

# Ergodic theory for energetically open compressible fluid flows

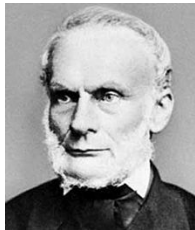
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# Motivation

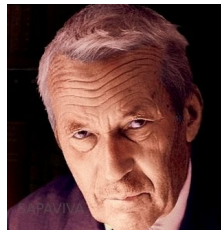


**Rudolf Clausius**  
1822–1888

**Basic principles of thermodynamics of closed systems**  
Die Energie der Welt ist constant. Die Entropie der Welt strebt einem Maximum zu.

## **Turbulence - ergodic hypothesis**

Time averages along trajectories of the flow converge, for large enough times, to an ensemble average given by a certain probability measure



**Andrey  
Nikolaevich  
Kolmogorov**  
1903–1987

# Dynamical systems

## Dynamical system

$$\mathbf{U}(t, \cdot) : [0, \infty) \times X \rightarrow X$$

- **Closed system:**  $\mathbf{U}(t, X_0) \rightarrow \mathbf{U}_\infty$  equilibrium solution as  $t \rightarrow \infty$

- **Open system:**  $\frac{1}{T} \int_0^T F(\mathbf{U}(t, X_0)) dt \rightarrow \int_X F(X) d\mu, T \rightarrow \infty$   
 $\mu$  a.s. in  $X_0$

## Principal mathematical problems:

### ■ Low regularity of global in time solutions

Global in time solutions necessary. For many problems in fluid dynamics – Navier–Stokes or Euler system – only weak solutions available

### ■ Lack of uniqueness

Solutions do not, or at least are not known to, depend uniquely on the initial data. Spaces of trajectories: Sell, Nečas, Temam and others

### ■ Propagation of oscillations

Realistic systems are partly hyperbolic: propagation of oscillations “from the past”, singularities

# Abstract setting



## Space of entire trajectories

$$\mathcal{T} = C_{\text{loc}}(\mathbb{R}; X), \quad t \in (-\infty, \infty)$$

**George Roger  
Sell**  
1937–2015

$\omega$ -limit set

$$\omega[\mathbf{U}(\cdot, X_0)] \subset \mathcal{T}$$

$$\omega[\mathbf{U}(\cdot, X_0)] = \left\{ \mathbf{V} \in \mathcal{T} \mid \mathbf{U}(\cdot + t_n, X_0) \rightarrow \mathbf{V} \text{ in } \mathcal{T} \text{ as } t_n \rightarrow \infty \right\}$$

## Necessary ingredients

- **Dissipativity** – ultimate boundedness of trajectories
- **Compactness** – in appropriate spaces

# Strong and weak ergodic hypothesis

## Krylov – Bogolyubov construction

$T \mapsto \frac{1}{T} \int_0^T \delta_{\mathbf{U}(\cdot+t, X_0)} dt$  – a family of probability measures on  $\mathcal{T}$

tightness in  $\mathcal{T} \Rightarrow T_n \mapsto \frac{1}{T_n} \int_0^{T_n} \delta_{\mathbf{U}(\cdot+t, X_0)} dt \rightarrow \mu \in \mathcal{P}[\mathcal{T}]$

$[\mathcal{T}, \mu]$  stationary statistical solution

**Ergodic hypothesis**  $\Leftrightarrow \mu$  is unique  $\Rightarrow T \mapsto \frac{1}{T} \int_0^T \delta_{\mathbf{U}(\cdot+t, X_0)} dt \rightarrow \mu$

unique  $\approx$  unique on  $\omega[\mathbf{U}(\cdot, X_0)]$

## Weak ergodic hypothesis

$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \delta_{\mathbf{U}(\cdot+t, X_0)} dt = \mu$  exists in the narrow sense in  $\mathcal{P}[\mathcal{T}]$

$[\mathcal{T}, \mu]$  stationary statistical solution

# Barotropic Navier–Stokes system

## Field equations

$$\begin{aligned}\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) &= 0 \\ \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p &= \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u}) + \varrho \mathbf{g}\end{aligned}$$

## Constitutive equations

- barotropic (isentropic) pressure–density EOS  $p = p(\varrho)$  ( $p = a\varrho^\gamma$ )
- Newton's rheological law

$$\mathbb{S} = \mu \left( \nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{d} \operatorname{div}_x \mathbf{u} \mathbb{I} \right) + \eta \operatorname{div}_x \mathbf{u} \mathbb{I}, \quad \mu > 0, \quad \eta \geq 0$$

