

# Mathematical methods in fluid mechanics

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# Example of a PDE system in fluid mechanics

## Euler system of compressible barotropic fluid

$$\begin{aligned}\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) &= 0 \\ \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho) &= 0 \text{ in } (0, T) \times \Omega\end{aligned}$$

## Impermeability boundary conditions

$$\mathbf{u} \cdot \mathbf{n}|_{\partial\Omega} = 0$$

## Initial state

$$\varrho(0, \cdot) = \varrho_0, \quad \mathbf{u}(0, \cdot) = \mathbf{u}_0$$

# Mathematical problems - facts

## Absence of global-in-time smooth solutions...

Smooth solutions typically develop shocks in a finite time; this is true for a “generic” class of data.

## Weak solutions

$$\int [\varrho \partial_t \varphi + \varrho \mathbf{u} \cdot \nabla_x \varphi] = 0$$

$$\int [\varrho \mathbf{u} \cdot \partial_t \varphi + \varrho \mathbf{u} \otimes \mathbf{u} : \nabla_x \varphi + p(\varrho) \operatorname{div}_x \varphi] = 0 \text{ for smooth } \varphi, \varphi$$

## Admissibility - energy inequality

$$\partial_t \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) \right) + \operatorname{div}_x \left[ \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) + p(\varrho) \right) \mathbf{u} \right] \leq 0$$

$$P(\varrho) = \varrho \int_1^\infty \frac{p(z)}{z^2} dz$$

# Some (more shocking) facts about shocks

## Recent mathematical (exact) results

- The problem admits global in time (weak) solutions for any (smooth) initial data (good news!)
- There are infinitely many weak solutions for any (smooth) initial data (bad news!)
- There are infinitely many physically admissible weak solutions (satisfying the energy inequality) for a large class of (not necessarily smooth) data (even worse!)
- There are smooth (Lipshitz) initial data for which the problem admits infinitely many admissible weak solutions (devastating news!)

# What is a good weak solution?

## Desired properties

- A weak solution exists globally in time for “any” choice of the initial state
- A weak solution can be identified as a limit of suitable approximate problems, e.g. by adding artificial viscosity
- The set of weak solutions is closed; a limit of a family of weak solutions is another weak solution
- A weak solution can be identified as a limit of a numerical scheme
- A weak solution is the most general object that enjoys the weak–strong uniqueness property

## Weak strong uniqueness

A weak solution coincides with a strong (classical) solution as long as the latter exists

# Even more general solutions?

## Measure-valued solutions

$$\int [\langle \nu_{t,x}; \varrho \rangle \partial_t \varphi + \langle \nu_{t,x}; \varrho \mathbf{u} \rangle \cdot \nabla_x \varphi] = \mathcal{R}_1$$
$$\int [\langle \nu_{t,x}; \varrho \mathbf{u} \rangle \cdot \partial_t \varphi + \langle \nu_{t,x}; \varrho \mathbf{u} \otimes \mathbf{u} \rangle : \nabla_x \varphi + \langle \nu_{t,x}; p(\varrho) \rangle \operatorname{div}_x \varphi] = \mathcal{R}_2$$
$$\int \left\langle \nu_{\tau,x}; \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) \right\rangle + \mathcal{D} = \int \left\langle \nu_{0,x}; \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) \right\rangle$$

## Compatibility

$$\mathcal{R}_1 + \mathcal{R}_2 \leq \mathcal{D}$$

# Why to go measure-valued

## Main advantages

- They capture singularities - oscillations in hyperbolic systems.
- The notion is easy to extend to viscous fluids described via the Navier–Stokes equations.
- They are the solutions generated by (some) numerical schemes
- **Weak – strong uniqueness** A measure valued solution coincides with the strong solution emanating from the same initial data as long as the latter exists

# Compressible Navier-Stokes system

## Field equations

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho) = \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u})$$

## Isentropic EOS, Newton's rheological law

$$p(\varrho) = a\varrho^\gamma$$

$$\mathbb{S}(\nabla_x \mathbf{u}) = \mu \left( \nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{3} \operatorname{div}_x \mathbf{u} \mathbb{I} \right) + \eta \operatorname{div}_x \mathbf{u} \mathbb{I}, \quad \mu > 0, \quad \eta \geq 0$$

## No-slip boundary conditions

$$\mathbf{u}|_{\partial\Omega} = 0$$



# Numerical method [T. Karper]

## FV framework

regular tetrahedral mesh,  $Q_h = \{v \mid v = \text{piece-wise constant}\}$

## FE framework - Crouzeix - Raviart

$V_h = \left\{ v \mid v = \text{piece-wise affine, } \tilde{v}_\Gamma \text{ continuous on face } \Gamma \right\}$

$$\tilde{v}_\Gamma \equiv \frac{1}{|\Gamma|} \int_\Gamma v \, dS_x$$

## Upwind discretization of convective terms

$$\langle \mathbf{h}\mathbf{u}; \nabla_x \varphi \rangle_E \approx \sum_\Gamma \int_\Gamma \text{Up}[h, \mathbf{u}][[\varphi]] \, dS_x$$

# Dissipative upwind operator

## Upwind operator

$$\begin{aligned} \text{Up}[r_h, \mathbf{u}_h] &= \underbrace{\{r_h\} \langle \mathbf{u}_h \cdot \mathbf{n} \rangle_\Gamma}_{\text{convective part}} - \frac{1}{2} \underbrace{\max\{h^\alpha; |\langle \mathbf{u}_h \cdot \mathbf{n} \rangle_\Gamma|\}}_{\text{dissipative part}} [[r_h]] \\ &= \underbrace{r_h^{\text{out}} [\langle \mathbf{u}_h \cdot \mathbf{n} \rangle_\Gamma]^- + r_h^{\text{in}} [\langle \mathbf{u}_h \cdot \mathbf{n} \rangle_\Gamma]^+}_{\text{standard upwind}} - \frac{h^\alpha}{2} [[r_h]] \chi \left( \frac{\langle \mathbf{u}_h \cdot \mathbf{n} \rangle_\Gamma}{h^\alpha} \right) \end{aligned}$$

