ..1)$
8.81e-01	8.70e-01	8.00e-01	6.16	1.07	9.85e-01
7.24e-03	6.87e-03	9.40e-03	9.05e-01	4.20e-03	6.46e-03
8.50e-04	7.22e-04	9.21e-04	1.22e-02	4.21e-04	5.08e-04
1.64e-06	1.17e-06	1.64e-06	7.50e-04	2.51e-07	3.76e-07
1.09e-09	1.05e-09	1.94e-09	1.00e-04	1.55e-10	1.55e-10

jumps 1:10

jumps 1:10:100

$\alpha = 1/2$	α_j diag. Sch.	$d = (1, ..1)$	$\alpha = 1/2$	α_j diag. Sch.	$d = (1, ..1)$
1.00	8.82e-01	8.01e-01	5.95	5.65	6.17e-01
1.35e-02	1.34e-02	8.85e-03	2.57e-01	2.56e-01	5.48e-02
1.05e-03	7.49e-04	7.48e-04	7.82e-03	3.63e-03	1.09e-02
2.23e-06	1.73e-06	4.86e-06	1.29e-04	6.94e-05	1.33e-04
8.35e-10	9.52e-10	3.22e-08	1.24e-06	8.84e-08	3.29e-05

Conclusions

- a new form of the averaging operator E was proposed
- 3 choices of E were compared:
 1. arithmetic average $\alpha = 1/2$
 2. $\alpha_i^k = s_{ii}^k / \widehat{s}_{ii}$ (fractions of Schur diagonal entries)
 3. $\alpha^k = (\mathbf{d}^k)^T \mathbf{S}^k \mathbf{d}^k / \mathbf{d}^T \widehat{\mathbf{S}} \mathbf{d}$
with \mathbf{d} chosen as **ones** for a given edge, **zeros** otherwise
- best choice of E can differ for PCG and Richardson method
 - for Richardson method: choice of **3** is the best
 - for PCG:
 - ▶ choice of **1** is better than **2** or **3** for constant coefficients
 - ▶ **2** is the best choice for jumps in coefficients
 - ▶ **2** can be replaced by **3** for jump in coeff. across the interface
- future work: tests for large numbers of subdomains