- Gravitational external force

$$\mathbf{g} = \nabla_x F, \quad F = F(x)$$

## Energy

$$E(\varrho, \mathbf{m}) \equiv \frac{1}{2} \frac{|\mathbf{m}|^2}{\varrho} + P(\varrho) - \varrho F, \quad P'(\varrho)\varrho - P(\varrho) = p(\varrho), \quad \mathbf{m} = \varrho \mathbf{u}$$

# Energetically insulated system

## Conservative boundary conditions

$\Omega \subset R^d$  bounded (sufficiently regular) domain

- impermeability  $\mathbf{u} \cdot \mathbf{n}|_{\partial\Omega} = 0$
- no-slip  $[\mathbf{u}]_{\text{tan}}|_{\partial\Omega} = 0$

### Long-time behavior – Clausius scenario

- Total mass conserved

$$\int_{\Omega} \varrho(t, \cdot) \, dx = M_0$$

- Total energy – Lyapunov function

$$\frac{d}{dt} \int_{\Omega} E(\varrho, \mathbf{m}) \, dx + \int_{\Omega} \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} \, dx = (\leq) 0, \quad \int_{\Omega} E(\varrho, \mathbf{m}) \, dx \searrow \mathcal{E}_{\infty}$$

- Stationary solution

$$\mathbf{m}_{\infty} = 0, \quad \nabla_x p(\varrho_{\infty}) = \varrho_{\infty} \nabla_x F, \quad \int_{\Omega} \varrho_{\infty} \, dx = M_0, \quad \int_{\Omega} E(\varrho_{\infty}, 0) \, dx = \mathcal{E}_{\infty}$$

## Energetically open system

### In/out flow boundary conditions

$$\mathbf{u} = \mathbf{u}_b \text{ on } \partial\Omega$$

$$\Gamma_{\text{in}} = \left\{ x \in \partial\Omega \mid \mathbf{u}_b(x) \cdot \mathbf{n}(x) < 0 \right\}, \quad \Gamma_{\text{out}} = \left\{ x \in \partial\Omega \mid \mathbf{u}_b(x) \cdot \mathbf{n}(x) \geq 0 \right\}$$

### Density (pressure) on the inflow boundary

$$\varrho = \varrho_b \text{ on } \Gamma_{\text{in}}$$

### Energy balance

$$\begin{aligned} & \frac{d}{dt} \int_{\Omega} \frac{1}{2} \varrho |\mathbf{u} - \mathbf{u}_b|^2 + P(\varrho) \, dx + \int_{\Omega} \mathbb{S} : \nabla_x \mathbf{u} \, dx dt \\ & + \int_{\Gamma_{\text{in}}} P(\varrho_b) \mathbf{u}_b \cdot \mathbf{n} \, dS_x + \int_{\Gamma_{\text{out}}} P(\varrho) \mathbf{u}_b \cdot \mathbf{n} \, dS_x \\ & = (\leq) - \int_{\Omega} [\varrho \mathbf{u} \otimes \mathbf{u} + p(\varrho) \mathbb{I}] : \nabla_x \mathbf{u}_b \, dx + \frac{1}{2} \int_{\Omega} \varrho \mathbf{u} \cdot \nabla_x |\mathbf{u}_b|^2 \, dx dt \end{aligned}$$



# Global bounded trajectories

## Global in time weak solutions

$\mathbf{U} = [\varrho, \mathbf{m} = \varrho \mathbf{u}]$  – weak solution of the Navier–Stokes system satisfying energy inequality and defined for  $t > T_0$

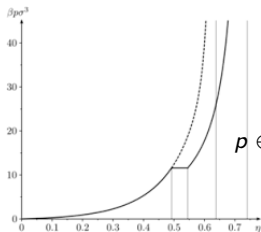
## Bounded energy

$$\limsup_{t \rightarrow \infty} \int_{\Omega} E(\varrho, \mathbf{m}) \, dx \leq \mathcal{E}_{\infty}$$

## Available results

- **Existence:** T. Chang, B. J. Jin, and A. Novotný, *SIAM J. Math. Anal.*, **51**(2):1238–1278, 2019  
H. J. Choe, A. Novotný, and M. Yang *J. Differential Equations*, **266**(6):3066–3099, 2019
- **Globally bounded solutions:** F. Fanelli, E. F., and M. Hofmanová **arxiv preprint No. 2006.02278**, 2020  
J. Březina, E. F., and A. Novotný, *Communications in PDE's* 2020