## Auxilliary function

$$\chi(z) = \begin{cases} 0 & \text{for } z < -1, \\ z + 1 & \text{if } -1 \leq z \leq 0 \\ 1 - z & \text{if } 0 < z \leq 1 \\ 0 & \text{for } z > 1 \end{cases}$$

# Numerical scheme

## Discrete time derivative - implicit scheme

$$D_t v_h^k = \frac{v_h^k - v_h^{k-1}}{\Delta t}$$

## Continuity method

$$\int_{\Omega_h} D_t \varrho_h^k \phi dx - \sum_{\Gamma \in \Gamma_{\text{int}}} \int_{\Gamma} \text{Up}[\varrho_h^k, \mathbf{u}_h^k] [[\phi]] dS_x = 0$$

## Momentum method

$$\begin{aligned} \int_{\Omega_h} D_t (\varrho_h^k \langle \mathbf{u}_h^k \rangle) \cdot \phi dx - \sum_{\Gamma \in \Gamma_{\text{int}}} \int_{\Gamma} \text{Up}[\varrho_h^k \langle \mathbf{u}_h^k \rangle, \mathbf{u}_h^k] \cdot [[\langle \phi \rangle]] dS_x \\ - \int_{\Omega_h} p(\varrho_h^k) \text{div}_h \phi dx \\ + \mu \int_{\Omega_h} \nabla_h \mathbf{u}_h^k : \nabla_h \phi dx + \left( \frac{\mu}{3} + \eta \right) \int_{\Omega_h} \text{div}_h \mathbf{u}_h^k \text{div}_h \phi dx = 0 \end{aligned}$$

# Convergence results for Karper's scheme

## Convergence to weak solutions

**Karper [2013]:** Convergence to a weak solution if  $\gamma > 3$

## Error estimates

**Gallouet, Herbin, Maltese, Novotný [2015]**

Convergence to smooth solutions + error estimates if  $\gamma > 3/2$ ,  $\Omega$  a polyhedral domain

# Convergence for general adiabatic coefficient

EF, M. Lukáčová/Medvidová [2016]

Let  $\Omega \subset \mathbb{R}^3$  be a smooth bounded domain. Let

$$1 < \gamma < 2, \Delta t \approx h, 0 < \alpha < 2(\gamma - 1).$$

Suppose that the initial data are smooth and that the compressible Navier-Stokes system admits a smooth solution in  $[0, T]$  in the class

$$\varrho, \nabla_x \varrho, \mathbf{u}, \nabla_x \mathbf{u} \in C([0, T] \times \bar{\Omega})$$

$$\partial_t \mathbf{u} \in L^2(0, T; C(\bar{\Omega}; \mathbb{R}^3)), \varrho > 0, \mathbf{u}|_{\partial\Omega} = 0.$$

Then

$$\varrho_h \rightarrow \varrho \text{ (strongly) in } L^\gamma((0, T) \times K)$$

$$\mathbf{u}_h \rightarrow \mathbf{u} \text{ (strongly) in } L^2((0, T) \times K; \mathbb{R}^3)$$

for any compact  $K \subset \Omega$ .

# General strategy

## Basic properties of numerical scheme

Show stability, consistency, discrete energy inequality

## Measure valued solutions

Show convergence of the scheme to a **measure – valued solution**

## Weak-strong uniqueness

Use the weak-strong uniqueness principle in the class of measure-valued solutions. Strong and measure valued solutions emanating from the same initial data coincide as long as the latter exists

# Corollary

## **Convergence of numerical solutions**

Bounded numerical solutions emanating from smooth data that converge to a measure-valued solution converge, in fact, unconditionally to the unique strong solution

# Singular limit problem

## Scaled Euler system

$$\begin{aligned}\partial_t \varrho + \operatorname{div}_x \mathbf{m} &= 0 \\ \partial_t \mathbf{m} + \operatorname{div}_x \left( \frac{\mathbf{m} \otimes \mathbf{m}}{\varrho} \right) + \frac{1}{\varepsilon^2} \nabla_x p(\varrho) &= 0\end{aligned}$$

## Incompressible (low Mach) limit - EF, Ch.Klingenberg, S.Markfelder[2017]

Convergence to the limit system

$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x (\mathbf{v} \otimes \mathbf{v}) + \nabla_x \Pi = 0$$

for well/ill prepared initial data.



# Complete Euler system

## Field equations

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho, \vartheta) = 0$$

$$\begin{aligned} \partial_t \left[ \frac{1}{2} \varrho |\mathbf{u}|^2 + \varrho e(\varrho, \vartheta) \right] + \operatorname{div}_x \left( \left[ \frac{1}{2} \varrho |\mathbf{u}|^2 + \varrho e(\varrho, \vartheta) \right] \mathbf{u} \right) \\ + \operatorname{div}_x(p(\varrho, \vartheta) \mathbf{u}) = 0 \end{aligned}$$

## Entropy inequality (admissibility)

$$\partial_t(\varrho s(\varrho, \vartheta)) + \operatorname{div}_x(\varrho s(\varrho, \vartheta) \mathbf{u}) \geq 0$$

## Constitutive relations

$$p = \varrho \vartheta, \quad e = c_v \vartheta, \quad s = \log(\vartheta^{c_v}) - \log(\varrho)$$