# Hard sphere pressure EOS



$$p \in C[0, \bar{\varrho}] \cap C^1(0, \bar{\varrho}), \quad p'(\varrho) > 0 \text{ for } \varrho > 0, \quad \lim_{\varrho \rightarrow \bar{\varrho}^-} p(\varrho) = \infty$$

**Ultimate boundedness of trajectories – bounded absorbing set**

$$\limsup_{t \rightarrow \infty} \int_{\Omega} E(\varrho, \mathbf{m}) \, dx \leq \mathcal{E}_{\infty}$$

$\mathcal{E}_{\infty}$  – universal constant

## $\omega$ – limit sets

$$p \approx a\rho^\gamma, \quad \gamma > \frac{d}{2} \text{ or hard sphere EOS}$$

### Trajectory space

$$X = \left\{ \rho, \mathbf{m} \mid \rho(t, \cdot) \in L^\gamma(\Omega), \mathbf{m}(t, \cdot) \in L^{\frac{2\gamma}{\gamma+1}}(\Omega; R^d) \hookrightarrow W^{-k,2} \right\}$$

$$\mathcal{T} = C_{\text{loc}}(R; L^1 \times W^{-k,2})$$

### Fundamental result on compactness [Fanelli, EF, Hofmanová, 2020]

The  $\omega$ -limit set  $\omega[\rho, \mathbf{m}]$  of each global in time trajectory with globally bounded energy is:

- *non – empty*
- *compact* in  $\mathcal{T}$
- time shift invariant
- consists of entire (defined for all  $t \in R$ ) weak solutions of the Navier–Stokes system

# Propagation of oscillations

## Equation of continuity

$$\partial_t \varrho + \mathbf{u} \cdot \nabla_x \varrho = -\varrho \operatorname{div}_x \mathbf{u}$$

## Renormalized equation of continuity

$$\partial_t b(\varrho) + \operatorname{div}_x (b(\varrho) \mathbf{u}) + \left( b'(\varrho) \varrho - b(\varrho) \right) \operatorname{div}_x \mathbf{u} = 0$$

## Weak convergence

$$\begin{aligned} b(\varrho_n) &\rightarrow \overline{b(\varrho)} \text{ weakly in } L^1 \\ \partial_t \left[ \overline{b(\varrho)} - b(\varrho) \right] + \operatorname{div}_x \left( \overline{b(\varrho) \mathbf{u}} - b(\varrho) \mathbf{u} \right) \\ &= \left( b'(\varrho) \varrho - b(\varrho) \right) \operatorname{div}_x \mathbf{u} - \overline{\left( b'(\varrho) \varrho - b(\varrho) \right) \operatorname{div}_x \mathbf{u}} \\ &\quad \left[ \overline{b(\varrho)} - b(\varrho) \right] (0, \cdot) = 0 \text{ is needed!} \end{aligned}$$

# Vanishing oscillation defect, I

Compactness of densities:

$$\varrho_n \equiv \varrho(\cdot + T_n) \rightarrow \varrho \text{ in } C_{\text{weak,loc}}(R; L^\gamma(\Omega))$$

$$\varrho_n \log(\varrho_n) \rightarrow \overline{\varrho \log(\varrho)} \geq \varrho \log(\varrho)$$

$$\text{oscillation defect: } D(t) \equiv \int_{\Omega} \overline{\varrho \log(\varrho)} - \varrho \log(\varrho) \, dx \geq 0$$

Renormalized equation:

$$\frac{d}{dt} D + \int_{\Omega} \left[ \overline{\varrho \operatorname{div}_x \mathbf{u}} - \varrho \operatorname{div}_x \mathbf{u} \right] dx = 0, \quad 0 \leq D \leq \bar{D}, \quad t \in R$$

Lions' identity

$$\overline{\varrho \operatorname{div}_x \mathbf{u}} - \varrho \operatorname{div}_x \mathbf{u} = \overline{p(\varrho)\varrho} - p(\varrho) \varrho \geq 0$$

## Vanishing oscillation defect, II

### Crucial differential inequality

$$\frac{d}{dt}D + \Psi(D) \leq 0, \quad 0 \leq D \leq \bar{D}, \quad t \in R$$

$$\Psi \in C(R), \quad \Psi(0) = 0, \quad \Psi(Z)Z > 0 \text{ for } Z \neq 0$$

$\Rightarrow$

$$D \equiv 0$$

## Statistical stationary solutions

### Application of Krylov – Bogolyubov method

$$\frac{1}{T_n} \int_0^{T_n} \delta_{\varrho(\cdot+t, \cdot), \mathbf{m}(\cdot+t, \cdot)} dt \rightarrow \mu \in \mathcal{P}[\mathcal{T}] \text{ narrowly}$$

$[\mathcal{T}, \mu]$  (canonical representation) – statistical stationary solution

$\mu(t)|_X$  (marginal) independent of  $t \in \mathbb{R}$

### Application of Birkhoff – Khinchin ergodic theorem

$$\frac{1}{T} \int_0^T F(\varrho(t, \cdot), \mathbf{m}(t, \cdot)) dt \rightarrow \bar{F} \text{ as } T \rightarrow \infty$$

$F$  bounded Borel measurable on  $X$  for  $\mu$  – a.a.  $(\varrho, \mathbf{m}) \in \omega$

**Related results for incompressible Navier–Stokes system with conservative boundary conditions**

F.Flandoli and D. Gatarek, F.Flandoli and M.Romito (stochastic forcing),

# Back to ergodic hypothesis – conclusion

## Ergodicity

$\mu$  ergodic  $\Leftrightarrow \mathcal{B} \subset \omega[\varrho, \mathbf{m}]$  shift invariant  $\Rightarrow \mu[\mathcal{B}] = 1$  or  $\mu[\mathcal{B}] = 0$

$$\mu \in \text{conv} \left\{ \text{ergodic measures on } \omega[\varrho, \mathbf{m}] \right\}$$

### State of the art for compressible Navier–Stokes system

- Each bounded energy global trajectory generates a stationary statistical solution – a shift invariant measure  $\mu$  – sitting on its  $\omega$ –limit set  $\omega[\varrho, \mathbf{m}]$
- The weak ergodic hypothesis (the existence of limits of ergodic averages for any Borel measurable  $F$ ) holds on  $\omega[\varrho, \mathbf{m}]$   $\mu$ –a.s.
- The (strong) ergodic hypothesis definitely holds for energetically isolated systems and a class of potential forces  $F$ , where all solutions tend to equilibrium



# Complete Navier–Stokes–Fourier system



Claude Louis  
Marie Henri  
Navier  
[1785-1836]

## Equation of continuity

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho, \vartheta) = \operatorname{div}_x \mathbb{S} + \varrho \mathbf{f}$$



George Gabriel  
Stokes

## Entropy production

$$\partial_t(\varrho s(\varrho, \vartheta)) + \operatorname{div}_x(\varrho s(\varrho, \vartheta) \mathbf{u}) + \operatorname{div}_x \left( \frac{\mathbf{q}}{\vartheta} \right) = \sigma$$

$$\sigma = (\geq) \frac{1}{\vartheta} \left( \mathbb{S} : \nabla_x \mathbf{u} - \frac{\mathbf{q} \cdot \nabla_x \vartheta}{\vartheta} \right)$$

# Constitutive relations



Joseph Fourier [1768-1830]

## Fourier's law

$$\mathbf{q} = -\kappa(\vartheta)\nabla_x\vartheta$$



Isaac Newton  
[1643-1727]

## Newton's rheological law

$$\mathbb{S} = \mu(\vartheta) \left( \nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{3} \operatorname{div}_x \mathbf{u} \right) + \eta(\vartheta) \operatorname{div}_x \mathbf{u} \mathbb{I}$$

# Boundary conditions

**Impermeability**

$$\mathbf{u} \cdot \mathbf{n}|_{\partial\Omega} = 0$$

**No-slip**

$$\mathbf{u}_{\text{tan}}|_{\partial\Omega} = 0$$

**No-stick**

$$[\mathbb{S}\mathbf{n}] \times \mathbf{n}|_{\partial\Omega} = 0$$

**Thermal insulation**

$$\mathbf{q} \cdot \mathbf{n}|_{\partial\Omega} = 0$$

# Long-time behavior

## Dichotomy for the closed/open system

$$\mathbf{f} = \mathbf{f}(x)$$

**Either**

$\mathbf{f} = \nabla_x F \Rightarrow$  all solutions tend to a single equilibrium

**or**

$$\mathbf{f} \neq \nabla_x F \Rightarrow \int_{\Omega} E(t, \cdot) dx \rightarrow \infty \text{ as } t \rightarrow \infty$$